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Sim-a-a-S in the loop

Enhancing Rapid Prototyping of Complex Industrial Machines with Automatic Data Synthesis based on Numerical Simulation of Fluid Flow and Machine Learning

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Zentrales Innovationsprogram Mittelstand





Introduction

Experiment vs Simulation of complex industrial machines

02.

Simulation-as-a-Service

The engine that drives data synthesis

03.

AI assistants

Machine Learning-driven assisting of Rapid Prototyping

Introduction

Experiment vs Simulation of complex industrial machines



Introduction

Rapid Prototyping based on simulation

analyse

results

start

tensor





Digital Twin

Frontend and data layer





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Simulation batch

The simulation data tensor





The result data tensor





Simulation-as-a-Service

The engine that drives data synthesis: **Sim-a-a-S := I-a-a-S + S-a-a-S**



Geveler, M.; Turek, S.: Fundamentals of a numerical cloud computing for applied sciences – Preparing cloud computing for Simulation-as-a-Service, European Commission Workshop on Cloud Computing Research Innovation Challenges for WP 2018-2020, -, http://ec.europa.eu/digital-single-market/events/cf/public-consultation-on-cloud-computing-research-innovation-challenges-for-wp-2018-2020/stream-items.cfm?id=3, 2016



Digital Twin

Geometric layer: Automatic geometry processing I







Digital Twin

Geometric layer: Automatic geometry processing II







Sim-a-a-S

Numerical simulation of fluid flow: the behavioural layer of the Digital Twin



Solve NSEs efficiently

$$u_t - \nu \Delta u + u \cdot \nabla u + \nabla p = f,$$

$$-\nabla \cdot u = 0$$

- recursive domain decomposition
 Newton-Krylov-*multigrid schemes*
- local geometric multigrid highly hardware-optimised and accelerated with GPUs or similar
- smoother determines overall efficiency



Sim-a-a-S

Numerical simulation of fluid flow: the behavioural layer of the Digital Twin: FEAT family

$$\begin{aligned} & \underset{\text{Sim-a-a-S loop}}{\text{weak}} \quad \int_{\Omega} \partial_t u \ v \ dx + \int_{\Omega} (u \cdot \nabla u) \ v \ dx - \nu \int_{\Omega} \Delta u \ v \ dx + \int_{\Omega} \nabla p \ v \ dx \ = \int_{\Omega} f \ v \ dx \\ & \int_{\Omega} (\nabla \cdot u) \ q \ dx \ = 0 \end{aligned} \\ & \text{FEM} \quad (\partial_t u_h, v_h) + (u_h \cdot \nabla u_h, v_h) + \nu (\nabla u_h, \nabla v_h) - (p_h, \nabla \cdot v_h) = (f, v_h) \\ & -(q_h, \nabla \cdot u_h) = 0 \end{aligned} \\ & \underset{\text{matrix}}{\text{matrix}} \quad \begin{bmatrix} M & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \partial_t u \\ 0 \end{bmatrix} + \begin{bmatrix} K(u) + \nu L & B \\ -B^T & 0 \end{bmatrix} \begin{bmatrix} u \\ p \end{bmatrix} = \begin{bmatrix} F \\ 0 \end{bmatrix} \\ & S(u) = \alpha M + \theta \Delta t(K(u) + \nu L) \end{aligned} \\ & \text{theta} \quad g = [M - (1 - \theta) \Delta t(K(u) + \nu L)] \cdot u^n + \theta \Delta t F^{n+1} + (1 - \theta) \Delta t F^n. \end{aligned} \\ & \text{scheme} \begin{bmatrix} S(u) & B \\ -B^T & 0 \end{bmatrix} \begin{bmatrix} u^{n+1} \\ p^{n+1} \end{bmatrix} = \begin{bmatrix} g \\ 0 \end{bmatrix} \end{aligned} \\ & \underset{\text{decouple} \\ & + \text{ some magic} \end{aligned} \qquad \begin{bmatrix} S(\tilde{u}) \cdot \tilde{u} = f_{FP} \\ P \cdot q = \frac{1}{\Delta t} B^T \cdot u \end{aligned}$$

- Pressure Poisson
 Problem Consumes
 most of the time
- Recursive Domain
 Decomposition
 Newton-Krylov Multigrid schemes
- Local geometric multigrid highly hardware-optimised and accelerated with GPUs or similar
- smoother determinesoverall efficiency



Data visualisation and -derivatives





0.05

10⁻² 10⁻¹ 10⁰ 10¹ 10² Scherrate [s⁻¹]

max mean

> 400 600 Laufkoordinate z-Achse [mm]

800 1000

Sim-a-a-S

System Architecture



Sim-a-a-S increases simulation throughput and allows for fast data synthesis + standardized data





Connected to Sim-a-a-S



Connected to Sim-a-a-S



Connected to Sim-a-a-S

max temperature gradient, min washing time, pressure estimate in axial direction, "go!", ...







OUTPUT Test loss 0.145 Training loss 0.138

Connected to Sim-a-a-S





Connected to Sim-a-a-S



incremental training at the Sim-a-a-S gateway system
 re-training starting at data saturation point or nightly
 readily trained models generate pull request
 new models go to new Sim-a-a-S system version at update time (2-weekly)









Results



Automatic Simulation ready for

- Extrusion Dies
- Single Screw Extruders
- Hotrunner systems
- Excenterscrewpumps
- Twin Screw Extruders BETA
- Centrifugal pumps BETA
- Blow Mold ALPHA



AI Assistants in ALPHA for

- Extrusion Dies
- Single Screw Extruders
- Blow Mold



First alpha assistants predict simple indicators at high accuracy



Summary

based on variations of a digital twin



high end simulation results

based on neural nets that are trained with data derivatives from the synthetic results

Outlook



....

Thank you





STRÖMUNGS**RAUM**

https://ianus-simulation.de/en/stroemungsraum/

ZIM Zentrales Innovationsprogramm Mittelstand