Finite Element Simulation of Particle-Laden Gas Flows with Application to the Arc Spraying Process

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Aims

- Numerical simulation of the compressible particle-laden gas flow between the nozzle and the substrate
- Macroscopic 2-fluid model
- Development of implicit high-resolution finite element TVD-schemes based on algebraic flux correction



Contents

- Modelling
- FEM discretization of the Euler equations
- FEM discretization of the non-hyperbolic dust equations
- Benchmarking

Modelling

Main assumptions

- Continuum description of both phases
- Conservation of mass, momentum, and energy
- Coupling via the drag force and heat exchange
- Dilute flow (small volume fraction of particles)
- Pressureless particlulate phase, ideal gas
- No particle collisions occur



Control volume



Interphase terms

$$F_D = \alpha_p \gamma_D (u_p - u_g)$$

$$Q_T = \alpha_p \gamma_T (T_p - T_g)$$



Gas phase:

$$\begin{aligned} \partial_t(\alpha_g \rho_g) + \nabla \cdot (\alpha_g \rho_g u_g) &= 0 \\ \partial_t(\alpha_g \rho_g u_g) + \nabla \cdot (\alpha_g \rho_g u_g \otimes u_g + \alpha_g PI) &= P \nabla \alpha_g + F_D \\ \partial_t(\alpha_g \rho_g E_g) + \nabla \cdot (\alpha_g u_g (\rho_g E_g + P)) &= P V_i \nabla \alpha_g + V_i \cdot F_D + Q_T \end{aligned}$$

Particulate phase:

$$\begin{aligned} \partial_t(\alpha_p \rho_p) + \nabla \cdot (\alpha_p \rho_p u_p) &= 0 \\ \partial_t(\alpha_p \rho_p u_p) + \nabla \cdot (\alpha_p \rho_p u_p \otimes u_p) &= P \nabla \alpha_p - F_D \\ \partial_t(\alpha_p \rho_p E_p) + \nabla \cdot (\alpha_p u_p \rho_p E_p) &= P V_i \nabla \alpha_p - V_i \cdot F_D - Q_T \end{aligned}$$

Saturation condition: $\alpha_g + \alpha_p = 1$

• Two-way coupling via the volume fractions and interphase transfer terms.

Operator-Splitting





1. Hyperbolic step

$$\frac{U_{g}^{n+1/2} - U_{g}^{n}}{\Delta t} + \nabla \cdot F_{g}^{n+1/2} = 0$$

$$\frac{U_{p}^{n+1/2} - U_{p}^{n}}{\Delta t} + \nabla \cdot F_{p}^{n+1/2} = 0$$

Hyperbolic equations

2. Source term step



Nodal ODEs

Discretization of Convective Terms

High-order scheme:

$$M_C \frac{dU}{dt} = KU$$

Low-order scheme:

$$M_L \frac{dU}{dt} = KU + DU = LU$$

High-resolution scheme:

$$M_L \frac{dU}{dt} = KU + DU + F^*U = K^*U$$

Equivalent representation:

$$M_L \frac{dU}{dt} = L^* U$$



Euler Equations: High-Order Scheme



Galerkin FEM:

$$\sum_{j} m_{ij} \frac{dU_{j}}{dt} = -\sum_{j} c_{ij} \cdot F_{j}, \quad \forall i$$

$$m_{ij} = \int_{\Omega} \varphi_i \varphi_j dx \qquad \qquad o$$

$$c_{ij} = \int_{\Omega} \varphi_i \nabla \varphi_j dx$$

Lumped mass Galerkin scheme:





Characteristic LED criterion:

A semi-discrete scheme of the form

$$m_i \frac{dU_i}{dt} = \sum_{j \neq i} L_{ij} \left(U_j - U_i \right)$$

is LED, if all off-diagonal blocks L_{ij} are positive semi-definite.



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Low-order operator:

Design of the Artificial Diffusion Operator

Requirements:

- Block symmetry, zero row and column sums
- Enough dissipation to enforce the LED criterion

Local diffusion operator:

$$D_{loc} = \begin{pmatrix} -D_{ij} & D_{ij} \\ D_{ij} & -D_{ij} \end{pmatrix}, \qquad D_{ij} = R_{ij} |\Lambda_{ij}| R_{ij}^{-1}$$

Diffusive fluxes:

$$f_{ij}^{diff} = D_{ij} \left(U_j - U_i \right), \qquad f_{ji}^{diff} = -f_{ij}^{diff}$$

$$L_{ij} = K_{ij} + D_{ij} = R_{ij}\Lambda_{ij} R_{ij}^{-1} + R_{ij}|\Lambda_{ij}| R_{ij}^{-1}$$







Flux Limiting & Characteristic Variables



Characteristic variables:

Compute characteristic variables for each space dimension separately

- Decoupling of the linearized Euler equations along the edge ij
- Characteristic flux limiter of TVD type (Kuzmin 2007)

High-resolution scheme:

$$(K^*U)_i = \sum_{j \neq i} (K_{ij} + D_{ij} - F_{ij}^*) (U_j - U_i)$$



Weak Boundary Conditions: Euler Equations

Integration by parts:

$$\sum_{j} \int_{\Omega} \varphi_{i} \varphi_{j} dx \frac{dU_{j}}{dt} = \sum_{j} \int_{\Omega} \varphi_{j} \nabla \varphi_{i} dx \cdot F_{j} - \sum_{j} \int_{\partial \Omega} \varphi_{i} \varphi_{j} n ds \cdot F_{j}, \quad \forall i$$

- Improved convergence rates and robustness in steady computations
- Exclusively the boundary integrals are affected by the boundary conditions
- Fully implicit boundary treatment

Transonic Ni-Bump



 $\sum_{j} \int_{\partial \Omega} \varphi_{i} \varphi_{j} n ds \cdot F_{j}$



Overwrite the boundary flux by the imposed boundary condition





Dust Equations





Discrete transport operator:

Scalar LED criterion:

Modified Rusanov:

 $k_{ij} = -c_{ij} \cdot \begin{pmatrix} u_j \\ v_j \end{pmatrix}$

 $d_{ii} = d_{ii} = \max\{0, -k_{ii}, -k_{ii}\}$

 $d_{ij} = d_{ji} = \max\{|k_{ij}|, |k_{ji}|\}$

The dust equations lack hyperbolicity

possible nor necessary

Transformation to characteristic variables neither

Scalar dissipation, modified Rusanov's flux

Flux limiting in terms of conservative variables

Insufficient amount of diffusion to capture the whole solution

Sufficient amount of diffusion to compute a physical solution

Boundary Conditions: Dust Equations



r n Dirichlet inlet boundary conditions: $u \cdot n < 0$ Prescribe all conservative variables **Outlet boundary conditions:** $u \cdot n > 0$

Solid wall conditions: $u \cdot n = 0$

 Project the residual of the momentum equations on the tangent



Do nothing



Shock reflection at a compression corner

- Particles are located at the ramp
- Reflection of a shock impinging on the ramp
- Initial velocities at the ramp are zero
- Gas and particles are initially in thermal equilibrium
- Snapshots at time T=0.0007 sec

Particle X-velocity



Effective particle density



Particle temperature





Comparison of the gas properties for pure gas and particle-laden gas

• Snapshots at time T=0.0006 sec



Comparison of the gas density for pure gas and particle-laden gas

• Propagation of the shock wave





Particle-laden nozzle flow

- Curved boundaries
- Wide range of Mach numbers
- Subsonic inlet
- Compressible and incompressible areas
- High stiffness
- Stationary computation



Challenging problem

Effective particle density



ozzle flow





Effective gas density







- High resolution TVD-scheme is implemented and validated for several benchmarks
- All the necessary information is inferred from the discrete Galerkin operators
- No restriction to 2D, a generalization to 3D is straightforward
- Further work will focus on the efficiency of steady-state computations
- The FCT approach will be implemented for non-stationary flows
- Adaptivity will be used to reduce the computational cost (Matthias Möller)

