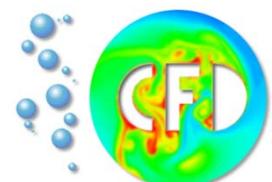


Was ist...? The Lattice Boltzmann Method

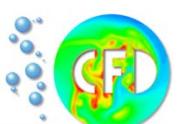
Presentation by:
Amin Safi

PhD Candidate in Applied Mathematics, Lsiii

May 14, 2014

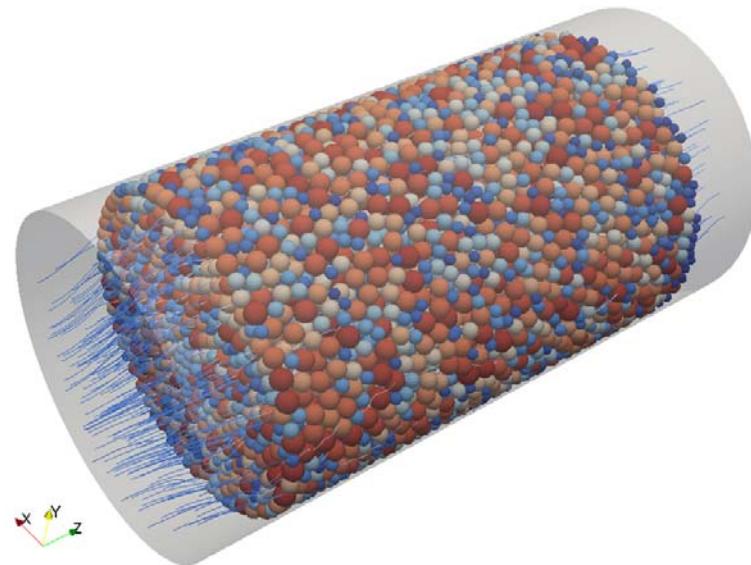


- **Opening and Introduction**
- **Historical Background**
- **Implementation**
- **From LBE to Navier-Stokes**
- **LBM in Action**
- **A word on parallel computing**

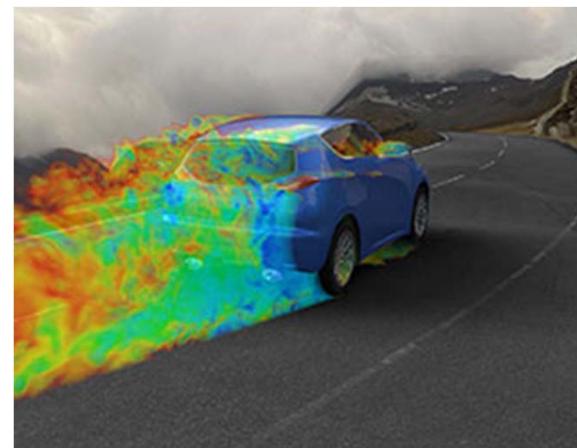


■ What is LBM?

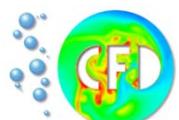
- ▶ Lattice Boltzmann Method is a rather new method in CFD
- ▶ Introduced in 1988 by *McNamara and Zanetti*
- ▶ Proved to be accurate for incompressible subsonic flows
- ▶ Robust for non-trivial geometries and complex physical phenomena
- ▶ Widely used in oil exploration, car aerodynamic design, ocean current studies, chemically reacting flows ...



Safi, Ashrafaadeh, 2013



EXA Corporation



■ Macroscopic Approach

- ▶ Continuum mechanics

Properties are continuous and derivatives exist!!

$$u(x, t), P(x, t), T(x, t)$$

- ▶ Governing partial differential equations (*Navier-Stokes Eq.*)

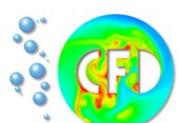
$$\frac{\partial u}{\partial t} + (u \nabla) u = -\nabla P + \nu \nabla^2 u$$

$$\nabla \cdot u = 0$$

- ▶ Pick a numerical scheme to discretize the PDE(s)

- ▶ Finite Difference (FD)
- ▶ Finite Volume (FV)
- ▶ Finite Element (FE)

- ▶ Implement the solution on computers (*write a code!!*)



■ Mesoscopic Approach

- ▶ Microscopic view of particles distribution, f

Probabilities to find a particle in specific space, velocity direction and time

$$f(x, v, t)$$

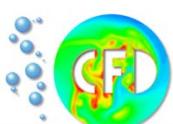
- ▶ Averaging over f gives the properties

$$\rho(x, t) = \int d^3v f(x, v, t)$$

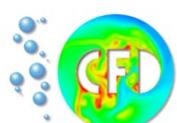
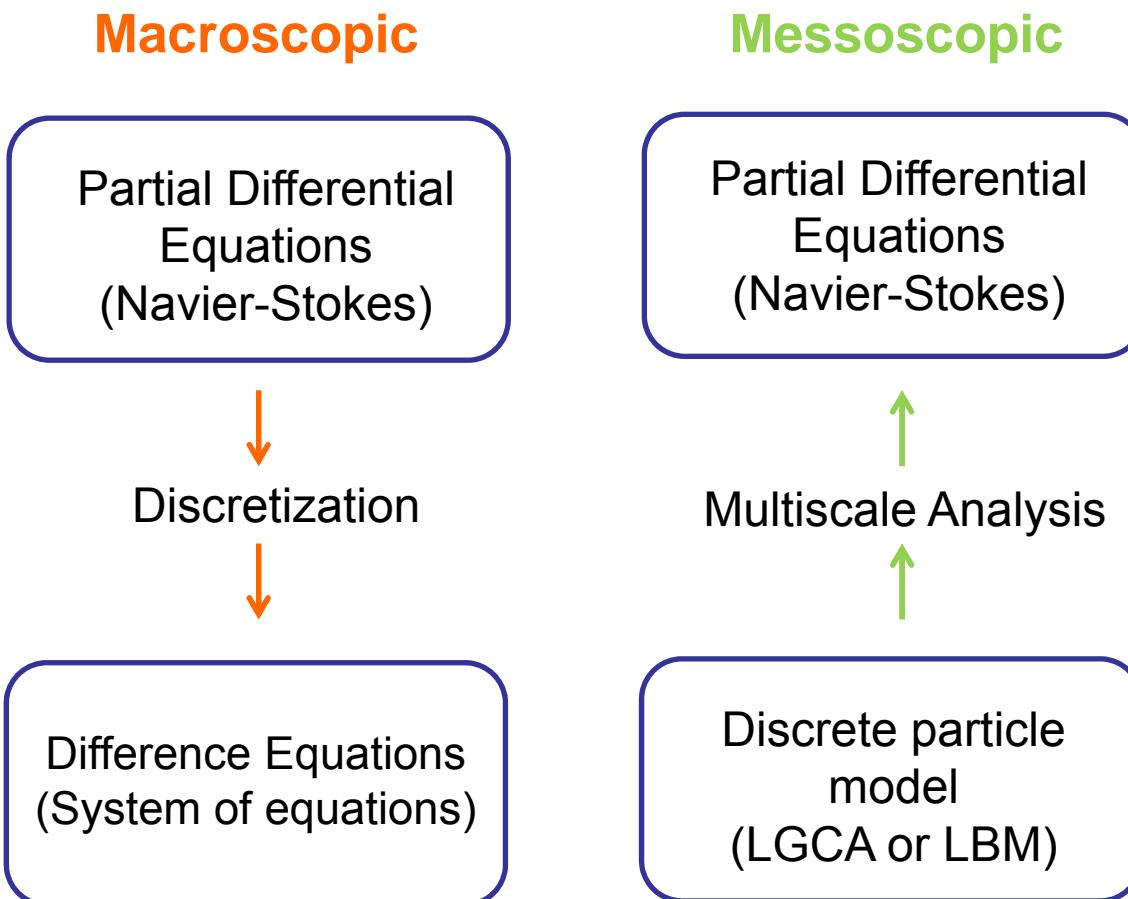
- ▶ Track the time evolution of f through *Boltzmann Equation*

$$\frac{\partial f}{\partial t} + v \frac{\partial f}{\partial x} = \Omega(x, t)$$

- ▶ Discretize v over a *lattice* and apply FD to solve the PDE
- ▶ Navier-Stokes Eqs. could be recovered through *multi-scale analysis!*

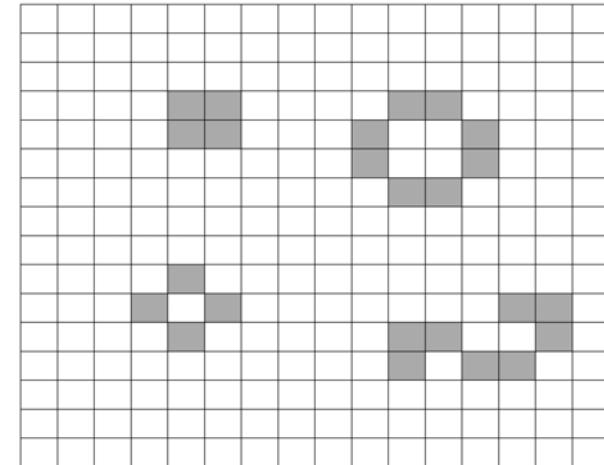


- Summary; *top-down* vs. *bottom-up* approach



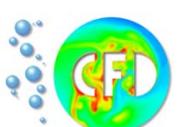
■ Cellular Automata (1950s)

- ▶ Regular arrangement of cells
- ▶ Cells hold finite number of states
- ▶ States update at discrete time levels
- ▶ Update based on certain *rules* (deterministic)
- ▶ Rules depend on the states of the neighboring cells

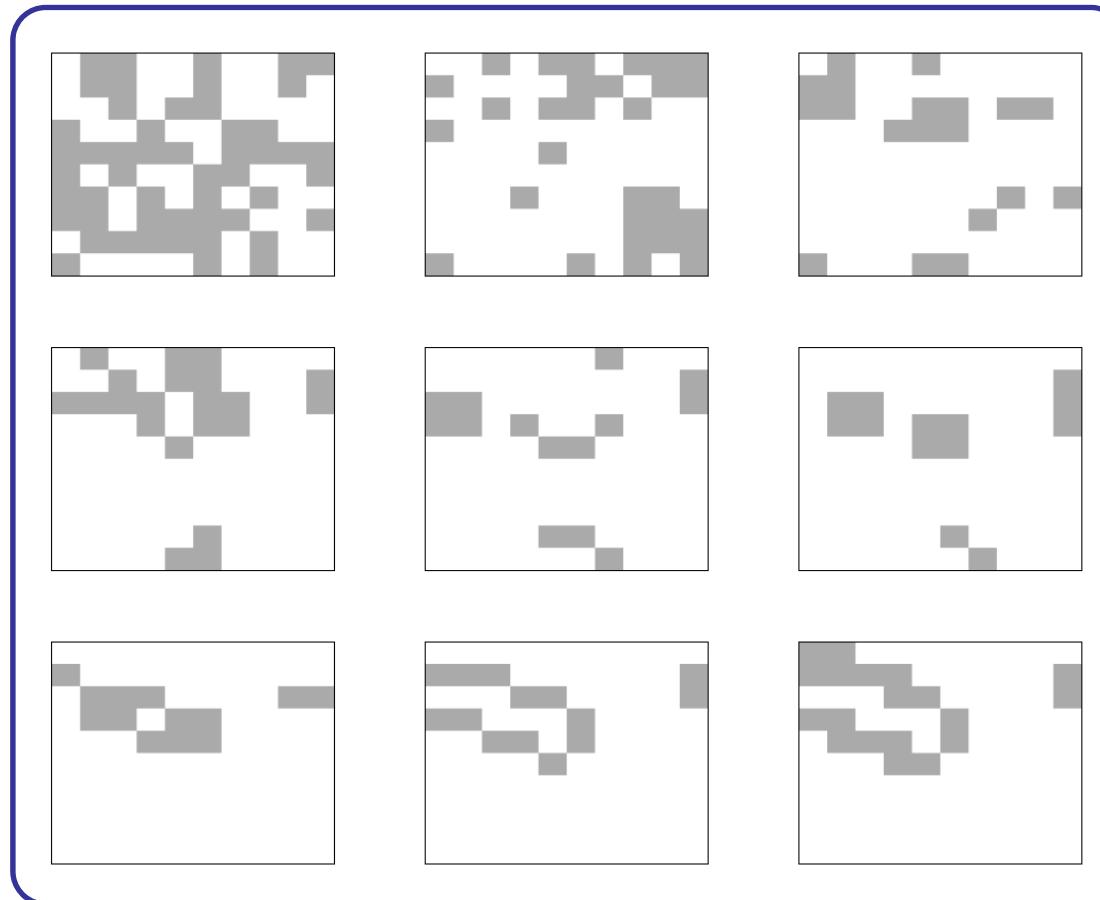


■ Rule example: ‘Life’ cellular automata (Conway 1970)

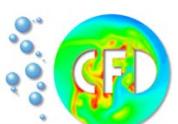
1. *Each live site will remain alive the next time-step if it has two or three live neighbors, otherwise it will die*
2. *At a dead site new live will be born only if there are exactly three live neighbors.*



'Life' cellular automata



10×10 array, $T = 0$ to $T = 7$

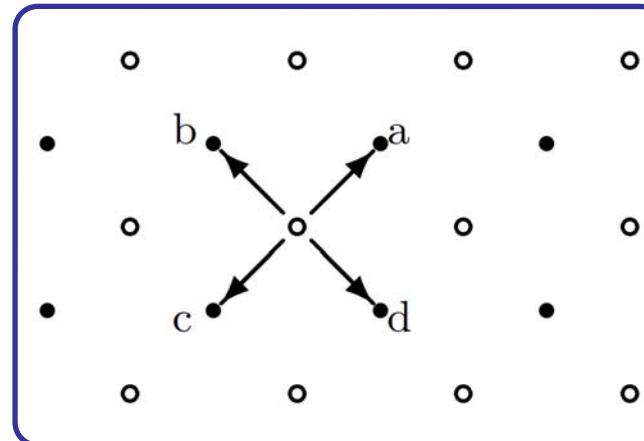


- Lattice Gas Cellular Automata (1970s)

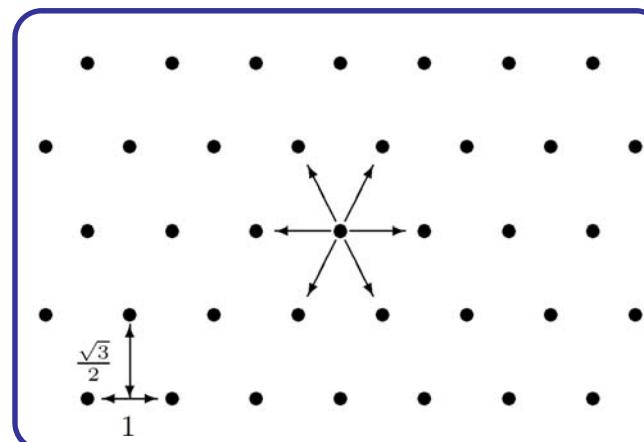
- ▶ Each node is surrounded by particle cells being empty (0) or full (1)
- ▶ Particles at cells around each node move on certain directions
- ▶ Collisions based on certain rules
- ▶ **Collision + Streaming** of particles synchronously for all nodes

$$n_i(t+1, r + c_i) = n_i + \Delta_i$$

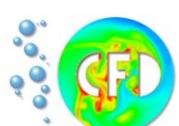
- ▶ Eventually simulates fluid flow
- ▶ **Problem:** high noise, non-deterministic collisions,...



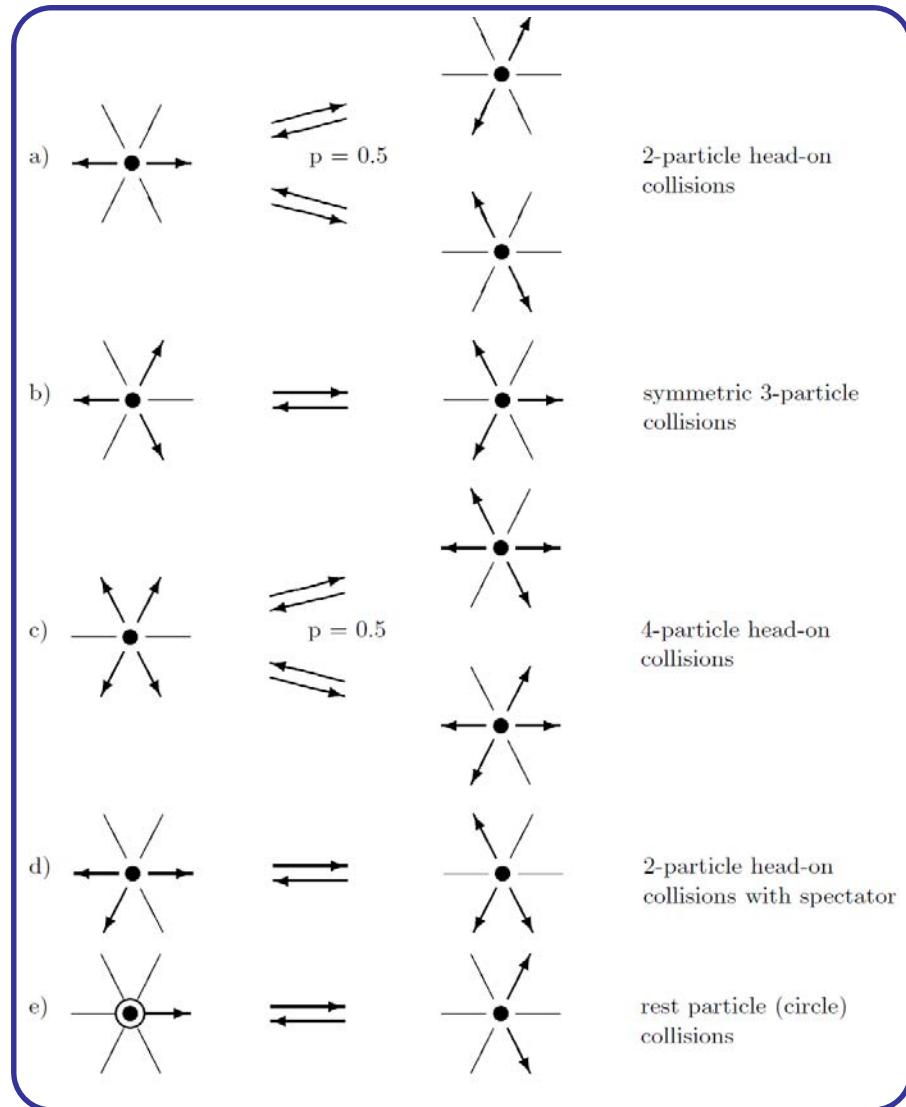
HPP model, Hardy, de Pazzis and Pomeau (1973)



FHP model, Frisch, Hasslacher and Pomeau (1986)



FHP: Collision rules



Wolf-Gladrow, Lattice-Gas Cellular Automata and Lattice Boltzmann Models, 2005

- Particle velocity

$$c_i = \left(\cos \frac{\pi}{3} i, \sin \frac{\pi}{3} i \right), \quad i = 1, \dots, 6$$

- Particle occupation

$$N_i(t, r) = \langle n_i(t, r) \rangle$$

- Macroscopic density

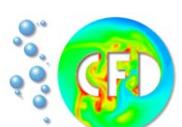
$$\rho(t, r) := \sum_i N_i(t, r)$$

- Macroscopic momentum

$$\mathbf{j}(t, r) := \sum_i c_i N_i(t, r)$$

- Macroscopic pressure

$$p = \frac{\rho}{2}$$



■ Lattice Boltzmann Method (1988)

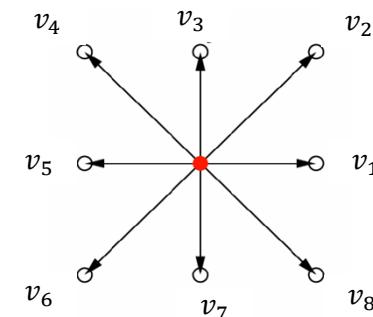
- ▶ Time evolution of $f(x, v, t)$ through **Boltzmann Equation (1870)**

$$\frac{Df}{Dt} = \frac{\partial f}{\partial t} + \mathbf{v} \frac{\partial f}{\partial x} = \Omega(x, t)$$

- ▶ Discretize the space of the velocities to a **finite** set of velocities

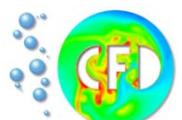
$$\mathbf{v} \longrightarrow \mathbf{v}_i \quad , i = 0, 1, \dots, b$$

$$f(x, v, t) \longrightarrow f_i(x, t)$$



- ▶ **Discrete Boltzmann equation (DBE)** with BGK form of collision

$$\frac{\partial f_i}{\partial t} + \mathbf{v}_i \frac{\partial f_i}{\partial x} = -\frac{1}{\tau} (f_i - f_i^{eq}), \quad i = 0, 1, \dots, b$$



- ▶ Non-dimensionalizing the Discrete Boltzmann Equation

$$\frac{\partial F_i}{\partial \hat{t}} + c_i \frac{\partial F_i}{\partial \hat{x}} = -\frac{1}{\hat{\tau}\epsilon} (F_i - F_i^{eq})$$

where: $c_i = \frac{v_i}{U}$, $\hat{x} = \frac{x}{L}$, $\hat{t} = \frac{t U}{L}$, $\hat{\tau} = \frac{\tau}{\Delta t}$, $F_i = \frac{f_i}{n_r}$, $\epsilon = \frac{\Delta t U}{L}$

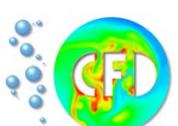
- ▶ Discretize the DBE in space and time using *finite difference* method

$$\frac{F_i(x, t + \Delta t) - F_i(x, t)}{\Delta \hat{t}} + c_{ix} \frac{F_i(x + \Delta x, t + \Delta t) - F_i(x, t + \Delta t)}{\Delta \hat{x}} + \dots = -\frac{1}{\hat{\tau}\epsilon} (F_i - F_i^{eq})$$

- ▶ Choosing $c_i = \frac{\Delta \hat{x}}{\Delta \hat{t}}$ leads to **Lattice Boltzmann Equation (LBE)**

$$F_i(x + \Delta x, t + \Delta t) - F_i(x, t) = -\frac{1}{\tau} (F_i(x, t) - F_i^{eq}(x, t))$$

Perfect shift form / Lagrangian form



■ LBM algorithm

- 1) Initialize to equilibrium state

$$F_i = F_i^{eq}(\rho, \mathbf{j}) = -\frac{w_i}{\rho} \left(\rho + \frac{m}{K_B T} c_i \cdot \mathbf{j} + \frac{m}{2 \rho K_B T} - \left[\frac{m}{K_B T} (c_i \cdot \mathbf{j})^2 - \mathbf{j}^2 \right] \right)$$

- 2) Perform collision and streaming

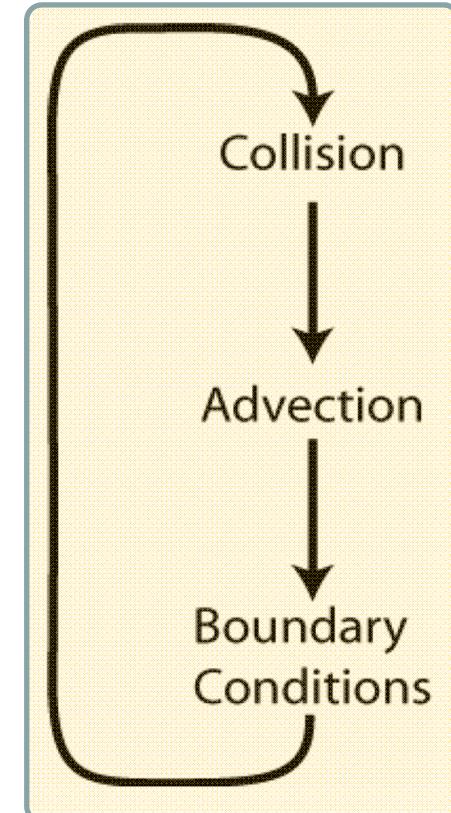
$$F_i(x + \Delta x, t + \Delta t) - F_i(x, t) = -\frac{1}{\tau} (F_i(x, t) - F_i^{eq}(x, t))$$

↗

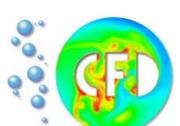
Collision: $F_i^*(x, t) = -\frac{1}{\tau} (F_i(x, t) - F_i^{eq}(x, t))$
Streaming: $F_i(x + \Delta x, t + \Delta t) = F_i^*(x, t)$

- 3) Apply boundary conditions

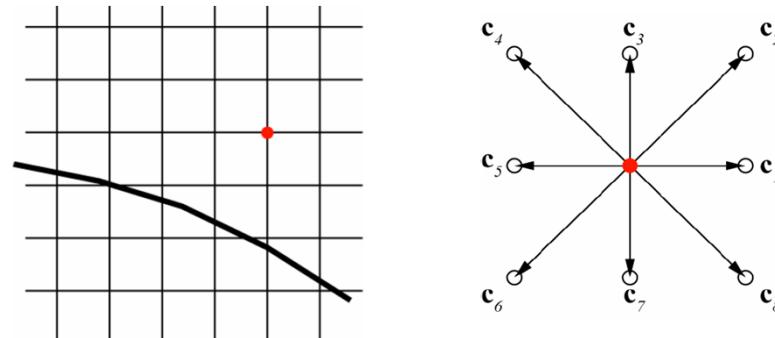
- 4) Calculate macroscopic properties and return to step 2



G. Pullan
Cambridge Uni.



- LBM in 2D: The D2Q9 model



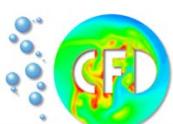
► Lattice velocities

$$\left\{ \begin{array}{l} c_0 = (0,0) \\ c_{1,5} = (\pm 1, 0) \\ c_{3,7} = (0, \pm 1) \\ c_{2,4,6,8} = (\pm 1, \pm 1) \end{array} \right.$$

► Macroscopic moments of F_i

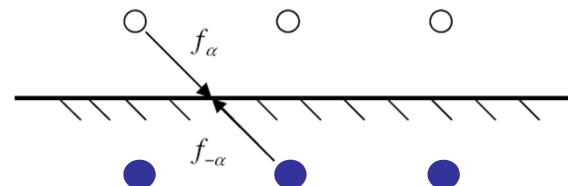
Density: $\rho(t, r) := \sum_i F_i(x, t)$

Momentum: $\rho \boldsymbol{u}_\alpha := \sum_i c_{i\alpha} F_i(x, t)$

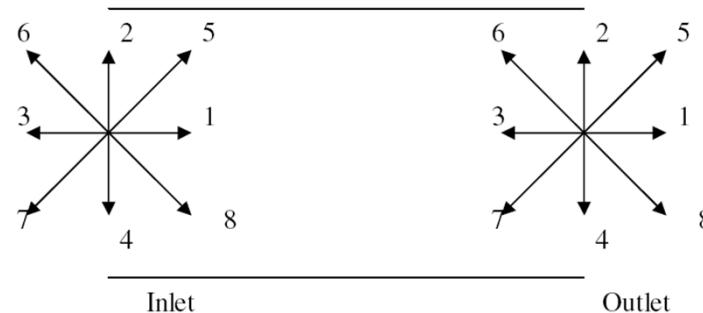


■ Boundary conditions

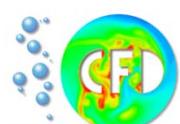
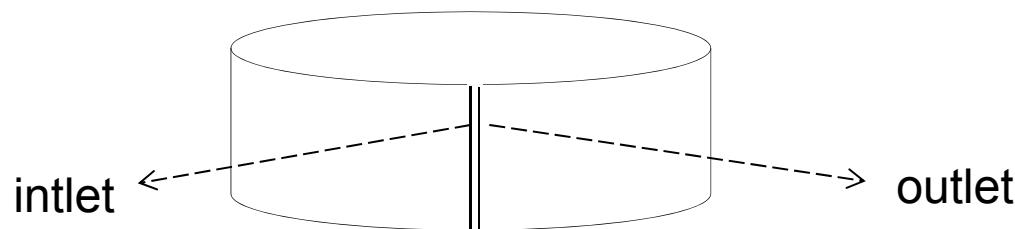
► Solid wall \longrightarrow bounce back scheme



► Inlet/outlet \longrightarrow Zou-He method



► Periodic boundaries



- The Multi-scale analysis

$$F_i(\mathbf{x} + \mathbf{c}_i \Delta t, t + \Delta t) - F_i(\mathbf{x}, t) = -\frac{\Delta t}{\tau} \left[F_i(\mathbf{x}, t) - F_i^{(0)}(\mathbf{x}, t) \right] \\ + \frac{\Delta t c_{i\alpha}}{12c^2} [K_\alpha(\mathbf{x}, t) + K_\alpha(\mathbf{x} + \mathbf{c}_i \Delta t, t + \Delta t)]$$

- Asymptotic expansion of F_i around equilibrium $F_i^{eq} = F_i^0$ up to ϵ^2

$$F_i(\mathbf{x}, t) = F_i^{(0)}(\mathbf{x}, t) + \epsilon F_i^{(1)}(\mathbf{x}, t) + \epsilon^2 F_i^{(2)} + \mathcal{O}(\epsilon^3)$$

- Taylor expansion of $F_i(\mathbf{x} + \Delta x, t + \Delta t)$ around $F_i(\mathbf{x}, t)$

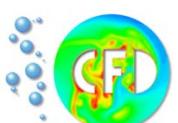
$$F_i(\mathbf{x} + \mathbf{c}_i \Delta t, t + \Delta t) = F_i(\mathbf{x}, t) + \Delta t \partial_t F_i + \Delta t c_{i\alpha} \partial_{x_\alpha} F_i$$

$$+ \frac{(\Delta t)^2}{2} [\partial_t \partial_t F_i + 2c_{i\alpha} \partial_t \partial_{x_\alpha} F_i + c_{i\alpha} c_{i\beta} \partial_{x_\alpha} \partial_{x_\beta} F_i] + \mathcal{O}(\partial^3 F_i)$$

- Use *two different scalings* for time and space derivatives

$$\partial_t \rightarrow \epsilon \partial_t^{(1)} + \epsilon^2 \partial_t^{(2)}$$

$$\partial_{x_\alpha} \rightarrow \epsilon \partial_{x_\alpha}^{(1)}.$$



- The Multi-scale analysis (*continued*)

4. Substitute the expansions in LBE and rearrange according to $O(\epsilon)$ and $O(\epsilon^2)$

$$0 = \epsilon E_i^{(0)} + \epsilon^2 E_i^{(1)} + \mathcal{O}[\epsilon^3]$$

where:

$$E_i^{(0)} = \partial_t^{(1)} F_i^{(0)} + c_{i\gamma} \partial_{x_\gamma}^{(1)} F_i^{(0)} + \frac{\omega}{\Delta t} F_i^{(1)} - \frac{c_{i\gamma}}{6c^2} K_\gamma$$

$$E_i^{(1)} = \partial_t^{(1)} F_i^{(1)} + \partial_t^{(2)} F_i^{(0)} + c_{i\gamma} \partial_{x_\gamma}^{(1)} F_i^{(1)} + \frac{\Delta t}{2} \partial_t^{(1)} \partial_t^{(1)} F_i^{(0)} + \dots$$

5. Take lattice moments of E^0 and E^1 and assume $\mathcal{O}(j^2) \approx 0$ for $Ma \ll 1$

$$\sum_i E_i^{(0)}$$

$$\sum_i c_{i\alpha} E_i^{(0)}$$

$$\sum_i E_i^{(1)}$$

$$\sum_i c_{i\alpha} E_i^{(1)}$$

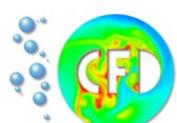
6. Sum up terms of orders ϵ and ϵ^2 and assume $\rho = \text{const.}$ (*incompressibility*)

Continuity

$$\nabla \cdot \mathbf{u} = 0$$

Momentum
conservation

$$\partial_t \mathbf{u} + (\mathbf{u} \nabla) \mathbf{u} = -\frac{1}{\rho} \nabla p + \nu \nabla^2 \mathbf{u} + \mathbf{K}$$

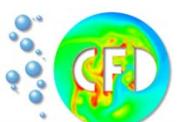


■ Some concluding remarks!!

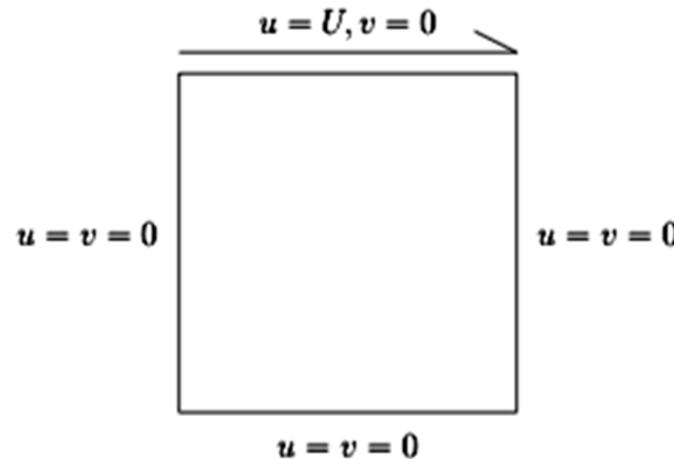
- ▶ Essential *by-products* of the multi-scale analysis

$$\frac{K_B T}{m} = \frac{1}{3}, \quad p = \frac{1}{3} \rho, \quad \nu = \frac{1}{3} (\tau - 0.5)$$

- ▶ *No non-linearity* to be worried about
- ▶ LBM is *2nd order in space* and *1st order in time*.
- ▶ LBM is *time marching* even for steady problems!
- ▶ Explicit time stepping means *small time steps* (CFL=1)
- ▶ Limited to small *Kn* number ($\epsilon \ll 1$) and incompressible flows ($Ma \ll 1$).
- ▶ The computational mesh is limited to *cartesian structured* one.

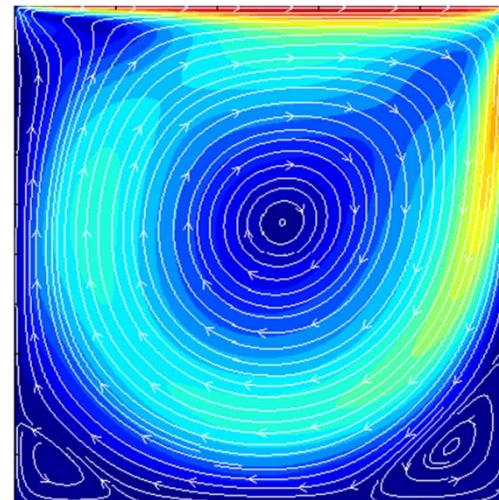


■ 2D Cavity Flow

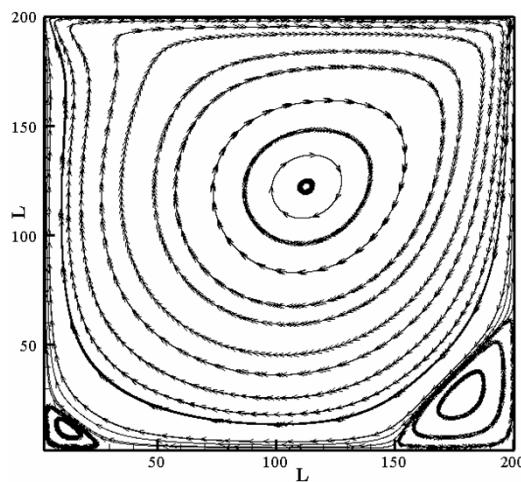


$$Re = \frac{UL}{v}$$

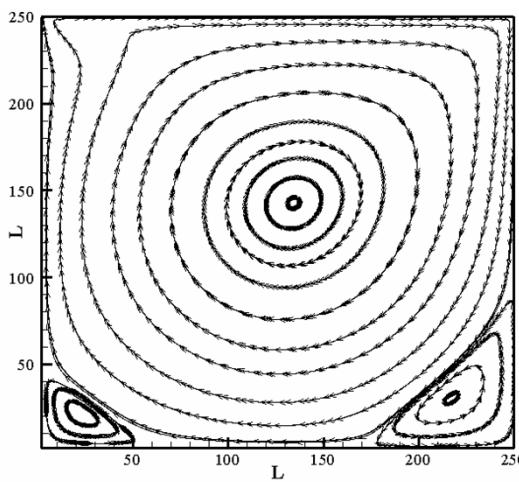
Re = 1000 , 512 x 512 Grid



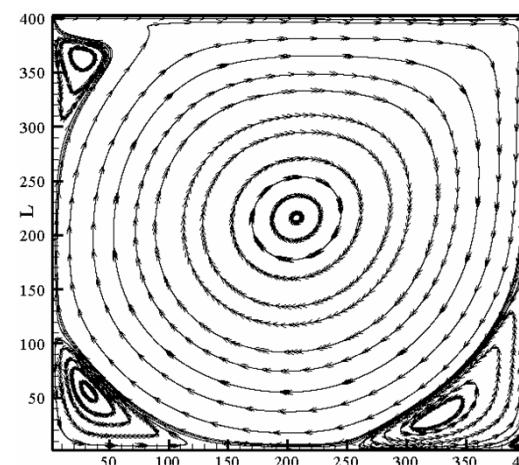
Velocity contour



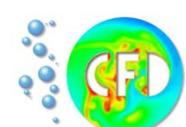
Re = 400



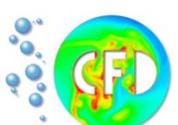
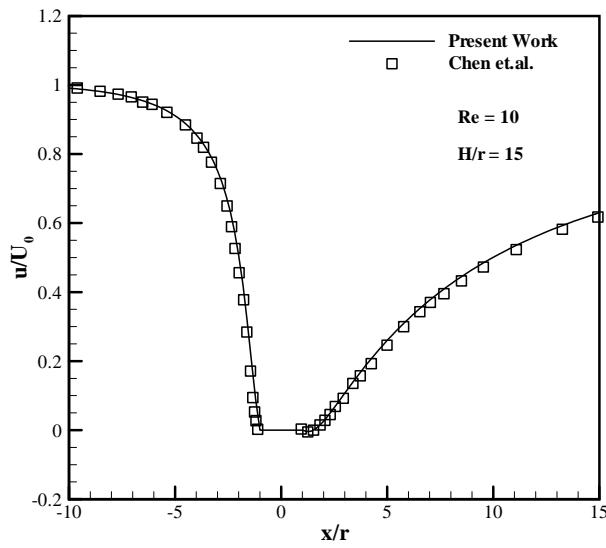
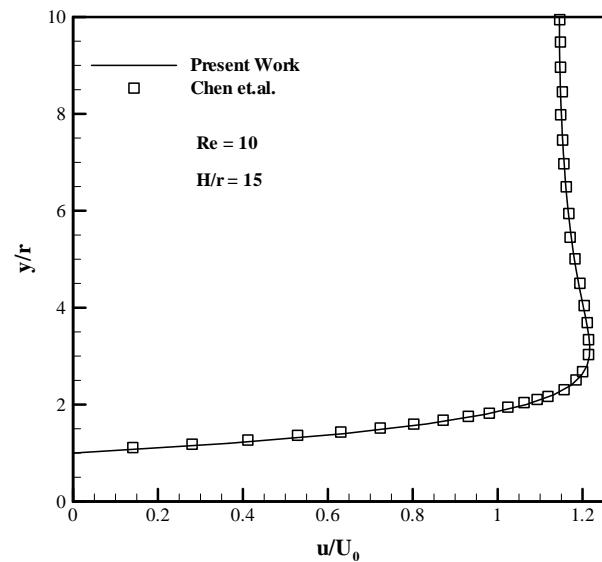
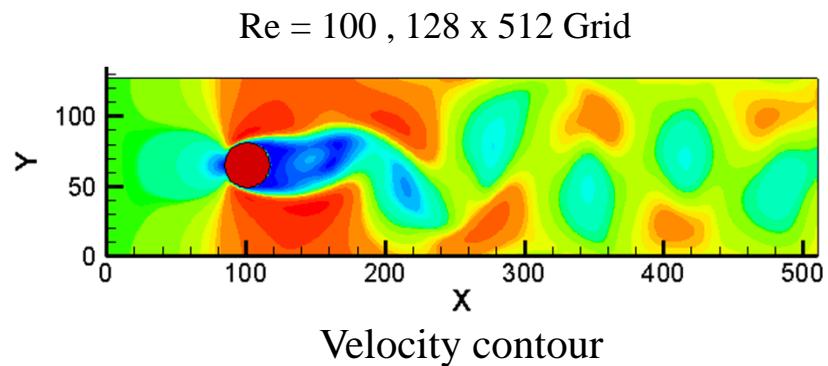
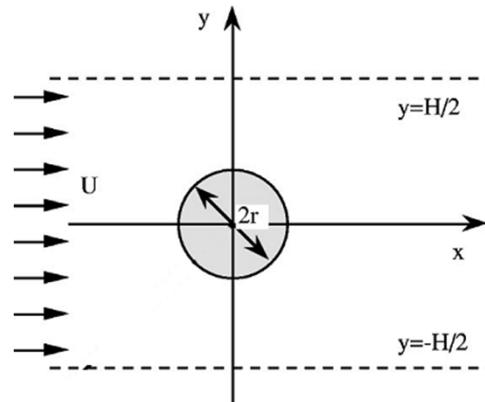
Re = 1000



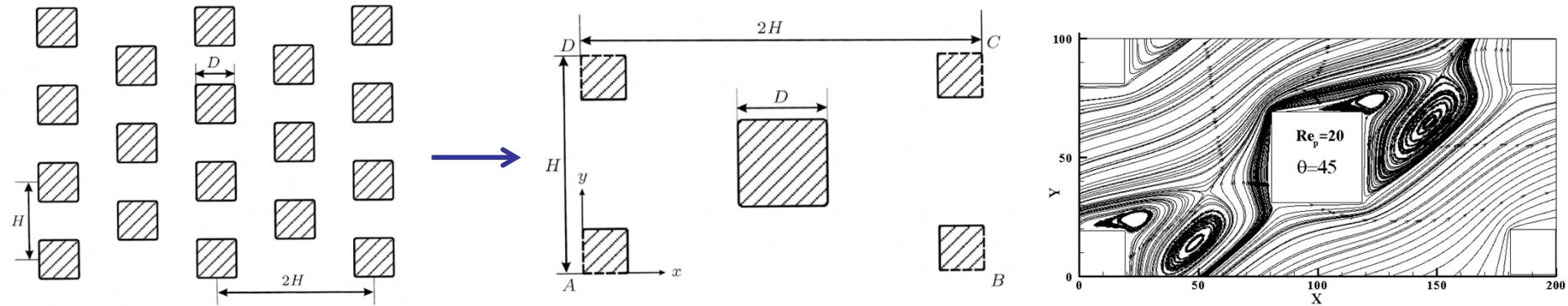
Re = 5000



■ 2D Flow around a column of cylinders

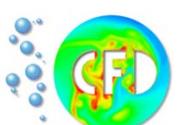
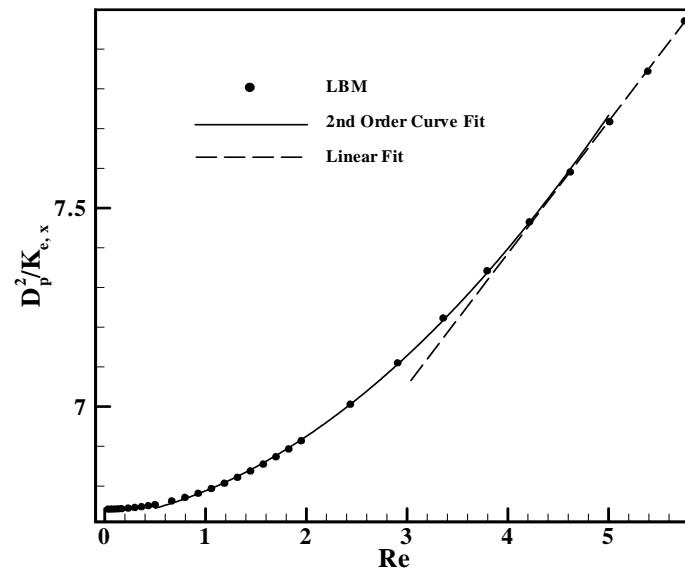


- 2D Flow in generic porous media

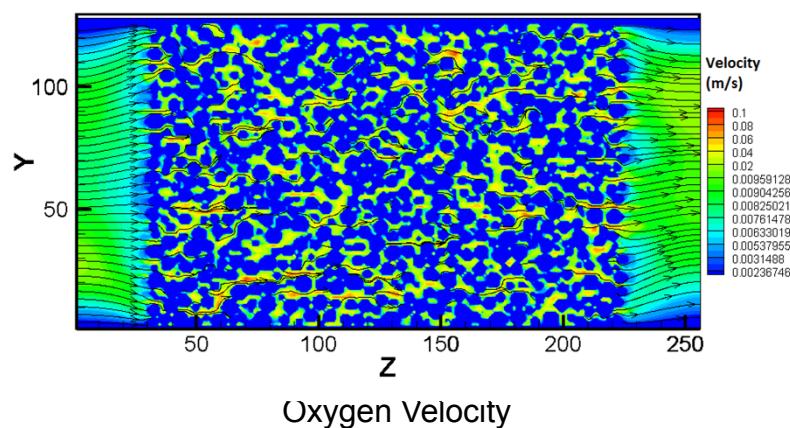
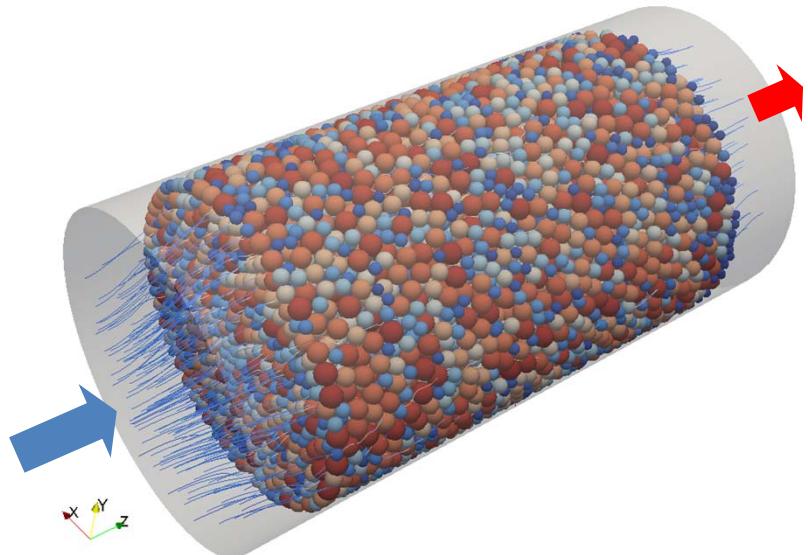


- *Darcy equation* for permeability in porous media:

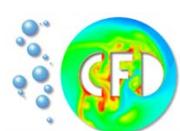
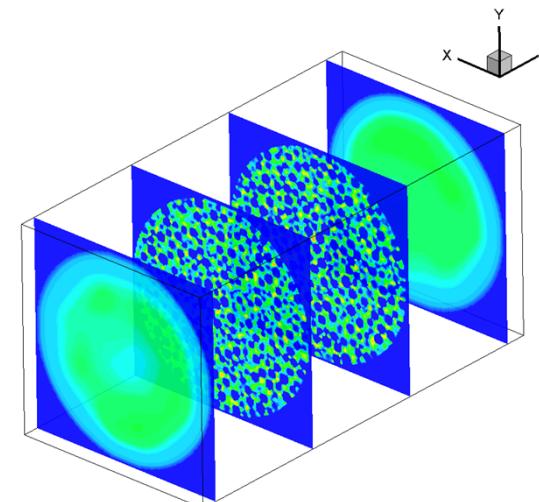
$$\frac{D_p^2}{K_e} = c_2 Re_p^2 + c'_1 Re_p + \frac{D_p^2}{K}$$



- 3D Multi-component flow of O_2 and N_2



- ▶ Air flow segregates into its ingredients
- ▶ Multicomponent, Entropic LB model
- ▶ *GPU parallel* implementation
- ▶ Direct application in production of *purified Nitrogen or Oxygen*



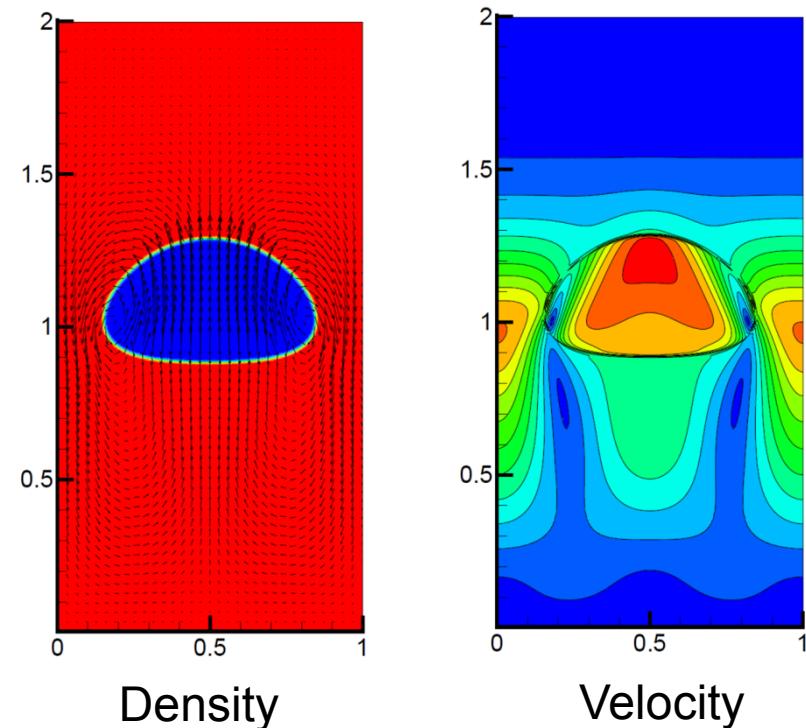
- Rising bubble at moderate density ratio

- ▶ *Shan-Cahn LB model* for inter-particle force at the interface

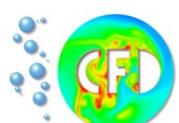
$$K(x, t) = -G \psi(x, t) \sum_i w_i \psi(x + c_i, t) c_i$$

$$\text{▶ } \frac{\rho_L}{\rho_G} = 10, \frac{\mu_L}{\mu_G} = 10$$

$$\text{▶ } Eo = \frac{4\rho_l g r_0^2}{\sigma} = 10, Re = \frac{\rho g (2r_0)^{3/2}}{\mu} = 35$$

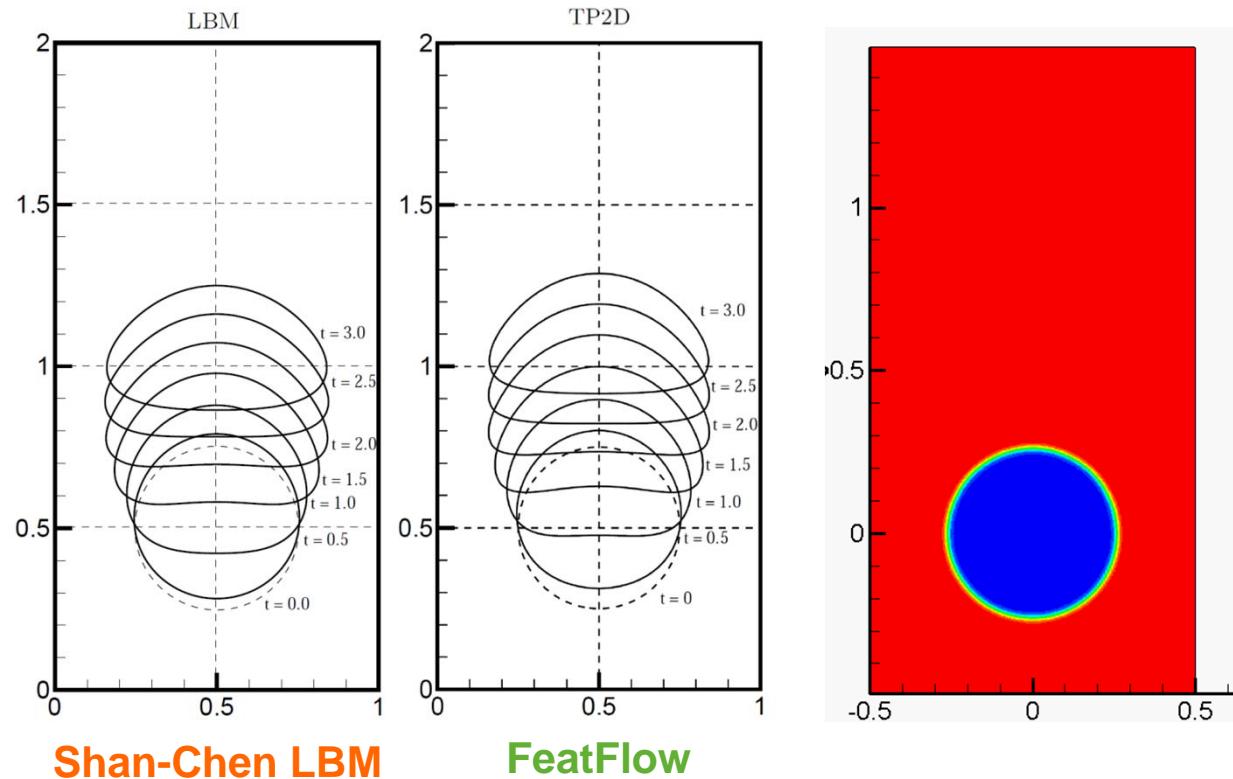


T=3, $\Delta x = 1/160$



- Rising bubble at moderate density ratio

- ▶ Validation against finite element *FeatFlow* solution



■ Rising bubble at high density ratio

- ▶ *Coupled LBM-LevelSet* model for surface tension force on interface

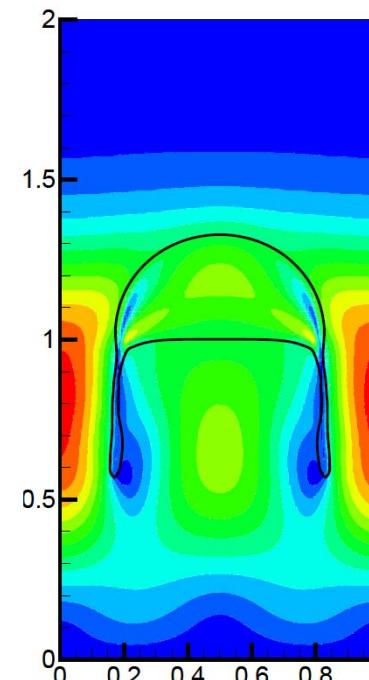
$$\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} + \frac{\nabla P}{\rho(\phi)} - \frac{\nabla \cdot (\mu(\phi)(\nabla \mathbf{u} + \nabla \mathbf{u}^T))}{\rho(\phi)} = -\frac{\sigma \kappa(\phi) \mathbf{n}(\phi) \delta_\varepsilon(\phi)}{\rho(\phi)}$$

+

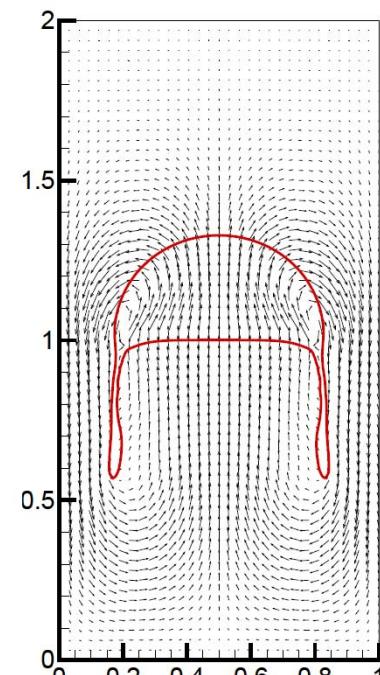
$$\partial_t \phi + \mathbf{u} \cdot \nabla \phi = 0 \quad \text{where} \quad \phi(\mathbf{x}) = 0 \quad \text{at} \quad X = \Gamma$$

$$▶ \frac{\rho_L}{\rho_G} = 1000, \frac{\mu_L}{\mu_G} = 100$$

$$▶ Eo = \frac{4\rho_L g r_0^2}{\sigma} = 125, Re = \frac{\rho g (2r_0)^{3/2}}{\mu} = 35$$

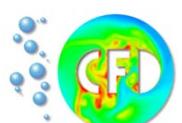


Velocity

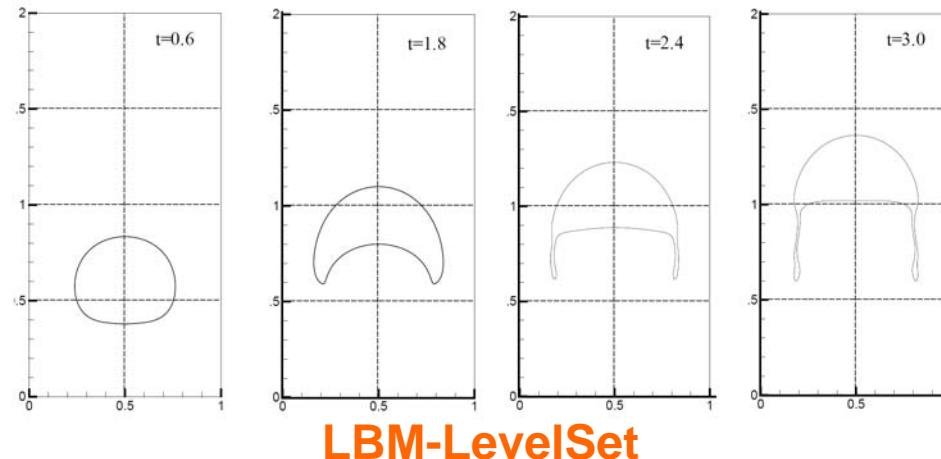


Velocity Vectors

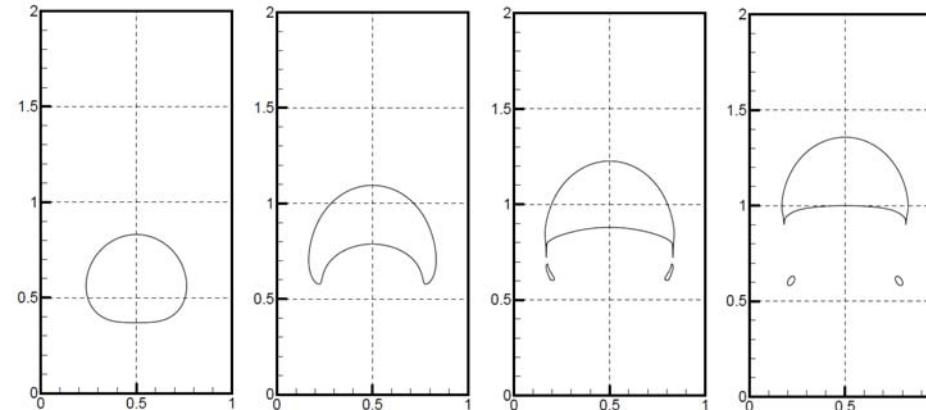
T=3, $\Delta x = 1/160$



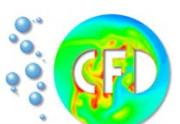
- Rising bubble at high density ratio



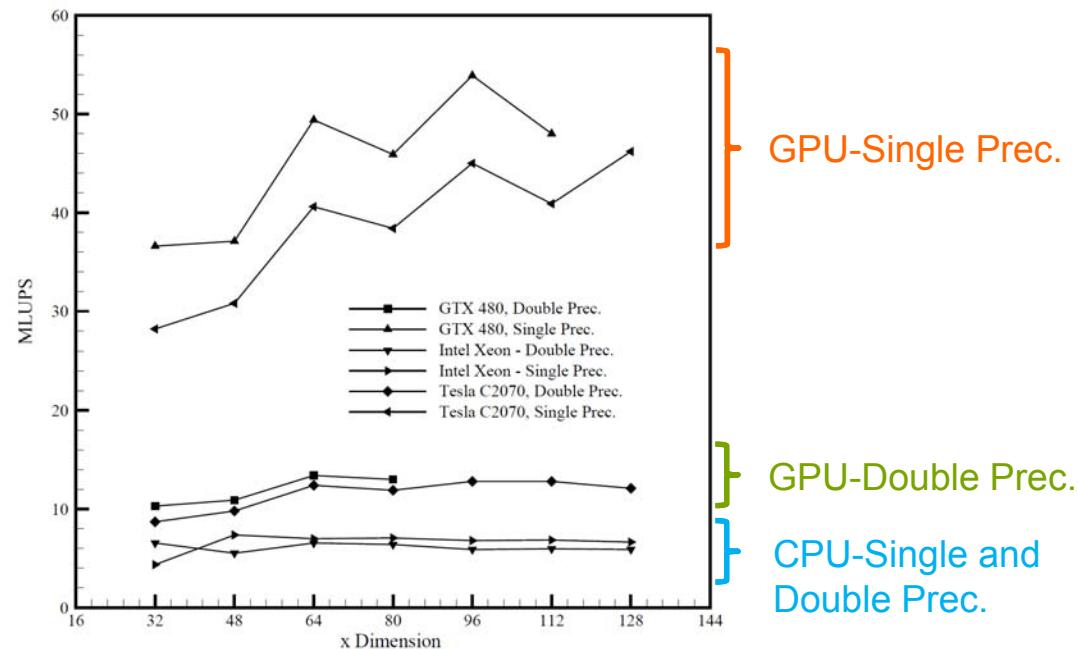
LBM-LevelSet



FeatFlow



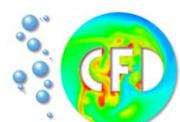
- ▶ *Node-level* independency of computations
- ▶ *Aligned* data access patterns
- ▶ A suitable candidate for *fine-grain parallelization*
- ▶ *GPU* implementations are in particular very promising



Weak-scaling performance for the 3D flow in packed bed



Tesla GPU



Thank You

