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MIXED-PRECISION GPU-MULTIGRID Solvers with Strong Smoothers

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Motivation

- Sparse iterative linear solvers are **the** most important building block in (implicit) schemes for PDE problems
- In FD, FV and FE discretisations
- Lots of research on GPUs so far for Krylov subspace methods, ADI approaches and multigrid
- But: Limited to simple preconditioners and smoothing operators

Preconditioner Construction

Use 'easily invertible' subsets of the system matrix as preconditioner, from left to right: Matrix bands used for Gauß-Seidel (GS), tridiagonal (TRIDI) and combined (TRIGS) preconditioner.

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Alternating Direction Implicit Method

Preconditioner construction depends on the numbering of the unknowns. To resolve anisotropies in different directions, multiple numbering variants are applied in succession and we speak of an Alternating Direction Implicit Method.

- Numerically strong smoothers exhibit inherently sequential data dependencies (impossible to parallelise?)
- Strong smoothers required in practice: Anisotropies (mesh, operator), localised nonlinearities from the PDEs etc. increase ill-conditioning of the systems drastically
- Multigrid is asymptotically optimal, all other iterative schemes suffer from *h*-dependencies
- In our context: Multigrid = geometric multigrid



Example: Time (in ms) per unknown per digit, double precision, generalised Poisson problem with anisotropic diffusion, serial CPU test. **Only** MG with a strong smoother performs optimally.

 \Rightarrow Goal: Robust multigrid solvers for illconditioned sparse linear systems

Multicolored Gauß-Seidel

Inexact parallelisation (decouple sequential dependencies into independent sweeps corresponding to a renumbering) yields more independent work than exact wavefront approach: Parallelism in multicolouring (left), lack of parallelism in natural ordering GS (right). Fuse two colours into one kernel to maximise coalescing.



Numerical Results

Generalised Poisson problem with anisotropic diffusion, mixed precision multigrid solvers: Time (in ms) per DOF per gained digit on CPU (top) and GPU (bottom).





Tridiagonal Solves

Parallelisation via cyclic reduction (exact, stable, cost-efficient). Challenge: Classical approach (top) parallelises operations and not memory accesses. Novel data placement (bottom) 2x-4x faster.





Massively parallel MPI solver, unstructured collection of structured subdomains. This poster addresses the local component, see references for how this is included in the large-scale solver. shmem x0 x2 x4 x6 x8 x10 x12 x14 x16 x1 x3 x5 x7 x9 x11 x13 x15 gmem x0 x1 x2 x3 x4 x5 x6 x7 x8 x9 x10 x11 x12 x13 x14 x15 x16

Combination: TRI-GS

Combination of multicoloured GS and novel, fast TRIDI. Sequential: GS-shift of solution from previous row to RHS, tridiagonal solve. Parallel: New multicoloured row scheme balances numerical performance and parallelism.

References

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