

GPU Computing with CUDA

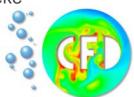
Part 1: GPU Computing Evolution

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 - ARCS 2008 GPGPU and CUDA Tutorials http://www.mathematik.tu-dortmund.de/~goeddeke/arcs2008/
 - University of New South Wales Workshop on GPU Computing with CUDA

http://www.cse.unsw.edu.au/~pls/cuda-workshop09/





- Why GPUs need to be fast
- The graphics pipeline
- Evolution towards programmability
- The first wave of GPGPU: 2003-2006
- Example architecture: GeForce 6800 Ultra (2004)
- Consolidation with DirectX 10?

Why GPUs need to be fast



- Huge FLOP requirements
 - Full HD 1080p screen resolution: 2 million pixels
 - 50-100 Hz refresh rate
 - 10-100 operations per vertex
 - 100-1000 operations per fragment (proto-pixel)
- Huge bandwidth requirements
 - Texturing from multiple texture maps
 - Bilinear and anisotropic filtering
 - Full-screen antialiasing
- Performance demands insatiable

Why GPUs are fast



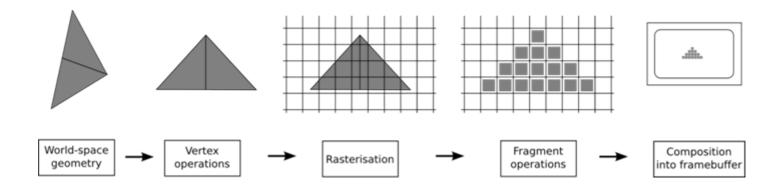


Graphics workloads



- Inherently massively parallel
 - Task- and data-parallelism
 - Vertices in parallel
 - Pixels (fragments) in parallel
 - All simultaneously
- 6 orders of magnitude gap
 - Human visual system: millisecond scale
 - GHz processor: nanosecond scale
- Latency of individual operations not (so) important
 - Throughput is maximised
- GPU hardware is designed around these observations





- Common abstraction of graphics workloads and hardware since 1992
- Exploits parallelism on all scales
- Maximizes throughput over latency



- Expose pipeline, not hardware
 - Configure pipeline stages
- OpenGL
 - Extension model for rapid adoption of new features
 - Vendor- and platform independent
- DirectX
 - Windows only
 - Rigorous mandatory feature set for 3-year+ product cycles
 - DirectX version used to identify GPU generations



- 1999: NVIDIA GeForce 256
 - Term GPU was coined during the launch
 - First to implement the entire pipeline in hardware
 - Limited "programmability" (hardware T&L)
 - Register combiners for fragment stage
- GPGPU:
 - Very preliminary work by very few enthusiasts
 - "Hacking the GPU"



- Late 2000: DirectX 8
 - GeForce 3 and Radeon 8500
 - Assembly language for vertex and fragment stage
 - Programmable shading
 - Very limited functionality
 - Instruction count
 - Precision
 - ...
- GPGPU:
 - Slow momentum build-up
 - First PDE solvers mostly for physically-based effects, visually-accurate
 - Cumbersome programming through graphics APIs
 - Hacky, cumbersome and error-prone

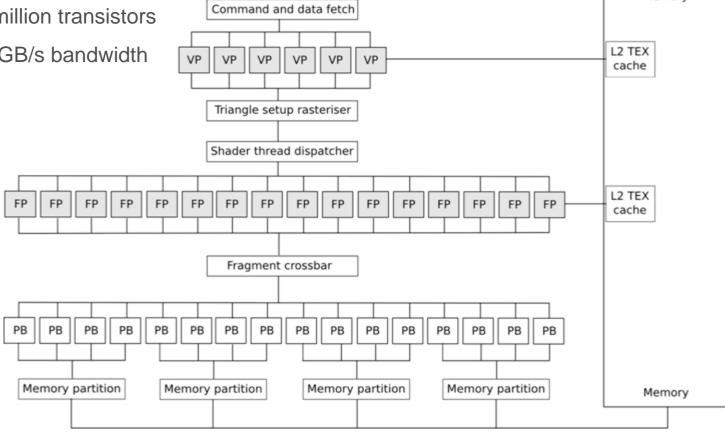


- DirectX 9: The first wave of GPU computing 2003-2006
 - Floating point support, proper render-to-texture
 - Performance improvements faster than Moore's Law
- GPGPU:
 - Growing community (http://gpgpu.org)
 - Cumbersome programming through graphics APIs
 - But: Early high level languages like BrookGPU and Sh
 - Growing # of conference tutorials and workshops
 - Many groundbreaking papers and algorithms published



Memory

- April 2004
- 222 million transistors
- 35.6 GB/s bandwidth





Main limitations

- Programming cumbersome and error-prone (graphics APIs)
- No scatter support (concurrent read exclusive write model)
- Loadbalancing between stages difficult (often only fragment stage used at all)

• But:

- Lots of success by early adoptors
- First commercial ventures
 - RapidMind
 - Acceleware
 - PeakStream (bought by google in 2007)
- People reluctantly started to take GPGPU seriously
- Hardware vendors saw market opportunity

DirectX 10



- Released 2006/2007
 - Unified architecture
 - Vertex, fragment and (new) geometry stage same virtual machine
 - Hardware loadbalancing
 - Many many hacky features now mandatory via clean interfaces
 - Big leap forward in mandatory graphics features
- Consolidation?
 - Plausible
- But something entirely different happened
 - Unified graphics and compute
 - NVIDIA CUDA and AMD Stream (CAL/HAL/CTM...)
 - GPU computing started to take off