



AMFLOW 2001

Workshop on

Adaptive Methods for Flow Computation

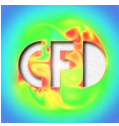
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Heidelberg University

Multigrid Method for Stabilized Nonconforming Finite Element for Incompressible Flow

A. Ouazzi*, S. Turek

Dortmund University



1 Motivation

1.1 Quasi-Newtonian fluids

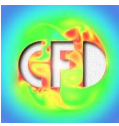
A fluid is called Quasi-Newtonian if the Cauchy stress tensor is given by

$$\sigma = 2\nu(D_{II}(u))D(u) \quad (1)$$

where

$$D_{II}(u) = \frac{1}{2}D(u) : D(u) = \frac{1}{2} \sum_{i,j} D_{i,j}(u)D_{i,j}(u),$$

and $\nu(\cdot)$ the viscosity



Models

- Power law defined for

$$\nu(z) = \nu_0 z^{\frac{r}{2}-1}$$

- Carreau law defined for

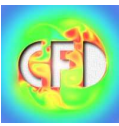
$$\nu(z) = \nu_\infty + (\nu_0 - \nu_\infty)(1 + \lambda z)^{\frac{r}{2}-1}$$

- Schaeffer model (Granular flow) defined for

$$pz^{\frac{-1}{2}}$$

- Further extension (planned)

$$\nu(D, p, T)$$



1.2 Nonlinear Newton variants

Let u^l being an initial state, Newton method reads

$$\begin{aligned} & \int_{\Omega} 2\nu(D_{II}(u^l)) D(u) : D(v) \\ + & \int_{\Omega} 2\nu'(D_{II}(u^l)) [D(u^l) : D(u)][D(u^l) : D(v)] \\ = & \int_{\Omega} f v - \int_{\Omega} 2\nu(D_{II}(u^l)) D(u^l) : D(v) \end{aligned} \quad \forall v \in V \quad (2)$$

where $\nu'(\cdot)$ is the derivative of ν

This leads to the sequence of linear problem

$$A(u^l)v + \delta A^*(u^l)v = Res(u^l).$$

2 Finite Element Approximation

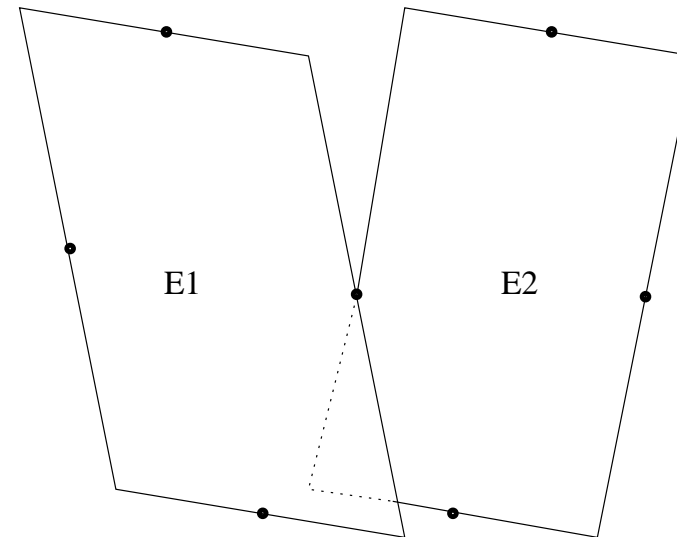
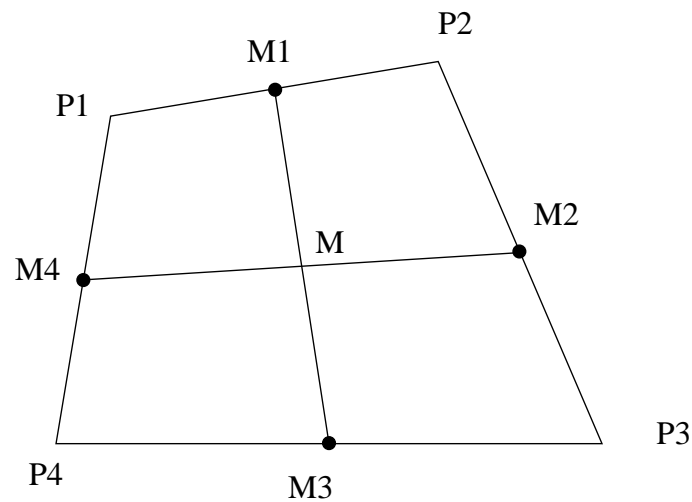
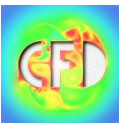


Figure 1: Rannacher-Turek element. Figure 2: Continuity across the edges.

- Advantage:
 - Stable and efficient for incompressible flow.
 - Compact data structures.

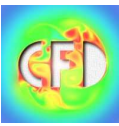


- Disadvantage:
 - Not satisfying discrete Korn's inequality

$$\|D(u)\|_{L_2(\Omega)} \geq \text{Const}\|u\|_{H^1(\Omega)}.$$

- Remedy (cf. Larson and Hansbo work)
Introduce the jump in a discrete formulation (Nitsche's method)
as a stabilization parameter of order h^{-1} ,

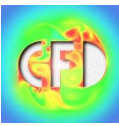
$$[E_h]_{i,j} = h^{-1} \sum_{\text{Edges}} \int_{\text{Edge}} [\phi_i][\phi_j] ds \quad (3)$$



The resulting system in a matrix form reads:

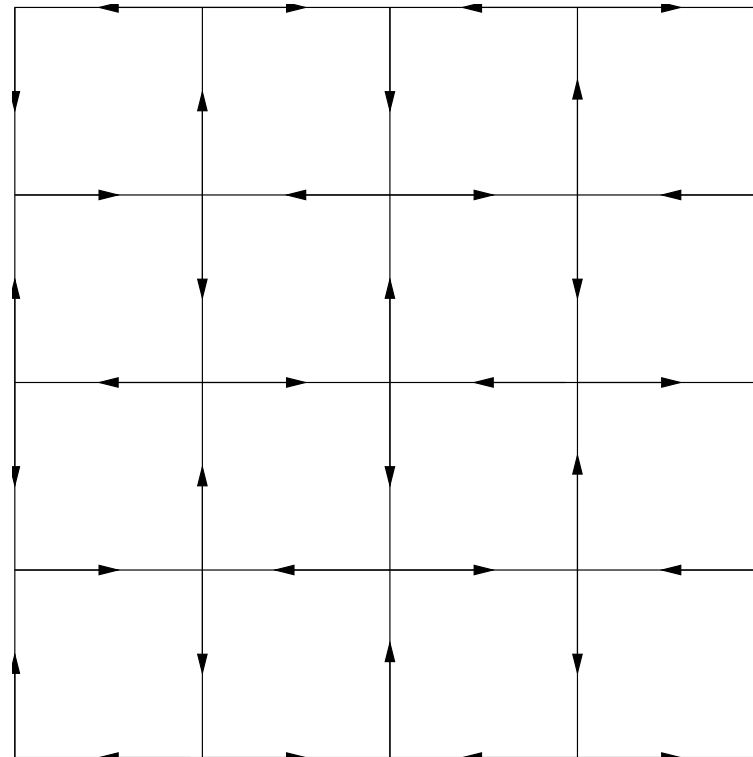
$$\begin{cases} A_h(u^l)u + \delta A_h^*(u^l)u + sE_h u + B_h p = Res_h(u^l), \\ B_h^T u = 0. \end{cases} \quad (4)$$

- Linearization
 - Fixed point linearization is supplied for $\delta = 0$.
 - Full Newton linearization is supplied for $\delta = 1$.
- Result (see Hansbo et. al)
 - Stable system.
 - Optimal accuracy.
- Problem
 - The solver?!

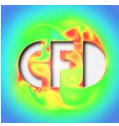


3 Korn's Inequality

Kernel Function



The kernel function takes -1 or 1 in midpoints



Korn's Inequality

Level	NEL	$\ u_h\ _A$	$\ u_h\ _T$	$\ u_h\ _{ST}$
2	4	0.91	$0.63E - 15$	0.30
3	16	1.1	$0.20E - 14$	0.60
4	64	1.3	$0.41E - 14$	0.76
5	256	1.3	$0.69E - 14$	0.85
6	1024	1.4	$0.14E - 14$	0.90
7	4096	1.4	$0.30E - 13$	0.92
8	16384	1.4	$0.61E - 13$	0.93

where

$$u_h = \sum_i X_i \phi_i$$

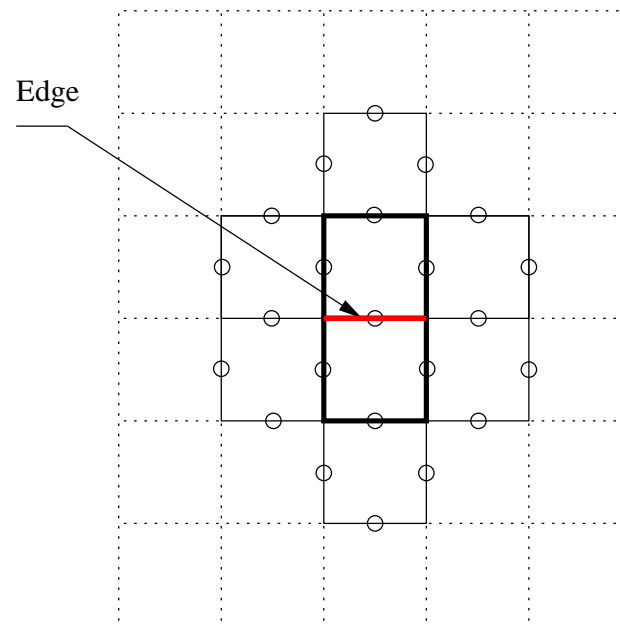
$$\|u_h\|_M = \left(\sum_{i,j} M_{ij} X_i X_j \right)^{\frac{1}{2}}$$

A, T and ST be the resulting matrices from gradient, tensor and stabilized tensor discretization respectively .

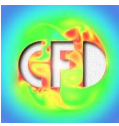
4 Linear multigrid solver

4.1 Sparsity of the matrix

Involved Elements for each Edge



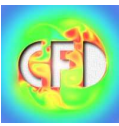
- Seems to contradict the FEM storage philosophy!



4.2 Vanka smoother as defect correction

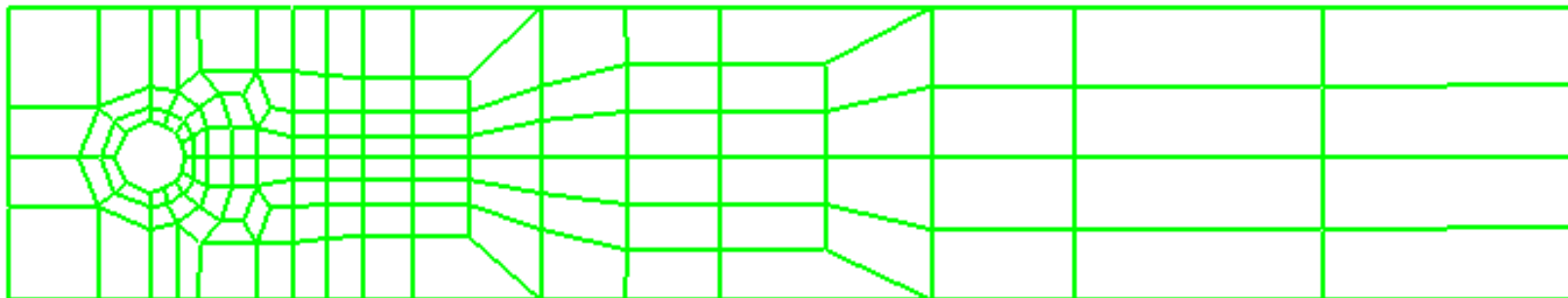
$$\begin{bmatrix} u^n \\ p^n \end{bmatrix} = \begin{bmatrix} u^{n-1} \\ p^{n-1} \end{bmatrix} + \sum_i \left(\begin{array}{cc} N_{|\Omega_i}^* & B_{|\Omega_i} \\ B_{|\Omega_i}^T & 0 \end{array} \right)^{-1} \begin{bmatrix} Res_1(u^{n-1}, p^{n-1}) \\ Res_2(u^{n-1}, p^{n-1}) \end{bmatrix}$$

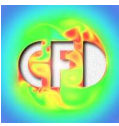
- Ω_i is a “patch” (which is only one element in our recent tests)
- $N^* = A + \delta A^*$
- Res is the full defect ($N^* + sE_h$)
- “ \sum_i ” means Jacobi, or Gauss-Seidel, or some kind of average.



5 Effect of convective term

The Coarse Mesh for Flow around cylinder Benchmark

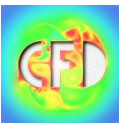




Lift and Drag Forces

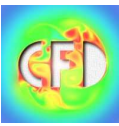
Level 5				
$1/\nu$		grad	Tensor	S. Tensor
1	lift	$0.31252D + 04$	$0.31221D + 04$	$0.31231D + 04$
	drag	$0.30898D + 02$	$0.30924D + 02$	$0.30936D + 02$
10	lift	$0.31258D + 03$	$0.31227D + 03$	$0.31237D + 03$
	drag	$0.36832D + 01$	$0.36851D + 01$	$0.36864D + 01$
100	lift	$0.32016D + 02$	$0.31981D + 02$	$0.31990D + 02$
	drag	$0.79786D + 00$	$0.79758D + 00$	$0.79770D + 00$
1000	lift	$0.55657D + 01$	$0.55531D + 01$	$0.55535D + 01$
	drag	$0.10180D - 01$	$0.10259D - 01$	$0.10277D - 01$

No differences !



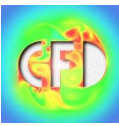
Effect of Convective Term

	$1/\nu$	1	10	100	1000($Re = 20$)
Level	Formulation	NL/MG	NL/MG	NL/MG	NL/MG
4	grad	3/3	4/3	6/3	11/4
	tensor	3/15	5/17	6/13	11/4
	stabilized tensor	3/3	5/3	6/3	11/4
5	grad	3/3	4/3	6/3	11/3
	tensor	4/140	5/35	6/15	11/10
	stabilized tensor	4/3	5/3	7/3	11/3
6	grad	3/3	4/3	6/3	11/3
	tensor	4/513	4/161	7/17	11/12
	stabilized tensor	3/3	4/3	7/3	11/3



Summary

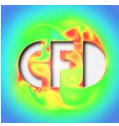
- Tensor
 - Problem only with multigrid for **small** Re number !
- Stabilized tensor
 - Stable.
 - Optimal accuracy.



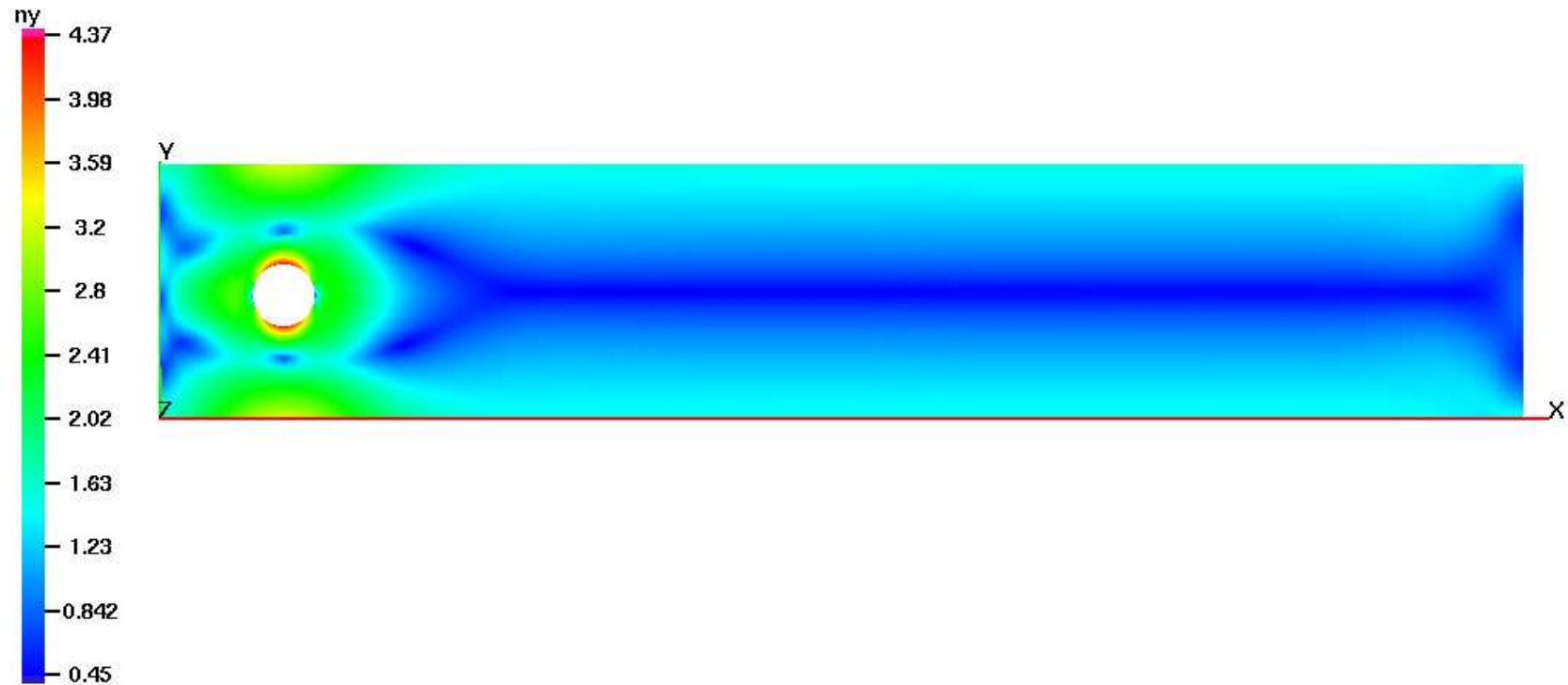
6 Stabilization parameters

NNL/NMG for Nonlinear Viscosity

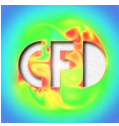
$\nu(D) = \nu_0(0.1 + \ D\)^\alpha.$						
α	-0.7			+0.7		
Level	0	s_{min}	s_{local}	0	s_{min}	s_{local}
3	26/48	48/2	35/2	17/7	17/2	17/2
4	26/140	26/2	36/ 2	18/15	17/2	17/2
5	27/414	24/3	32/2	50/212	17/3	17/3
6	–	27/3	25/3	–	17/3	17/3



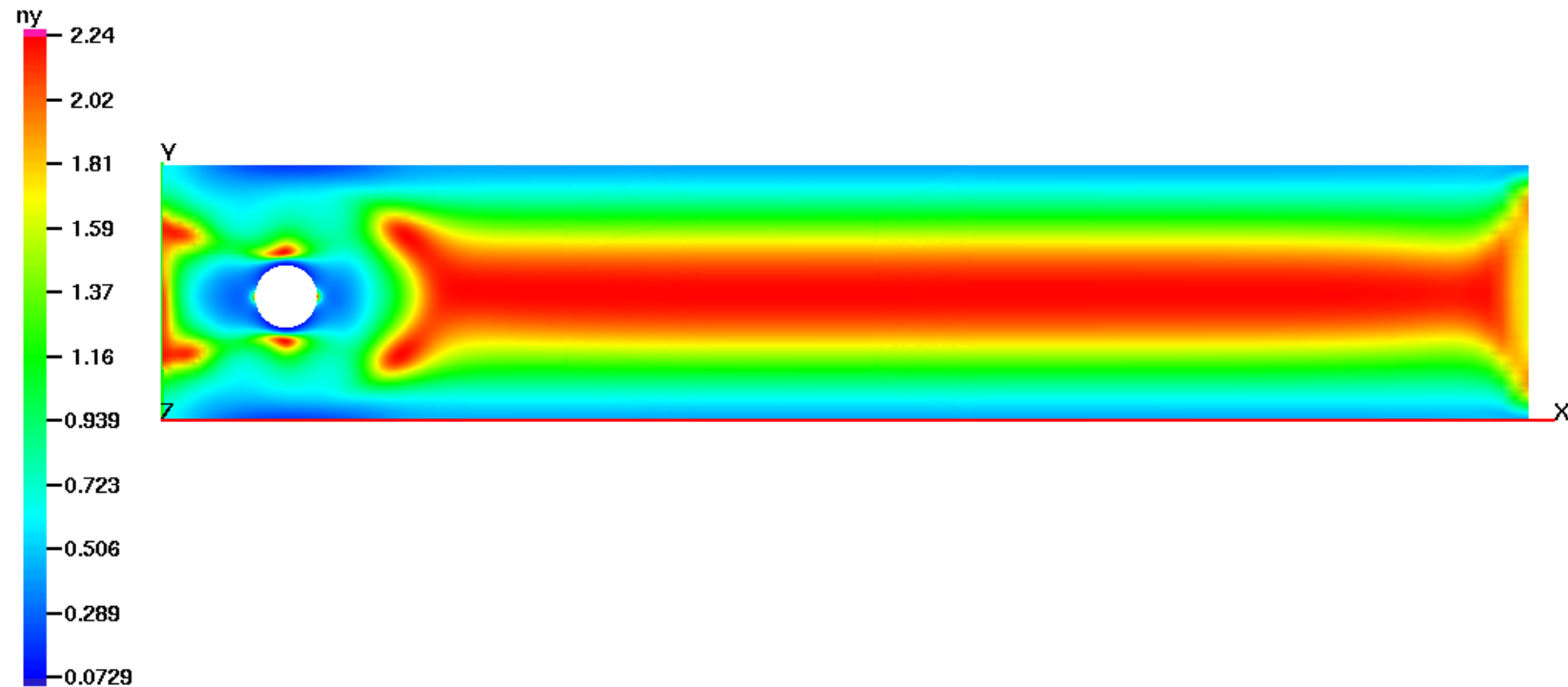
The viscosity for Shear Thickening



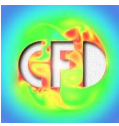
Factor of 10!



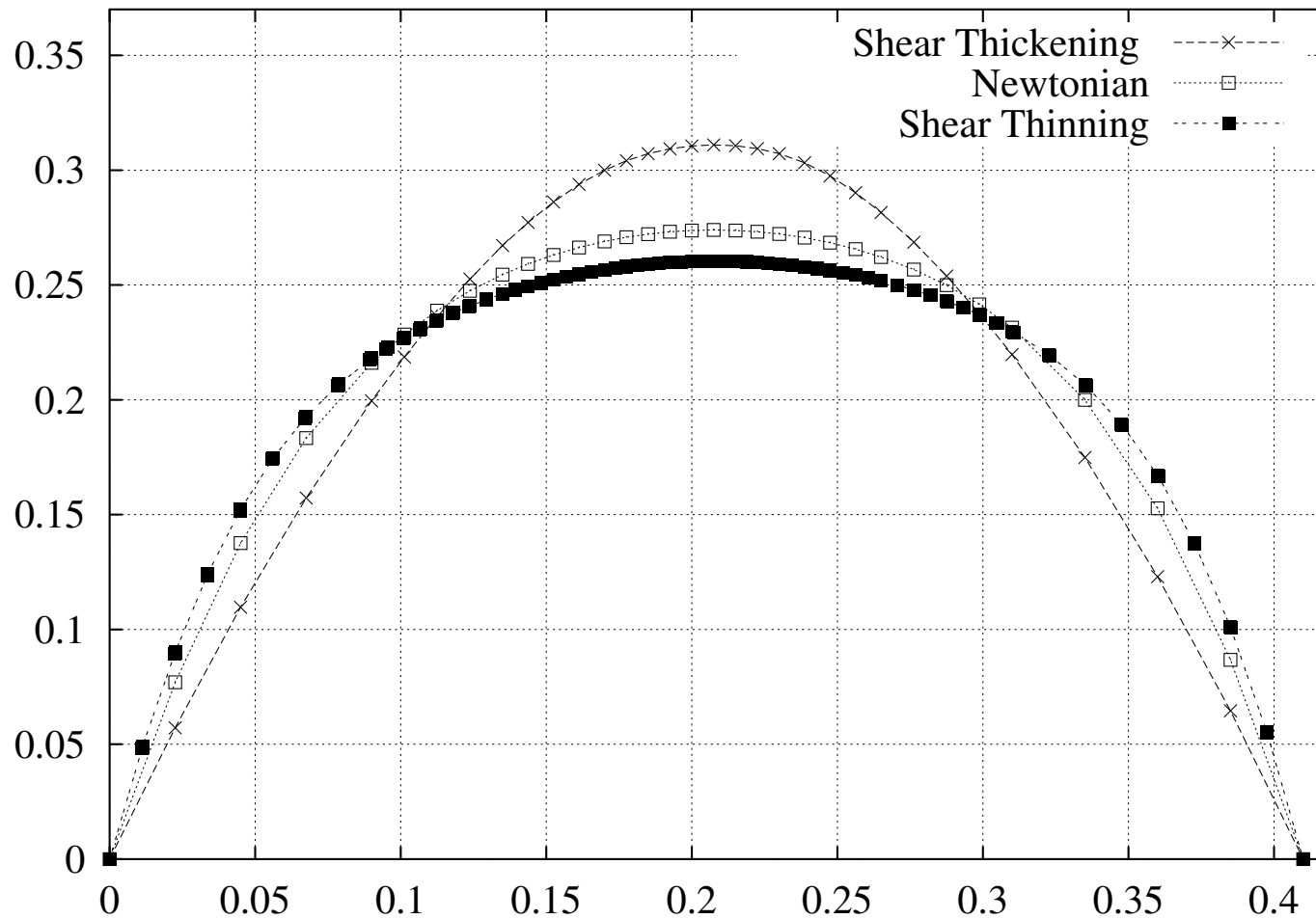
The viscosity for Shear Thinning

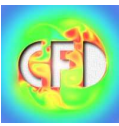


Factor of 30!



The velocity Profiles





7 Current work

Many challenges still remain to be overcome:

- Develop best strategy to apply the stabilization for the quasi-Newtonian models or plasticity model

$$\nu = \nu(D(u)) \rightarrow s(\cdot)?$$

- Develop best strategy to apply the stabilization in conjunction with the Newton linearization technique.
- Improve multigrid solver (adaptive patching).