

MULTILEVEL PRESSURE SCHUR COMPLEMENT

methods for solving the

incompressible Navier–Stokes equations

The case of GLOBAL MPSC

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Demands for the numerical solution of:

Incompressible Navier–Stokes equations

$$\mathbf{u}_t - \nu \Delta \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} + \nabla p = \mathbf{f} \quad , \quad \nabla \cdot \mathbf{u} = 0$$

+ boundary and initial values

- stable and accurate discretizations in space and time
- adaptive (error) control strategies
- nonlinear solvers or linearization techniques in time
- solvers for Stokes/Oseen–like equations
- linear solvers for scalar subproblems

Robustness

Efficiency



Implementation/Hardware (???)

Solution of discrete Nav.-St. problems:

- Nonlinearity → ‘OK’ (???)
 - Saddle point character (!!!)
- ‘large’ degrees of freedom ($10^6 - 10^8$)
- variable time scales
- complex geometries and locally **anisotropic** meshes
- changing ‘Reynolds numbers’ in time

Multilevel Pressure Schur Complement

1. Separation of discretization from solver (!) aspects
2. Classification and generalization of algorithms



Understanding of Advantages/Disadvantages

3. Improvements and rigorous (!!!) multigrid embedding



‘Local’ and ‘Global’ MPSC techniques

Example from Numerical Linear Algebra:

1.) Numerical solution of **Poisson/Heat** equation



Discretization in space and time

2.) Solution of discretized problems with **basic iterations**



Jacobi, Gauß-Seidel, SOR, ILU, etc.

3.) **Characterization** of iterative schemes



- Poisson problem ???
- $k \rightarrow 0$???
- complex spatial meshes/variable time steps ???
- (nonlinearity ???)

4.) Acceleration as **preconditioner** in Krylov-methods

5.) Acceleration as **smoother** in **multigrid** (!)

‘Pressure Schur Complement’ formulation:

$$\begin{bmatrix} S & kB \\ B^T & 0 \end{bmatrix} \begin{bmatrix} \mathbf{u} \\ p \end{bmatrix} = \begin{bmatrix} \mathbf{g} \\ 0 \end{bmatrix}$$



$$B^T S^{-1} B p = \frac{1}{k} B^T S^{-1} \mathbf{g} \quad , \quad \mathbf{u} = S^{-1}(\mathbf{g} - kBp)$$

Preconditioned Richardson schemes for scalar PSC:

$$\begin{aligned} p^l &= p^{l-1} - C^{-1}(Ap^{l-1} - b) \\ &= p^{l-1} - C^{-1}\left(B^T S^{-1} B p^{l-1} - \frac{1}{k} B^T S^{-1} \mathbf{g}\right) \end{aligned}$$



Choice of PSC preconditioner C^{-1} :

- $C^{-1} = \sum \alpha_i \tilde{C}_i^{-1}$
- $S := \alpha M + \theta_1 \nu k L + \theta_2 k N(\tilde{\mathbf{U}})$



Smoother in **Multigrid** for $B^T S^{-1} B$

‘Global’ MPSC schemes

‘Construct **globally** defined preconditioners for the partial operators by **discrete** and **continuous** arguments and use them in an **additive** way’

- Generalization of ‘**Projection methods**’, ‘**Pressure Correction**’, ‘**Fractional Step**’ und ‘**Uzawa**’ schemes
- New interpretation of ‘classical’ schemes (**Chorin, Van Kan, Gresho–2**) as special ‘**incomplete solvers**’ (!!!)
- More ‘efficiency’ through **Multigrid** (MPSC)

‘Local’ MPSC schemes

‘Solve ”**exactly**” on ”patches” and perform an outer **Block–Gauß-Seidel/Jacobi** iteration’

- Generalization of **Block-Jacobi/Gauß-Seidel** methods for saddle point problems
- Modification of ‘classical’ schemes (‘**Vanka**’)
- ‘Stabilization’ via **adaptive ‘Patching’**

Global PSC Preconditioner "C⁻¹" ???

Mass

Laplacian

Convection

$$\begin{aligned} B^T S^{-1} B &= B^T [M + \theta \nu k L + \theta k N]^{-1} B \\ &\sim B^T M^{-1} B + \frac{1}{\theta \nu k} B^T L^{-1} B + \frac{1}{\theta k} B^T N^{-1} B \end{aligned}$$

$$\begin{aligned} [B^T S^{-1} B]^{-1} &\sim [B^T M^{-1} B + \frac{1}{\theta \nu k} B^T L^{-1} B + \frac{1}{\theta k} B^T N^{-1} B]^{-1} \\ &\sim (B^T M^{-1} B)^{-1} + \theta \nu k (B^T L^{-1} B)^{-1} + \theta k (B^T N^{-1} B)^{-1} \end{aligned}$$

Reaction

Diffusion

Convection

Reactive Preconditioner:

- **explicit** calculation of $P := B^T M_l^{-1} B$
- **P "exact"** discrete PSC preconditioner for $k \rightarrow 0$
- nonconforming \tilde{Q}_1/Q_0 : **5 (2D)/7 (3D) stencil !!!**

OPTIMAL: "exact" for $k \rightarrow 0$, "minimal" numerical complexity

Diffusive Preconditioner:

- explicit calculation of $B^T L^{-1} B$ impossible (L^{-1} full !!!)
- **However:** $\nabla \cdot \Delta^{-1} \nabla \sim I \implies B^T L^{-1} B \sim M_p$

"OPTIMAL": spectrally optimal for discrete **Stokes** problems
 \implies (Modified) **Uzawa** scheme !!!

Convective Preconditioner: (???)

- discrete construction \longrightarrow **ILU ???**
- continuous construction \longrightarrow $\nabla \cdot (\beta \cdot \nabla)^{-1} \nabla \sim ???$

Complete "Additive" PSC Preconditioner:

$$\alpha_R P^{-1} + \alpha_D M_p^{-1}$$

with: $\alpha_R = 1$ (or 0), $\alpha_D = \theta \nu k$ + Damping if necessary

Complete PSC Basic Iteration:

$$p^l = p^{l-1} - [\alpha_R P^{-1} + \alpha_D M_p^{-1}] \left(B^T S^{-1} B p^{l-1} - \frac{1}{k} B^T S^{-1} \mathbf{g} \right)$$

Realization of 1 complete PSC Step:

$$S \tilde{\mathbf{u}} = \mathbf{g} - k B p^{l-1} \quad (\text{with } p^{l-1} \text{ given})$$

$$f_p := \frac{1}{k} B^T \tilde{\mathbf{u}} \quad \left[= \frac{1}{k} B^T S^{-1} \mathbf{g} - B^T S^{-1} B p^{l-1} = \text{Residual } (p^{l-1}) \right]$$

$$P q = f_p \quad (\sim \text{discrete "Pressure-Poisson" problem})$$

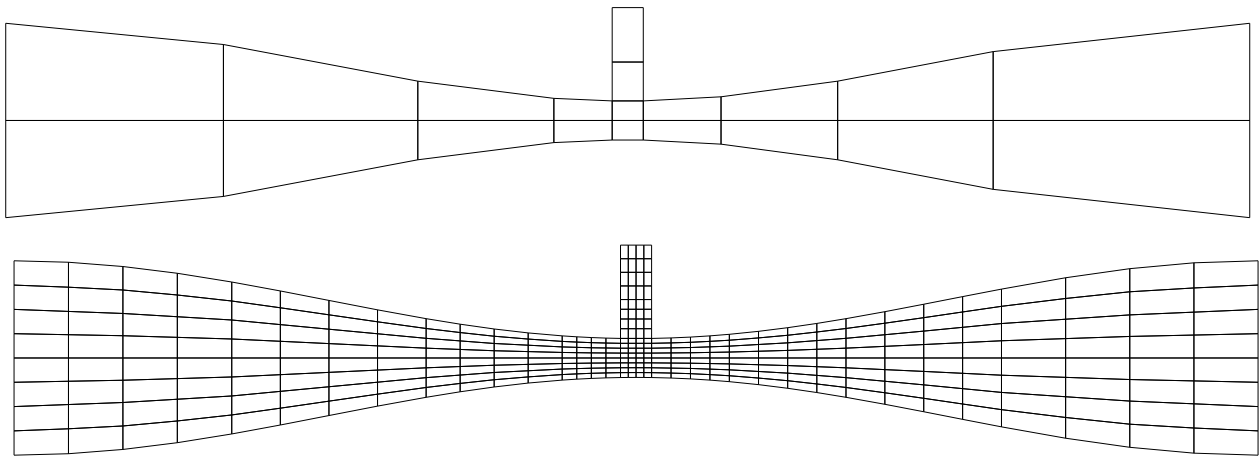
$$p^l = p^{l-1} + \alpha_R q + \alpha_D M_p^{-1} f_p$$

MPSC Multigrid for $A := B^T S^{-1} B$:

(Standard) Multigrid with **PSC smoother**

Additional "internal" multigrid for S^{-1} and P^{-1} !!!

Test: ‘Flow through a Venturi Pipe’



level	vertices	elements	midpoints	total unknowns
1	34	20	53	126
3	373	320	692	1,704
6	20,897	20,480	41,376	103,232

Test configuration:

- $\nu = 10^{-3}$, resulting Reynolds number $Re \approx 5,000$
- (*adaptive*) upwind discretization of the convective terms
- Fractional-step- θ -scheme as time discretization
- **adaptive time step control** for velocity (global, l_2) and **flux** (through upper device !!!)

Examined Navier-Stokes solvers:

- **n-Gal** nonlinear full Galerkin approach with nonlinear solver in each time step and global MPSC steps for each Oseen problem
- **l-Gal** global MPSC with 2nd order linearization
- **c-Gal** global MPSC with $\mathbf{u}^n \cdot \nabla \mathbf{u}^{n+1}$ linearization

”fully coupled in \mathbf{u} and p ”

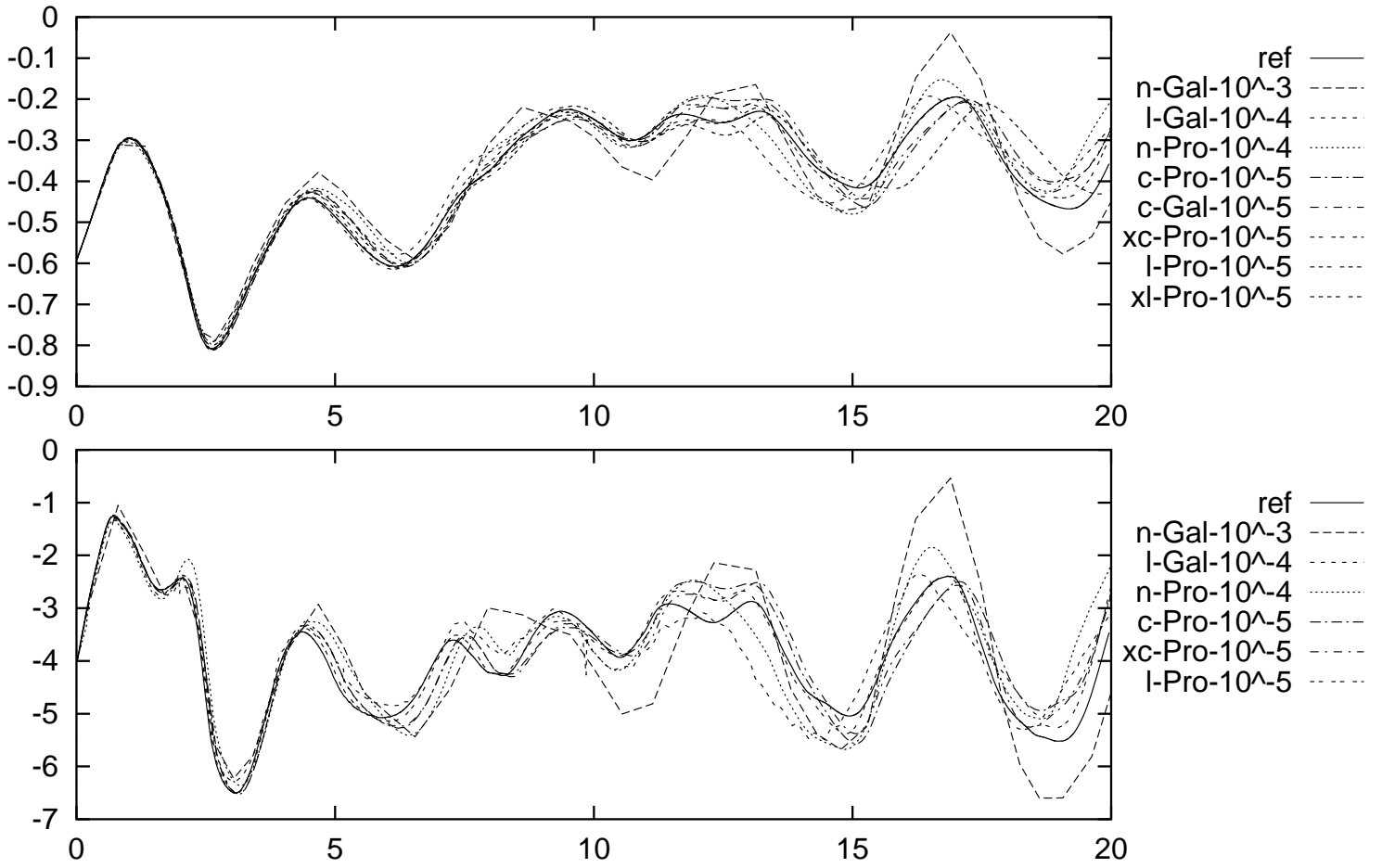
- **n-Pro** nonlinear projection with global PSC (‘Van Kan’)
- **l-Pro** semi-implicit projection with linear extrapolation
- **c-Pro** semi-implicit projection with constant treatment

”semi-implicit decoupled approach”

- **xl-Pro** semi-explicit projection with linear extrapolation
- **xc-Pro** semi-explicit projection with constant treatment

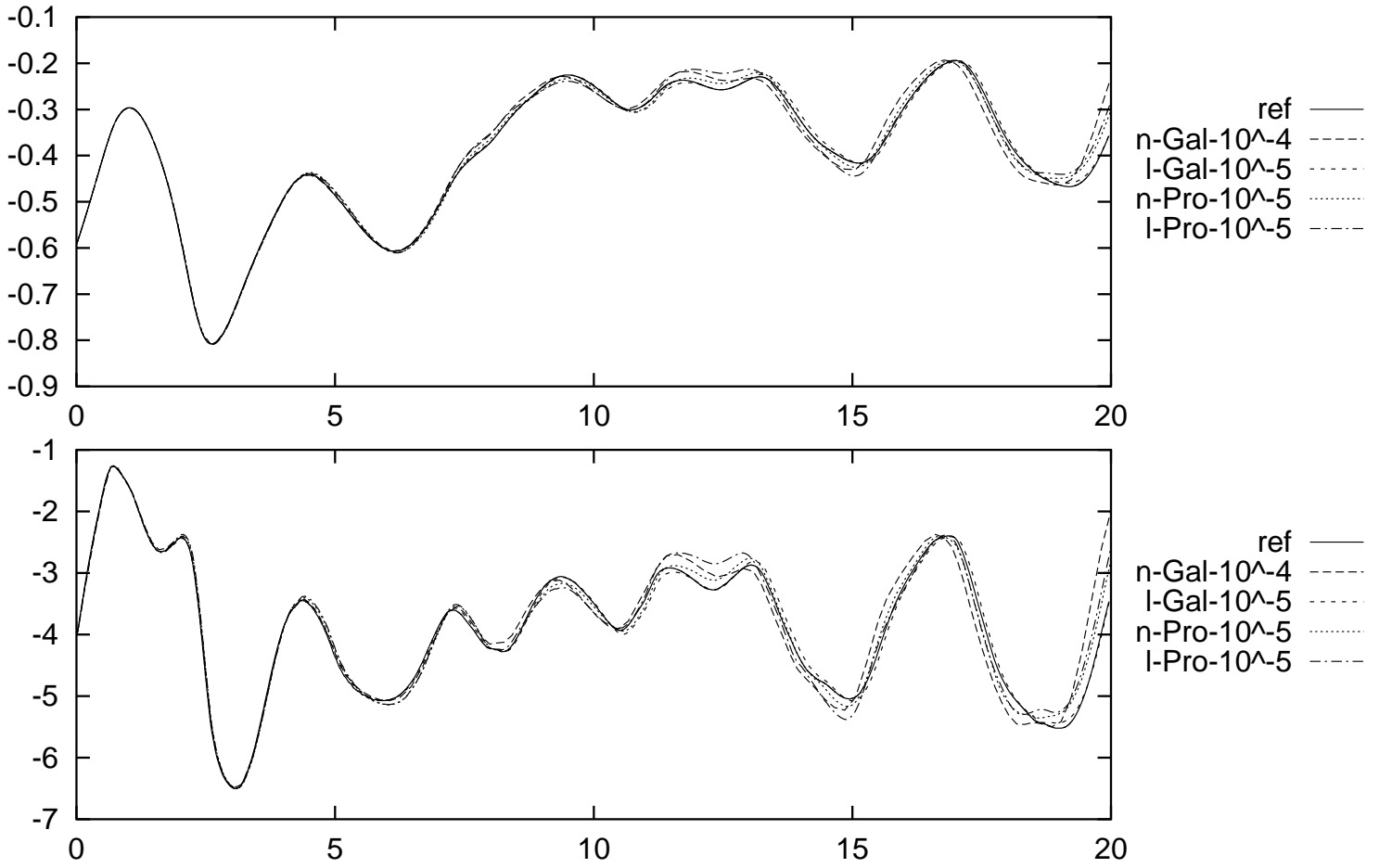
”semi-explicit approach with SPD’s only”

Results: 'OK' Ratings



	Meth.	#NT	Flux value			Pressure value		
			l_2	mean	peak	l_2	mean	peak
OK	n-Gal	38	15%	1%	3%	19%	1%	1%
	l-Gal	222	11%	2%	1%	13%	0%	3%
	n-Pro	263	11%	2%	1%	14%	3%	2%
	l-Pro	649	4%	0%	0%	5%	0%	0%
	c-Gal	768	6%	1%	0%	8%	1%	0%
	c-Pro	769	8%	2%	0%	10%	2%	0%
	xc-Pro	2730	7%	1%	1%	8%	0%	4%
	xl-Pro	6941	11%	0%	2%	14%	0%	22%

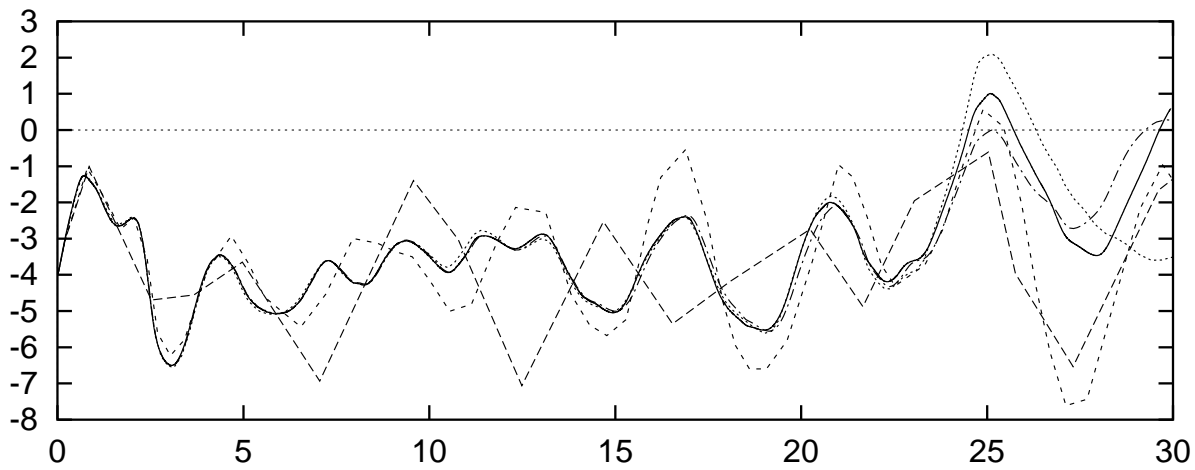
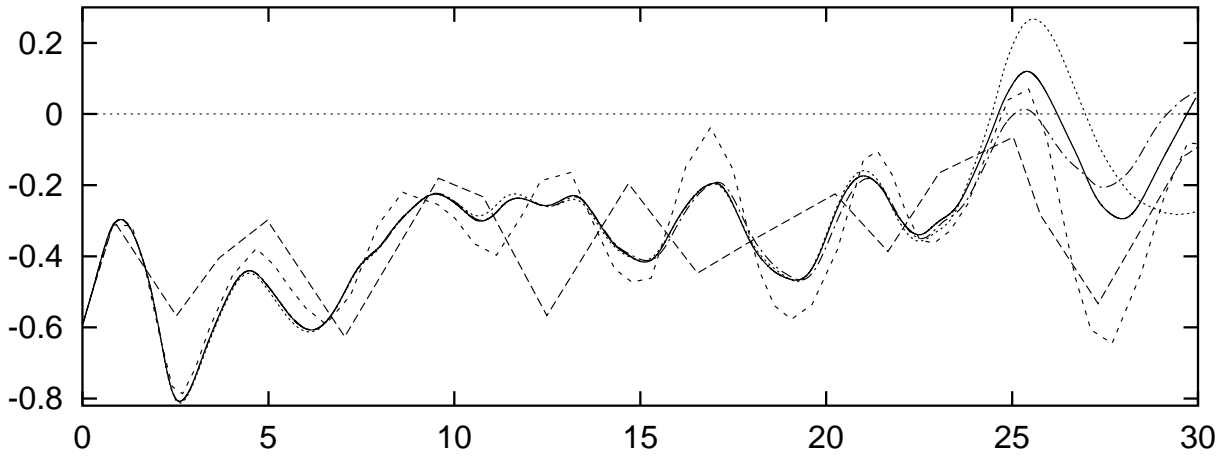
Results: 'PERF' Ratings



	Meth.	#NT	Flux value			Pressure value		
			l_2	mean	peak	l_2	mean	peak
P	n-Gal	117	5%	1%	0%	7%	1%	0%
E	l-Gal	508	1%	0%	0%	1%	0%	0%
R	n-Pro	630	3%	0%	0%	4%	0%	0%
F	l-Pro	649	4%	0%	0%	5%	0%	0%

Results: Comparison of n-Gal

Different tolerances for adaptive control



Conclusions:

- **”fully coupled in u and p”**

⇒ **Several PSC** projection steps in time step

⇒ Accelerated via **multigrid**

- **”fully nonlinear treatment”**

⇒ **Quasi-Newton** fixed point iteration

⇒ 2nd order linearization for **anisotropic meshes ???**

- **”Adaptive mixing of GLOBAL + LOCAL MPSC”**

⇒ LOCAL MPSC: **”optimal”** for **low – medium Re**

⇒ GLOBAL MPSC: **”optimal”** for **medium – high Re**



*Combination of higher accuracy of
Galerkin-type methods with high speed
of **Projection-type solvers** is possible !!!*