

Hierarchical Grid Adaptation for Hybrid Meshes

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Motivation 00 Grid adaptivity

Implementation details

Numerical examples

Overview



Ontivation

- Grid adaptation algorithm
 - Red-green refinement
 - Re-coarsening
- Implementation details
- O Numerical examples
 - Scalar transport problems
 - Compressible Euler equations
- Conclusions

Motivation 00

Why use hybrid grids?

Unstructured grids (triangles/quadrilaterals and tetrahedra/hexahedra)

- Itriangulation of complex domains (Delaunay, advancing front)
- I prevent distorted grids (e.g., near singular points)
- ${}^{\textcircled{R}}$ overhead costs due to indirect addressing

Structured grids (Cartesian and/or generalized tensor-product grids)

- d efficient numerics based on line-wise numbering (SBBLAS)
- ${\ensuremath{\,{\scriptscriptstyle \$}}}$ orthogonal grids to resolve boundary layers
- ${}^{\textcircled{R}}$ unflexible/impractical for complex domains

Hierarchical hybrid grids

Use **globally unstructured** coarse grid and employ **locally structured** and/or **locally unstructured** meshes for triangulation in each patch.

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Design goals for adaptivity

- Adaptation strategy should lead to conforming triangulations
- Mesh quality should not deteriorate due to grid refinement
- Grid coarsening should 'undo' previous refinement steps
- Coarse/initial grid should be preserved for all times
- Dynamic grid adaptation must be efficient for transient flows

Literature

Bank83 R. E. Bank, A. H. Sherman and A. Weiser, *Refinement algorithms and data structures for regular local mesh refinements*, in: Scientific Computing, eds. R. Stepleman et al. (IMACS, North-Holland, Amsterdam, 1983) pp. 3-17

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Motivation

Grid adaptivity 0000 Implementation details 000

Numerical examples

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Principle: Regular refinement in 2D [Bank83]

- Subdivide each marked cell into four similar cells (red refinement)
- Eliminate 'hanging nodes' by introducing transition elements that are removed prior to performing further refinement (green refinement)

Motivation 00 Implementation details

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- a set of elements $\mathcal{E}_0 = \{\Omega_k : k = 1, \dots N_{\rm E}\}$ and
- a set of vertices $\mathcal{V}_0 = \{v_i : i = 1, \dots, N_V\}$

The red-green refinement algorithm is used to transform a conforming triangulation T_{m-1} into a conforming triangulation T_m , m = 1, 2, ...

$$\begin{array}{l} \text{Generation function: } g: \mathcal{V}_m \to \mathbb{N}_0 \text{ (triangles in 20 (Hem09))} \\ \\ g(v_i) := \left\{ \begin{array}{ccc} 0 & \text{if} & v_i \in \mathcal{V}_0 & \text{initial triangulation} \\ \\ \max_{v_j \in \Omega_k \cap \Omega_l} g(v_j) + 1 & \text{if} & v_i \in \Omega_k \cap \Omega_l & \text{face/edge vertex} \\ \\ \\ \max_{v_j \in \Omega_k} g(v_j) + 1 & \text{if} & v_i \in \Omega_k \setminus \partial \Omega_k & \text{interior vertex} \end{array} \right.$$

Generation function can be used to prescribe maximum refinement level!

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Motivation 00 Grid adaptivity ○●○○ Implementation details 000 Numerical examples

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Motivation 00 Grid adaptivity

Implementation details 000 Numerical examples

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Motivation 00 Grid adaptivity ○●○○ Implementation details 000 Numerical examples

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Motivation 00 Grid adaptivity ○●○○ Implementation details 000 Numerical examples

Conclusions and Outlook

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Goal: Each refinement operation is reversed in a single step ⇒ re-coarsening must start from the red elements

Locking: $d: \mathcal{V}_m \to \mathbb{Z}; \quad d(v_i) := g(v_i) \ \forall v_i \in \mathcal{V}_m$ [Hem99]

• Vertex v_i is locked, i.e. $d(v_i) := -|d(v_i)|$ if it belongs to

• an element that is marked for further refinement

- an edge ij and there is a vertex v_j such that $m{g}(v_j) > m{g}(v_i)$
- a red element which should not be coarsened due to accuracy

O Vertices are locked if blue elements would be created otherwise

If two nodes of an inner red triangle are locked, then lock third vertex.
If the 'interior' node of a patch of four quadrilaterals is locked or if more than six nodes are locked, then lock all nodes of that patch

Result: Vertices $v_i \in \mathcal{V}_m$ with $d(v_i) \leq 0$ are locked; all other nodes are 'free' and can be deleted.

 $d(v_i) = 0 \\ \forall v_i \in \mathcal{V}_0$

Motivation

Grid adaptivity

Implementation details 000

Numerical examples

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Motivation

Grid adaptivity

Implementation details 000 Numerical examples

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Motivation

Grid adaptivity

Implementation details 000 Numerical examples

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Motivation

Grid adaptivity

Implementation details 000

Numerical examples

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Motivation

Grid adaptivity

Implementation details 000

Numerical examples

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Motivation

Grid adaptivity

Implementation details 000

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Motivation

Grid adaptivity

Implementation details 000

Numerical examples

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Motivation 00 Grid adaptivity

Implementation details 000

Numerical examples

Motivation

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Refinement algorithm: initial grid



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Refinement algorithm: mark elements for regular refinement



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Refinement algorithm: perform regular refinement



Refinement algorithm: mark elements for regular refinement



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Numerical examples

Refinement algorithm: perform regular refinement + transition cells



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Numerical examples

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Re-coarsening algorithm: vertices from initial grid are locked



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Re-coarsening algorithm: keep cells and lock connected vertices



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Numerical examples

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Re-coarsening algorithm: "lock vertex if there are younger ones"



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Numerical examples

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Re-coarsening algorithm: "prevent creation of blue elements"



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Numerical examples

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Re-coarsening algorithm: remove vertices and update elements



Motivation 00

Grid adaptivity ○○○●

Implementation details 000 Numerical examples



If the triangulation $\mathcal{T}_m = (\mathcal{E}_m, \mathcal{V}_m)$ is constructed from $\mathcal{T}_0 = (\mathcal{E}_0, \mathcal{V}_0)$ by performing *m* red-green refinement steps then each element $\Omega_k \in \mathcal{E}_m$ can be uniquely characterized by the generation number of the vertices.

Example: quadrilaterals

- If all vertices of Ω_k have zero age, then $\Omega_k \in \mathcal{E}_0$
- If three vertices of Ω_k have the same generation number, then the element is a red quadrilateral
- If exactly two consecutive vertices of Ω_k have largest generation number (in the cell), then the element is a green quadrilateral and the adjacent element Ω_l is the green neighbor





Motivation 00 Implementation details



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Motivation 00 Implementation details



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Motivation 00 Implementation details



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Motivation 00

Grid adaptivity 0000

Example: triangles

- If all vertices of Ω_k have the same generation number, then the element is an inner red triangle
- If exactly two vertices of Ω_k have largest generation number (in the cell), then the element is an outer red triangle provided that the adjacent element is an inner red triangle. Otherwise, it is a green triangle
- If exactly one vertex v_i of Ω_k has largest generation number (in the cell), then the element is a green triangle and three difference cases are possible:
 - Adjacent element Ω_l has one vertex with largest generation number and it is the common node v_i
 - There exists one neighboring green triangle with exactly two vertices with largest generation number
 - There exist **two** neighboring green triangles sharing the common node *v_i* with largest generation number



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Motivation 00 Implementation details

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Motivation

Implementation details OOO Numerical examples

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 - There exists one neighboring green triangle with exactly two vertices with largest generation number
 - There exist **two** neighboring green triangles sharing the common node v_i with largest generation number



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Idea I: State function $s : \mathcal{E}_m \to \mathbb{Z}$ (in MSB representation)

- Set Bit [0] to 1 for quadrilateral, otherwise set it to zero
- Set Bit [k=1..4] to 1 if both endpoints of edge k have same age
- If no two endpoints have same age, then find local position k of the youngest vertex, set Bit[k] to 1 and negate the state

Idea II: Define local ordering strategy within each element a priori

element characterization	element state

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11 Motivation

Grid adaptivity

Implementation details

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Idea I: State function $s : \mathcal{E}_m \to \mathbb{Z}$ (in MSB representation)

- Set Bit [0] to 1 for quadrilateral, otherwise set it to zero
- Set Bit [k=1..4] to 1 if both endpoints of edge k have same age
- If no two endpoints have same age, then find local position k of the youngest vertex, set Bit[k] to 1 and negate the state

Idea II: Define local ordering strategy within each element a priori

element characterization	element state		
triangle/quadrilateral from \mathcal{T}_0	0/1		
green quadrilateral	3, 5, 9, 11, 17, 21		
red quadrilateral	7, 13, 19, 25		
inner red triangle	14		
'other' triangle	2, 4, 8		
green triangle	-8, -4, -2		

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triangle/quadrilateral from \mathcal{T}_0	0/1		
green quadrilateral	5,	21	a b
red quadrilateral	13		#el+3
inner red triangle	14		#el+5
'other' triangle	4		#el+4 • • #el+2
green triangle	-8, -4, -2		a <u>1</u> b #el+1

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Motivation

Convection in
$$\Omega = (0, 1)^2$$
$$\frac{\partial u}{\partial t} + \nabla \cdot (\mathbf{v}u) = 0$$

with velocity $\mathbf{v}(t)$, $t \in (0, T)$

$$v_x = \sin^2(\pi x)\sin(2\pi y)g(t)$$

$$v_y = -\sin^2(\pi y)\sin(2\pi x)g(t)$$

$$g(t) = \cos(\pi t/T), \quad T = 1.5$$

 32×32 coarse grid + 3 ref. steps 29.345 cells, 26.189 vertices





Motivation 00 Grid adaptivity 0000 Implementation details 000

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Conclusions and Outlook

Implementation details 000

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 32×32 coarse grid + 3 ref. steps 30.798 cells, 27.452 vertices



Time 0.25

Implementation details 000

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 32×32 coarse grid + 3 ref. steps 33.080 cells, 29.516 vertices



Time 0.5

Implementation details 000

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 32×32 coarse grid + 3 ref. steps 33.371 cells, 29.817 vertices



Time 0.75

Convection in
$$\Omega = (0, 1)^2$$

$$\frac{\partial u}{\partial t} + \nabla \cdot (\mathbf{v}u) = 0$$

with velocity $\mathbf{v}(t)$, $t \in (0, T)$

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$$g(t) = \cos(\pi t/T), \quad T = 1.5$$

 32×32 coarse grid + 3 ref. steps 33.639 cells, 30.089 vertices



Time 1.0

Convection in
$$\Omega = (0, 1)^2$$
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with velocity $\mathbf{v}(t)$, $t \in (0, T)$

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$$v_y = -\sin^2(\pi y)\sin(2\pi x)g(t)$$

$$g(t) = \cos(\pi t/T), \quad T = 1.5$$

 32×32 coarse grid + 3 ref. steps 32.456 cells, 29.177 vertices



Time 1.25

Convection in
$$\Omega = (0, 1)^2$$

$$\frac{\partial u}{\partial t} + \nabla \cdot (\mathbf{v}u) = 0$$

with velocity $\mathbf{v}(t)$, $t \in (0, T)$

$$v_x = \sin^2(\pi x)\sin(2\pi y)g(t)$$

$$v_y = -\sin^2(\pi y)\sin(2\pi x)g(t)$$

$$g(t) = \cos(\pi t/T), \quad T = 1.5$$

 32×32 coarse grid + 3 ref. steps 30.774 cells, 27.691 vertices



Time 1.5

Example: Swirling flow, contd.

Initial profile



13

Motivation 00 Grid adaptivity 0000 Implementation details

Numerical examples

Conclusions and Outlook

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Example: Swirling flow, contd.

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Initial profile and final solution computed by semi-implicit FEM-FCT



13

Motivation 00 Grid adaptivity 0000 Implementation details 000

Numerical examples

Example: Compressible flows

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Forward facing step, t = 4.0, 30 contour lines



Double Mach reflection, t = 0.2, 30 contour lines



• solutions are computed by algebraic flux correction scheme; Kuzmin

• Crank-Nicolson time stepping approach is adopted

Implementation details

Example: Compressible flows

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Double Mach reflection, t = 0.2, 30 contour lines



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Grid adaptivity 0000 Implementation details

Conclusions

- hierarchical grid adaptivity can be based on red-green strategy
- grid re-coarsening can be based on locking of vertices
- grid genealogy can be recovered from nodal generation numbers
- cells can be easily identified from element state function

Future work

- Combine local grid adaptation with structured grids (HPC)
- Implement refinement/re-coarsening algorithms in 3D
- Improve error indicators/estimators also for time-dependent flows





Conclusions and Outlook

Motivation 00 Grid adaptivity 0000 Implementation details 000

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Motivation 00 Grid adaptivity 0000 Implementation details 000 Numerical examples

Conclusions and Outlook

technische universität

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Implementation details 000 Conclusions and Outlook

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Steady-state flows

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Scramjet inlet at Ma = 3.0, $\alpha = 0^{\circ}$



16

Motivation 00 Grid adaptivity 0000 Implementation details 000

Numerical examples

Steady-state flows

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Scramjet inlet at Ma = 3.0, $\alpha = 0^{\circ}$



16

Motivation 00 Grid adaptivity 0000 Implementation details

Numerical examples

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Conclusions and Outlook

16

Motivation 00 Grid adaptivity 0000 Implementation details