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Numerical Benchmarking of Fluid-Structure Interaction between elastic object and laminar incompressible flow

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Key question

- ***Accurate and robust description of the interaction mechanisms w.r.t. highly dynamical and nonlinear behaviour and significant geometry changes?***
- That includes:
 - Quality of different **discretization** techniques (FEM, FV, FD, LBM, resp., beam, shell, volume elements) for FSI?
 - Robustness and numerical efficiency of the integrated **solver** components?
 - **Coupling** mechanisms?

1st step: *Identification of appropriate **FSI** setting for numerical benchmarking*

2nd step: ***FSI** benchmark setting due to experimental studies*

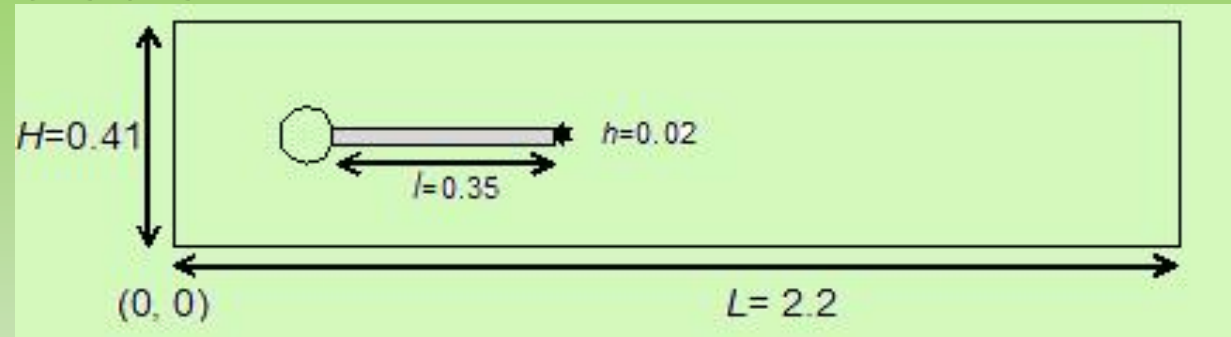
3rd step: *Extension to **FSI-Optimisation** benchmark*

Requirements for numerical FSI benchmarking

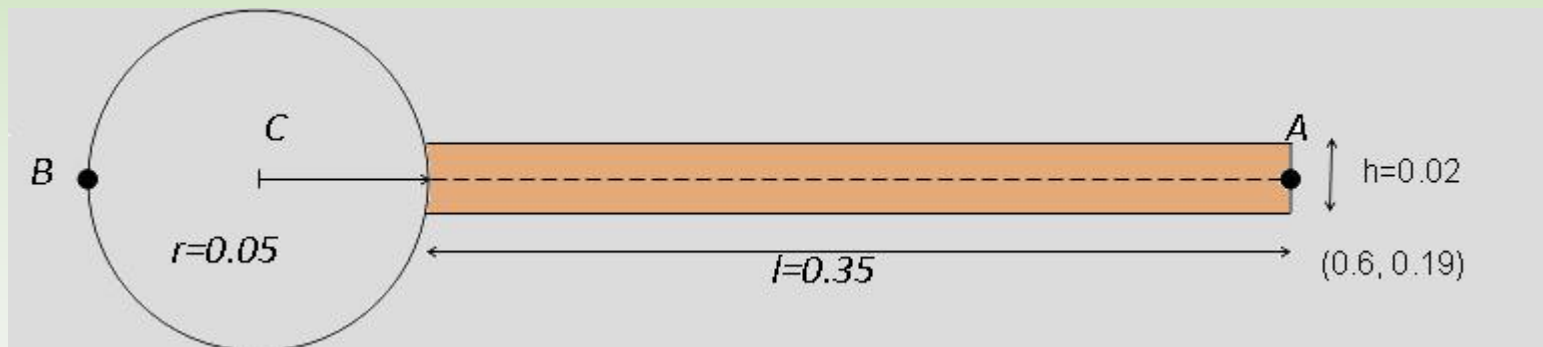
- Mainly based on the successful DFG *flow around cylinder* benchmark
- *Realistic materials*
 - **Incompressible Newtonian fluid**, laminar flow regime
 - Elastic solid, large deformations
- *Comparative evaluation*
 - Setup with periodical oscillations
 - Non-graphically based quantities
- *Computable configurations*
 - Laminar flow
 - Reasonable aspect ratios
 - Simple geometry (2D)

Computational domain

➤ Domain dimensions

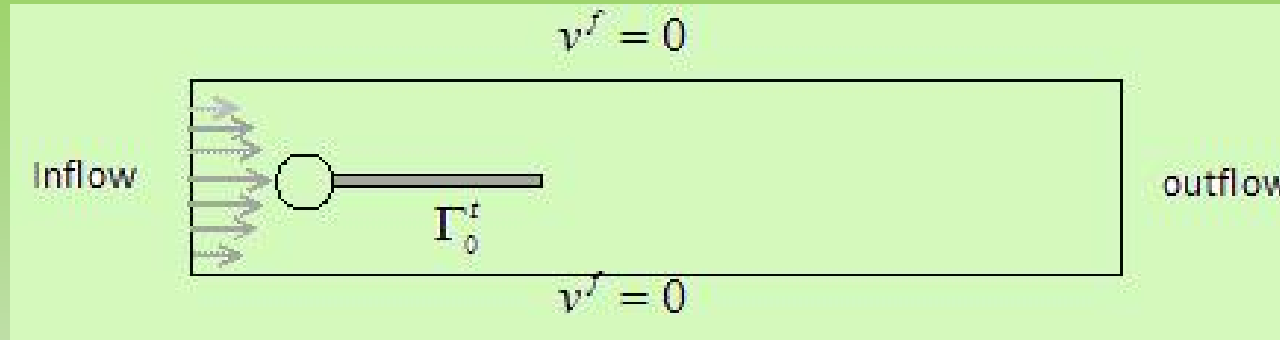


➤ Detail of the submerged structure



$$A(t=0) = (0.6, 0.2), \quad B = (0.15, 0.2), \quad C = (0.2, 0.2)$$

Boundary and initial conditions



- Inflow** Parabolic velocity profile is prescribed at the left end of the channel
- Outflow** Condition can be chosen by the user, assuming zero reference pressure (*stress free or do nothing*)
- otherwise** The *no-slip* condition is prescribed for the fluid on the other boundary parts. i.e. top and bottom wall and cylinder
- Initial** Zero velocity in the fluid and no deformation of the structure + smooth increase of the inflow profile

Fluid and structure properties

- **Incompressible** fluid with density ρ^f

$$\begin{aligned}\rho^f \frac{\partial \mathbf{v}^f}{\partial t} + \rho^f (\nabla \mathbf{v}^f) \mathbf{v}^f &= \operatorname{div} \boldsymbol{\sigma}^f \\ \operatorname{div} \mathbf{v}^f &= 0 \\ \boldsymbol{\sigma}^f &= -p^f \mathbf{I} + \rho^f \nu^f (\nabla \mathbf{v}^f + \nabla \mathbf{v}^{f\top})\end{aligned}\quad \text{in } \Omega_t^f$$

- Elastic material with density ρ^s , $\mathbf{F} = \mathbf{I} + \nabla \mathbf{u}^s$, $J = \det \mathbf{F}$: St. Venant – Kirchhoff material

$$\begin{aligned}\rho^s \frac{\partial^2 \mathbf{u}^s}{\partial t^2} &= \operatorname{div}(\boldsymbol{\sigma}^s \mathbf{F}^{-\top}) \\ \boldsymbol{\sigma}^s &= \frac{1}{J} \mathbf{F} (\lambda^s (\operatorname{tr} \mathbf{E}) \mathbf{I} + 2\mu^s \mathbf{E}) \mathbf{F}^\top \\ \mathbf{E} &= \frac{1}{2} (\mathbf{F}^\top \mathbf{F} - \mathbf{I})\end{aligned}\quad \text{in } \Omega^s$$

Suggested material parameters

solid

ρ^s density

ν^s Poisson ratio

μ^s shear modulus

fluid

ρ^f density

ν^f kinematic viscosity

Parameter	polybutadiene & glycerine	polypropylene & glycerine
$\rho^s [10^3 \text{ kg/m}^3]$	0.91	1.1
ν^s	0.50	0.42
$\mu^s [10^6 \text{ kg/ms}^2]$	0.53	317
$\rho^f [10^3 \text{ kg/m}^3]$	1.26	1.26
$\nu^f [10^{-3} \text{ m}^2 / \text{s}]$	1.13	1.13

Parameter	FSI1	FSI2	FSI3
$\rho^s [10^3 \text{ kg/m}^3]$	1	1	1
ν^s	0.4	0.4	0.4
$\mu^s [10^6 \text{ kg/ms}^2]$	0.5	0.5	2.0
$\rho^f [10^3 \text{ kg/m}^3]$	1	1	1
$\nu^f [10^{-3} \text{ m}^2 / \text{s}]$	1	1	1
$\bar{U} [\text{m/s}]$	0.2	1	2

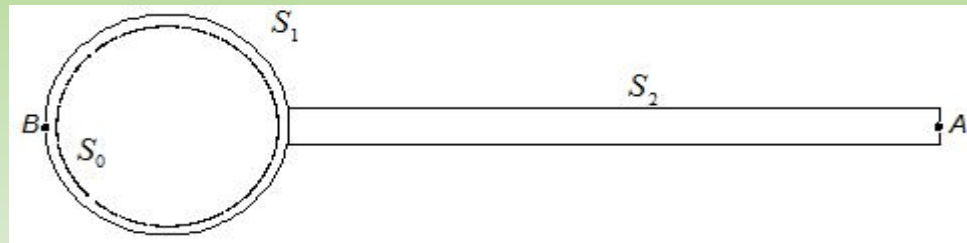
Parameter	FSI1	FSI2	FSI3
$\beta = \frac{\rho^s}{\rho^f}$	1	1	1
ν^s	0.4	0.4	0.4
$Ae = \frac{E^s}{\rho^f \bar{U}^2}$	3.5×10^4	1.4×10^3	1.4×10^3
$Re = \frac{\bar{U} d}{\nu^f}$	20	100	200
$\bar{U} [\text{m/s}]$	0.2	1	2

Quantities of interest

- The position $A(t) = (x(t), y(t))$ of the end of the structure \item pressure difference between the points $A(t)$ and B

$$\Delta p^{AB}(t) = p^B(t) - p^{A(t)}(t)$$

- Forces exerted by the fluid on the *whole body*, i.e. lift and drag forces acting on the cylinder and the structure together



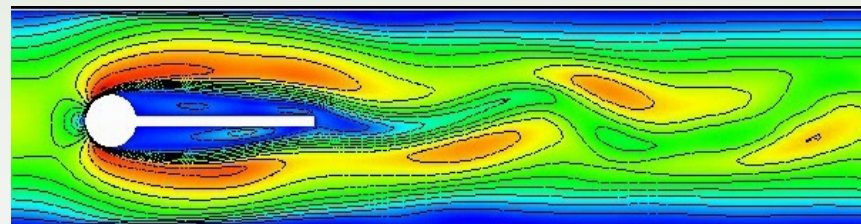
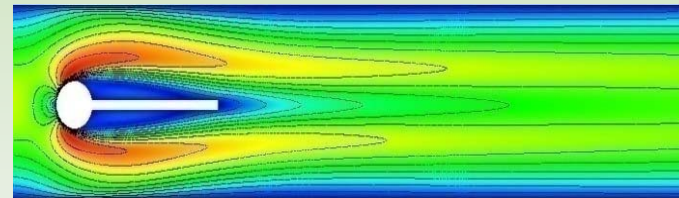
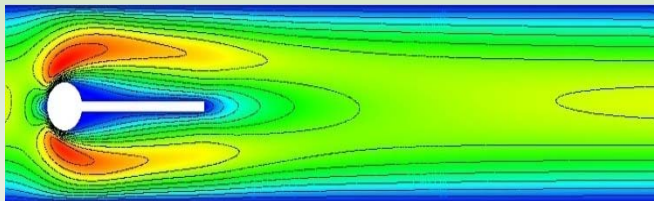
$$(F_D, F_L) = \int_S \sigma n dS = \int_{S_1} \sigma^f n dS + \int_{S_2} \sigma^{f|S} n dS = \int_{S_0} \sigma n dS$$

- Frequency and maximum amplitude
- Compare results for *one* full period and 3 different levels of spatial discretization h and 3 time step sizes Δt

1.Step: CFD tests for validation

	CFD1	CFD2	CFD3
$\rho^f [10^3 \text{ kg/m}^3]$	1	1	1
$\nu^f [10^{-3} \text{ m}^2/\text{s}]$	1	1	1
$\bar{U} [\text{m/s}]$	0.2	1	2
$\text{Re} = \frac{\bar{U}d}{\nu^f}$	20	100	200
$\bar{U} [\text{m/s}]$	0.2	1	2

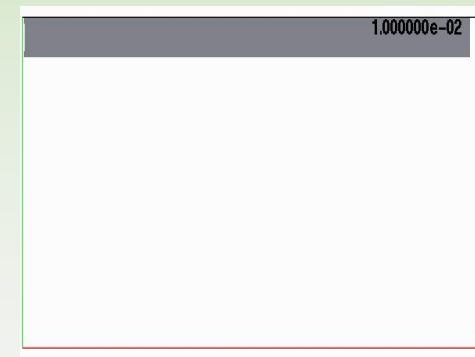
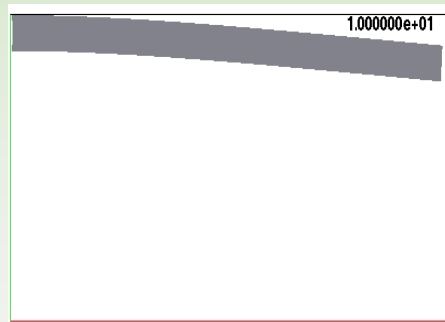
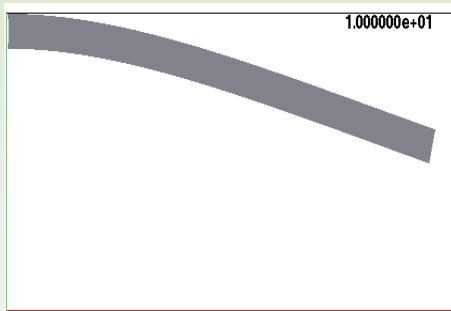
Test	Drag	Lift
CFD1	14.29	1.119
CFD2	136.7	10.53
CFD3	439.4 ± 5.618 [4.395]	-11.89 ± 437.8 [4.395]



2.Step: CSM tests for validation

	CSM1	CSM2	CSM3
$\rho^s [10^3 \text{ kg/m}^3]$	1	1	1
ν^s	0.4	0.4	0.4
$\mu^s [10^6 \text{ kg/ms}^2]$	0.5	2.0	0.5
$g [\text{m/s}^2]$	2	2	2
$\beta = \frac{\rho^s}{\rho^f}$	1	1	1
ν^s	0.4	0.4	0.4
$E^s [10^6 \text{ kg/ms}^2]$	1.4	5.6	1.4
$g [\text{m/s}^2]$	2	2	2

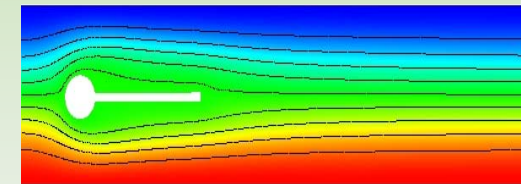
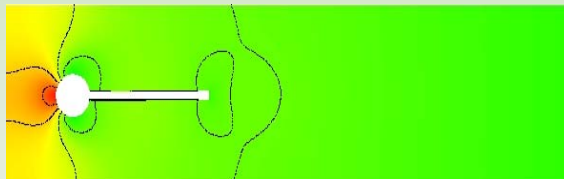
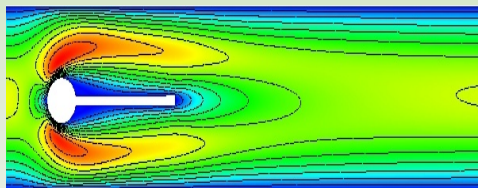
test	ux of A [$\times 10^{-3}$ m]	uy of A [$\times 10^{-3}$ m]
CSM1	− 7.187	− 66.10
CSM2	− 0.4690	− 16.97
CSM3	-14.305 ± 14.305 [1.0995]	-63.607 ± 65.160 [1.0995]



FSI1: steady, small deformations

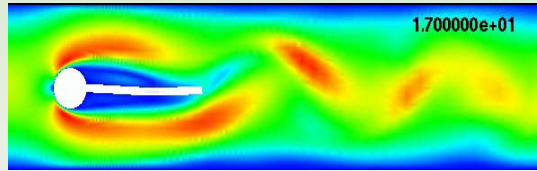
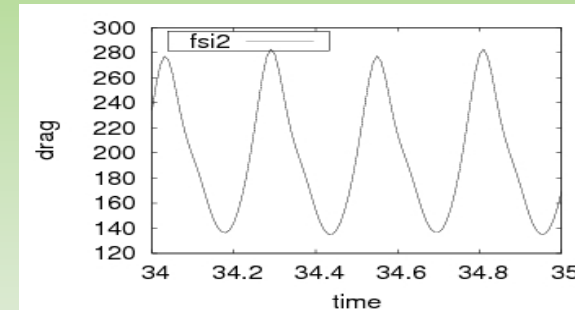
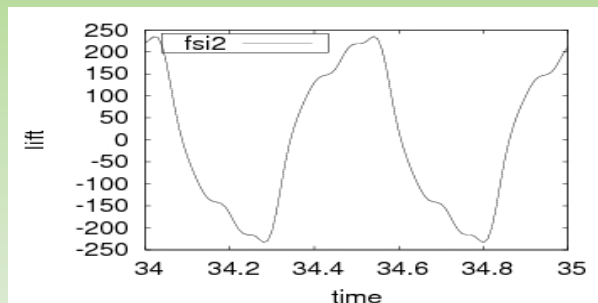
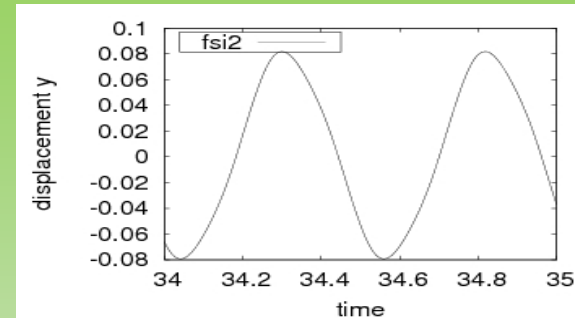
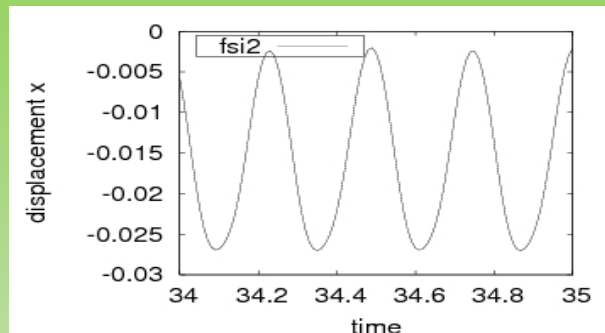
parameter	FSI1	FSI2	FSI3
$\rho^s [10^3 \text{ kg/m}^3]$	1	1	1
ν^s	0.4	0.4	0.4
$\mu^s [10^6 \text{ kg/ms}^2]$	0.5	0.5	2.0
$\rho^s [10^3 \text{ kg/m}^3]$	1	1	1
$\nu^s [10^{-3} \text{ m}^2/\text{s}]$	1	1	1
$\bar{U} [\text{m/s}]$	0.2	1	2

parameter	FSI1	FSI2	FSI3
$\beta = \frac{\rho^s}{\rho^f}$	1	1	1
ν^s	0.4	0.4	0.4
$Ae = \frac{E^s}{\rho^f \bar{U}^2}$	3.5×10^4	1.4×10^3	1.4×10^3
$Re = \frac{\bar{U} d}{\nu^f}$	20	100	200
$\bar{U} [\text{m/s}]$	0.2	1	2



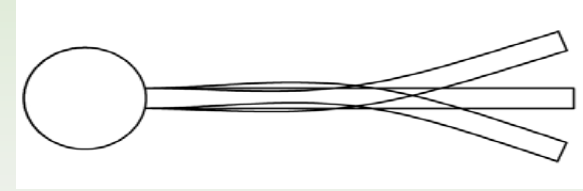
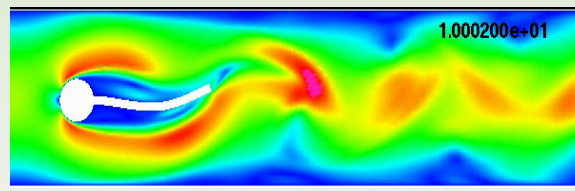
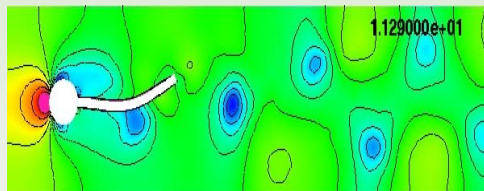
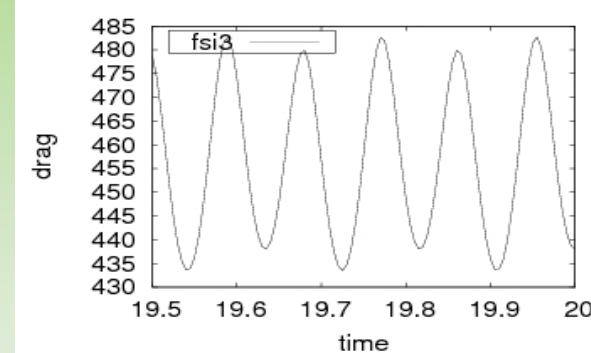
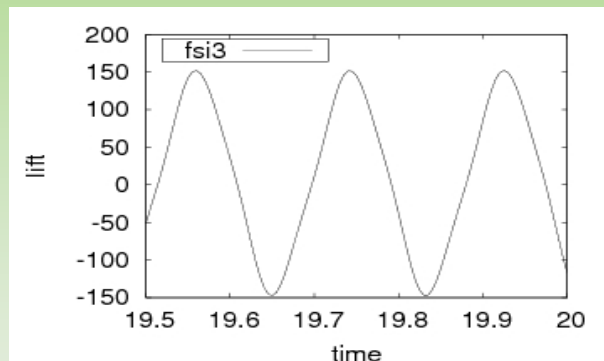
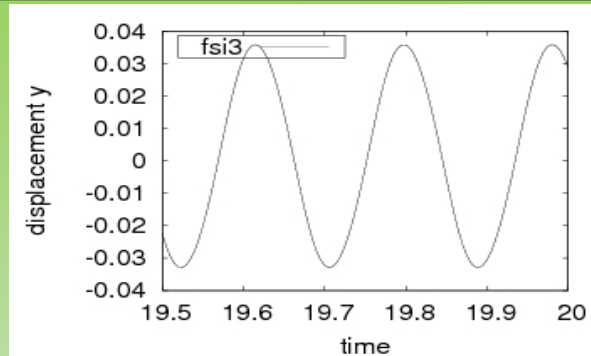
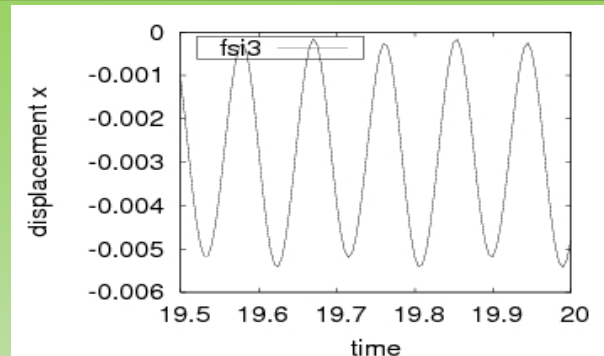
	ux of A [$\times 10^{-3} \text{ m}$]	uy of A [$\times 10^{-3} \text{ m}$]	drag	lift
FSI1	0.02270493	0.8208773	14.29426	0.763746

FSI2: large deformations, periodical oscillations



Test	ux of A [$\times 10^{-3}$ m]	uy of A [$\times 10^{-3}$ m]	drag	lift
FSI2	$-14.85 \pm 12.70 [3.86]$	$1.30 \pm 81.7 [1.93]$	$215.06 \pm 77.65 [3.86]$	$0.61 \pm 237.8 [1.93]$

FSI3: large deformations, complex oscillations



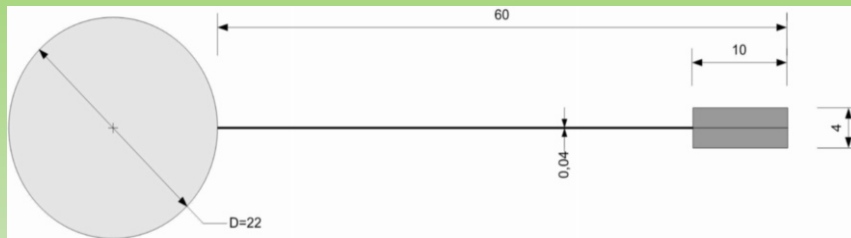
Test	u_x of A [$\times 10^{-3}$ m]	u_x of A [$\times 10^{-3}$ m]	drag	lift
FSI3	-2.88 ± 2.72 [10.93]	1.47 ± 34.99 [5.46]	460.5 ± 27.74 [10.93]	2.50 ± 153.91 [5.46]

Status of numerical benchmarking

- Subtests for validating CFD and CSM components are available:
 - CSM1-3: "OK"
 - CFD1: "easy" → $Re=20$
 - CFD2: (also) "easy" → $Re=100$
 - CFD3: "non-trivial" → $Re=200$
- FSI settings with desired properties:
 - FSI1: "simple" → for validation only
 - FSI3: "hard" → due to CFD3
 - FSI2: fully oscillating while CFD2 ($\approx$ same Re number!) is steady
⇒ Excellent check for interaction mechanisms
- **Evaluation and comparison of mathematical and algorithmic components - *everybody is invited to participate.***

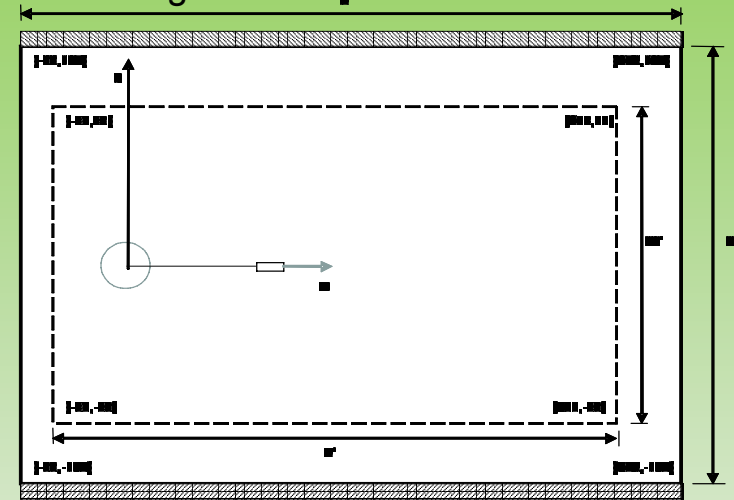
FSI4: Benchmarking of experimental data

- **Flustruc experiment**, Erlangen, <http://www.lstm.uni-erlangen.de/flustruc/>



fluid parameters	
density of the fluid	$1.05e-6 \text{ [kg/mm}^3\text{]}$
kinematic viscosity	164.0

solid parameters	
density of the beam (steel)	$7.85e-6 \text{ [kg/mm}^3\text{]}$
density of the rear mass	$7.8e-6 \text{ [kg/mm}^3\text{]}$
shear modulus	$7.58e13$
poisson ratio	0.3

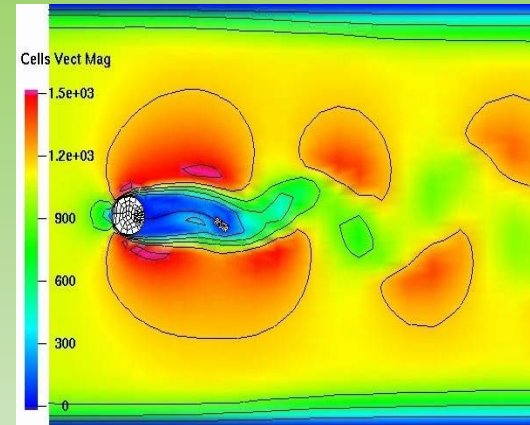


geometry parameter		value [mm]
channel length	L	338.0
channel width	W	240.0
cylinder center position	C	$(0.0, 0.0)$
cylinder radius	R	11.0
elastic structure length	l	50
elastic structure thickness	w	0.04
rear mass length	w'	10.0
rear mass thickness	h'	4.0
reference point (at $t=0$)	A	$(71.0, 0.0)$
reference point	B	$(11.0, 0.0)$

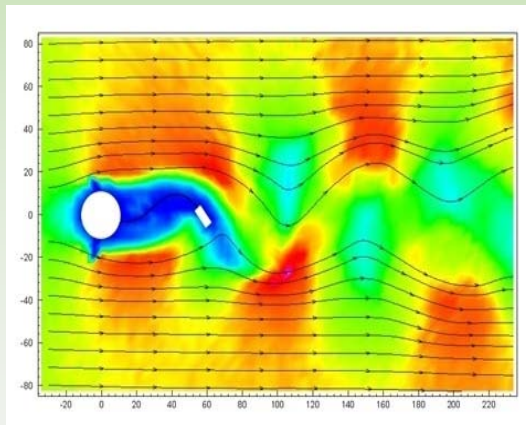
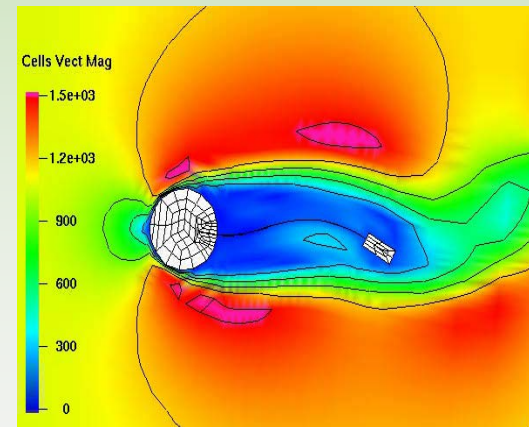
FSI4: New configuration

- + Laminar Flow (glycerine)
- + “2D” flow and deformation
- Rotational degree of freedom
- Large aspect ratio (thin structure),
- Corners

Laminar: Velocity=1.07 m/s, $Re=140$



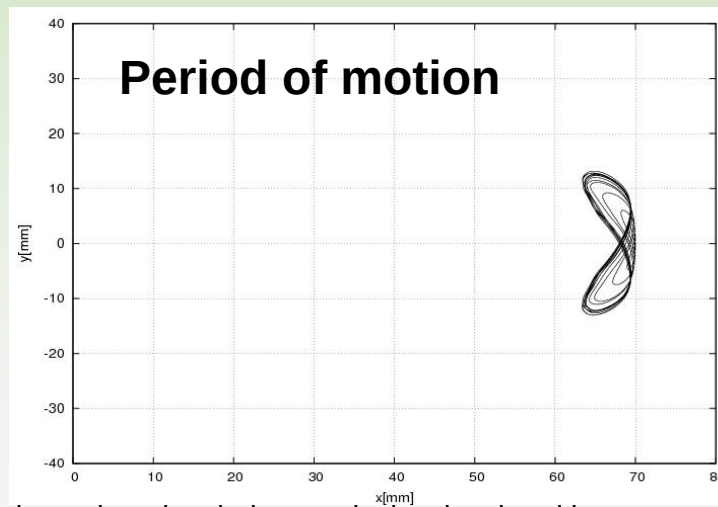
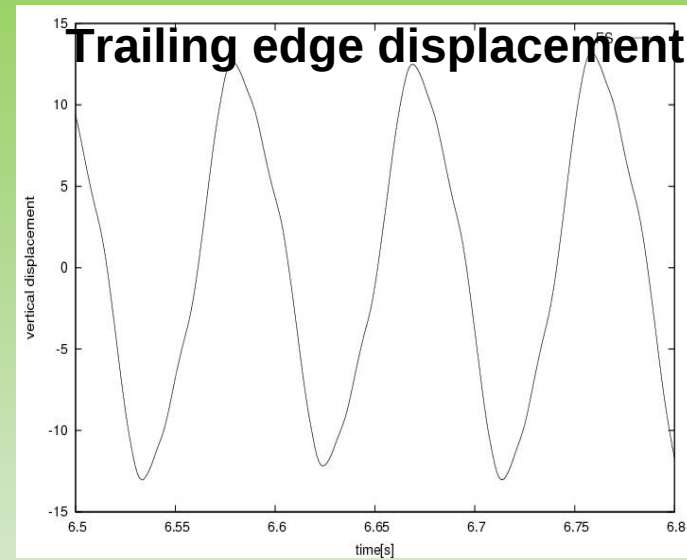
Zoomed



Flustruc experiment, Erlangen

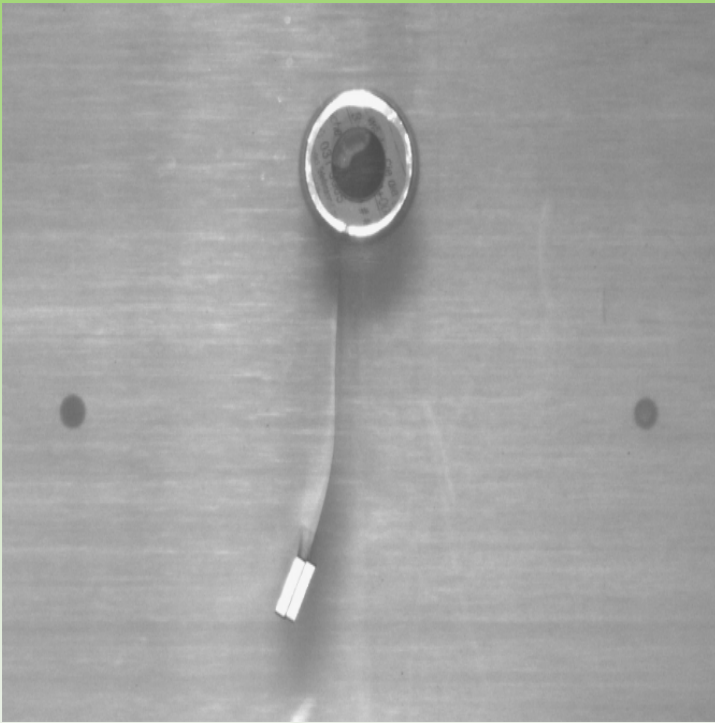
Computation

FSI4: Plots

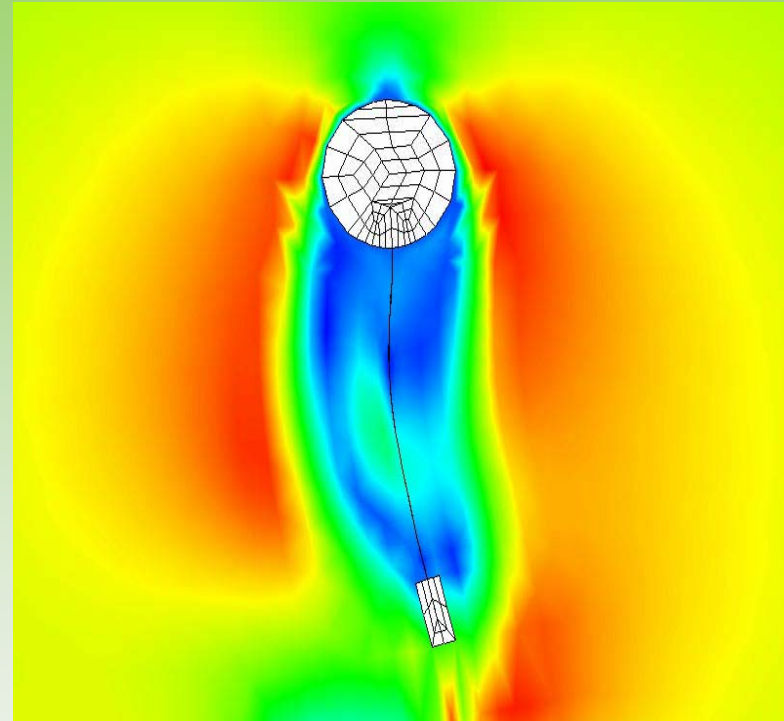


FSI4: Experiment and numerical simulations

Laminar: Velocity=1.07 m/s, $Re=140$



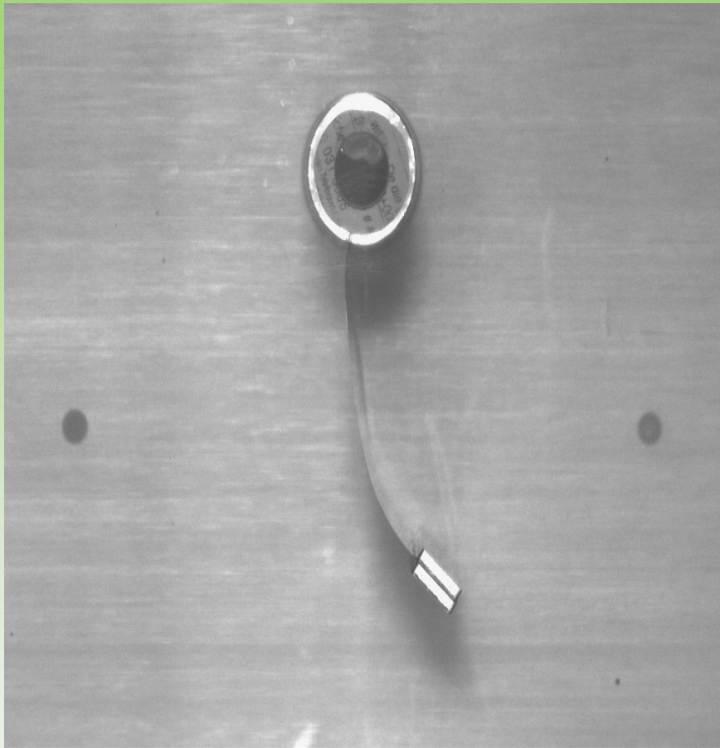
Experiment



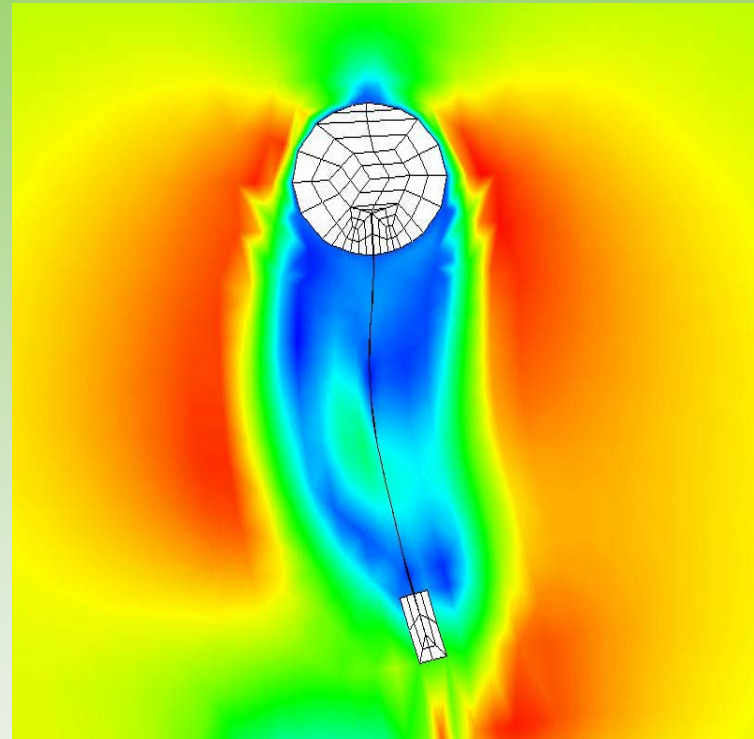
Numerical

FSI4: Experiment and numerical simulations

Laminar: Velocity=1.45 m/s, $Re=190$



Experiment



Numerical

FSI Optimization

- The main design aims could be
 - I) Drag/Lift minimization**
 - II) Minimal pressure loss
 - III) Minimal nonstationary oscillations

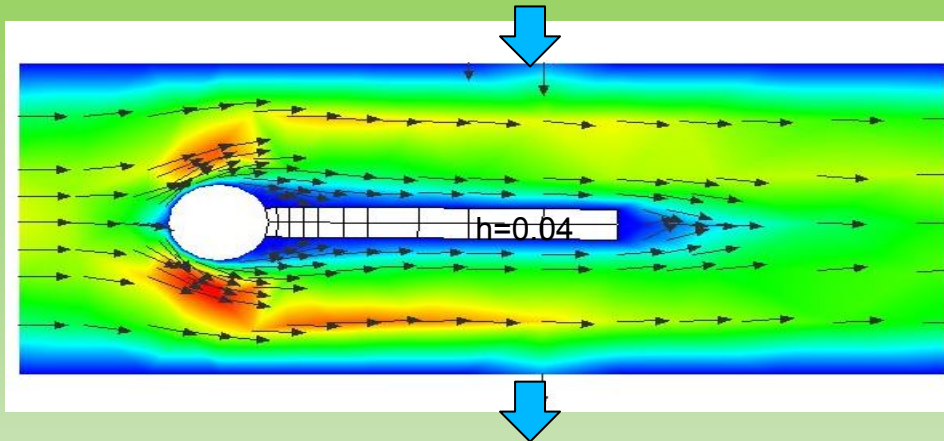
- To reach these aims, we might allow
 - 1. Boundary control of inflow section**
 - 2. Change of geometry: elastic channel walls or length/thickness of elastic beam
 - 3. Optimal control of volume forces

- Optimal control of nonstationary flow might be hard for the starting

- Results for the moment are combination of I)-III) with 1)-3)

FSI OPT 1

➤ Uncontrolled flow



	ux of A [$\times 10^{-3}$ m]	uy of A [$\times 10^{-3}$ m]	drag	lift
FSI1	0.0227	0.8209	14.295	0.7638

Lift $\neq$ 0

➤ Aim: minimize($lift^2 + \alpha V^2$)

w.r.t V1, V2.

V1 velocity from top

V2 velocity from below

FSI OPT 1

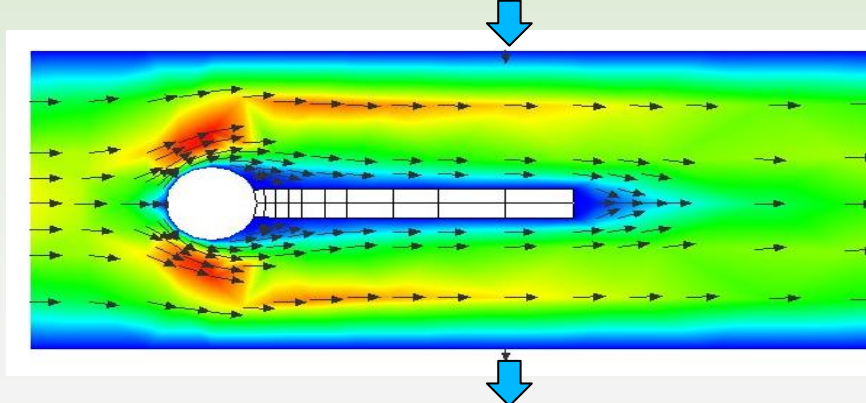
➤ TESTS for FSI 1 (Boundary control)

Level 1

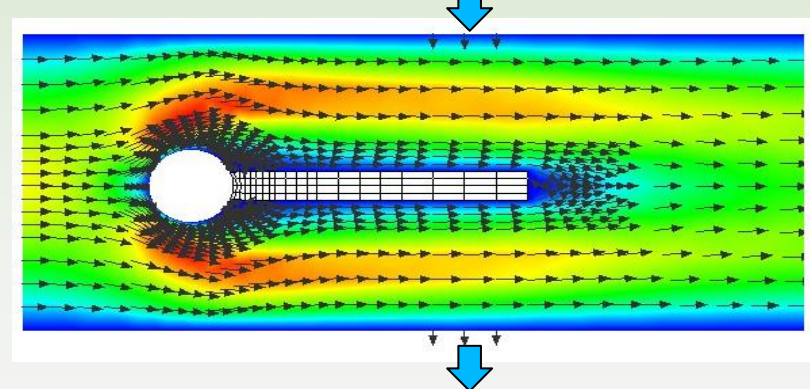
α	Iter steps	extreme point	drag	Lift	Iter steps	extreme point	drag	Lift
1e0	57	(3.74e-1,3.88e-1)	1.5471e+01	8.1904e-1	59	(3.66e-1,3.79e-1)	1.5550e+01	7.8497e-1
1e-2	60	(1.04e0,1.06e0)	1.5474e+01	2.2684e-2	59	(1.02e0,1.04e0)	1.5553e+01	2.1755e-2
1e-4	73	(1.06e0,1.08e0)	1.5474e+01	2.3092e-4	71	(1.04e0,1.05e0)	1.5553e+01	2.2147e-4
1e-6	81	(1.06e0,1.08e0)	1.5474e+01	2.3096e-6	86	(1.04e0,1.05e0)	1.5553e+01	2.2151e-6

Level 2

Level 1



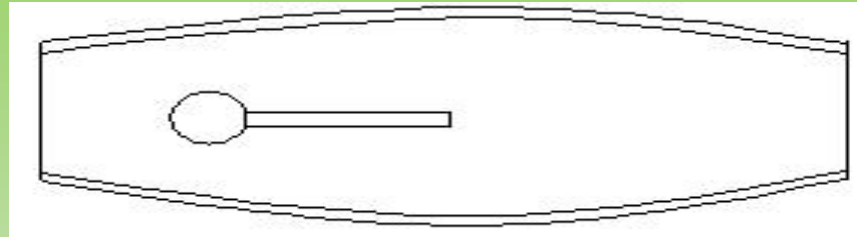
Level 2



Numerical benchmarking of fluid-structure interaction between elastic object and laminar incompressible flow

Outlook

➤ Further examples might be:



1. minimize($lift^2 + \alpha V^2$) for deformed case
2. Pressure loss minimize: minimize($p_{in} - p_{out}$)

w.r.t elastic deformation of the wall

or

w.r.t geometrical and material properties of beam