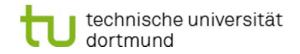
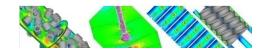
# Finite Element-Fictitious Boundary Methods (FEM-FBM) for time-dependent mixing processes in complex geometries

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<u>http://www.featflow.de</u> <u>http://www.mathematik.tu-dortmund.de/LS3</u>





### Motivation: Numerical & Algorithmic Challenges

Accurate, robust, flexible and efficient simulation of multiphase problems with dynamic interfaces and complex geometries, particularly in 3D, is still a challenge!

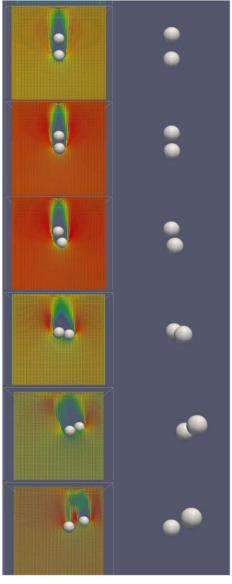
- Mathematical Modelling of Dynamic Interfaces
- Numerics / CFD Techniques
- HPC Techniques / Software
- Validation / Benchmarking

**Aim:** Highly efficient, flexible and accurate "real life" simulation tools based on modern numerics and algorithms while exploiting modern hardware!

**Realization:** 

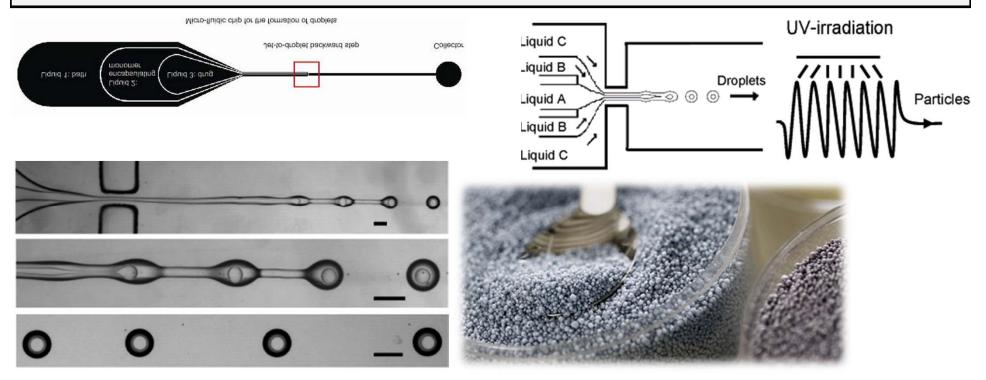
#### FEATFLOW



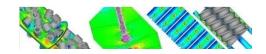


### **Motivation: Target Application I**

- Numerical simulation of *micro-fluidic drug encapsulation ("monodisperse compound droplets")* for application in lab-on-chip and bio-medical devices
- Polymeric "bio-degradable" outer fluid with viscoelastic effects
- Optimization of chip design w.r.t. boundary conditions, flow rates, droplet size, geometry

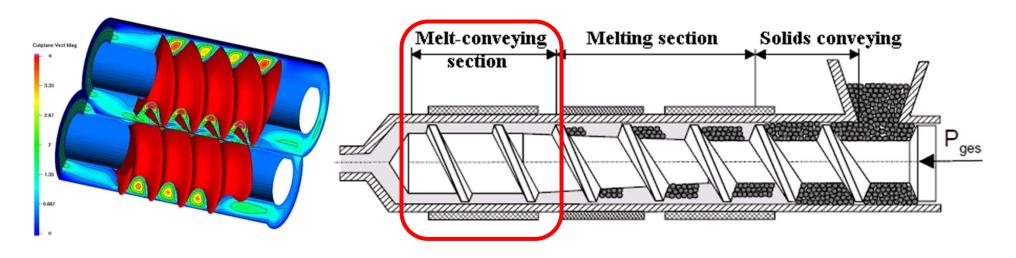


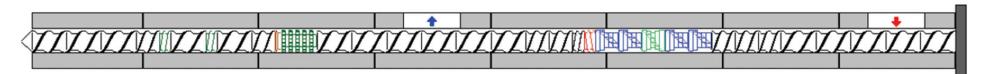




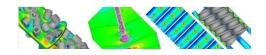
### Motivation: Target Application II

- Non-Newtonian rheological models (shear & temperature dependent)
- Non-isothermal flow conditions (cooling from outside, heat production)
- Evaluation of torque acting on the screws, resulting energy consumption
- Influence of local characteristics on global product quality
- Influence of gaps on back-mixing









## **Basic Flow Solver: FEATFLOW**

#### Numerical features:

- Parallelization based on domain decomposition
- FCT & EO stabilization techniques
- High order FEM (Q2/P1) discretization
- Use of unstructured meshes
- Adaptive grid deformation
- Newton-Multigrid solvers

#### **HPC** features

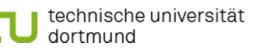
- Massive parallel
- GPU computing
- Open source

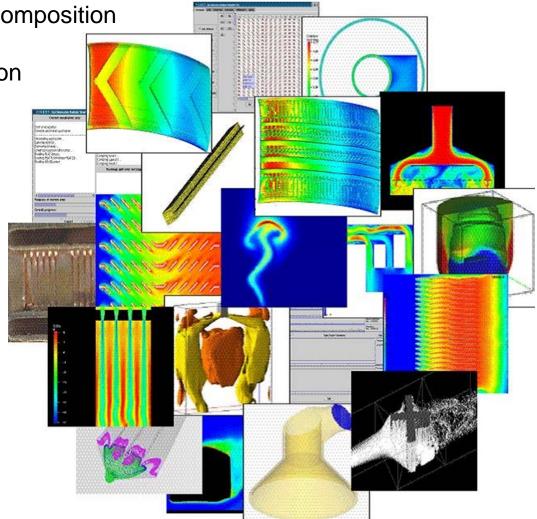


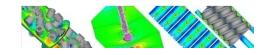


#### **Hardware-oriented Numerics**

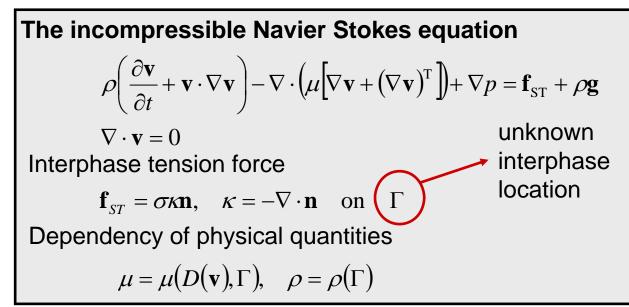








# Two phase flow (I-I) with resolved interphases



Interphase capturing realized by Level Set method

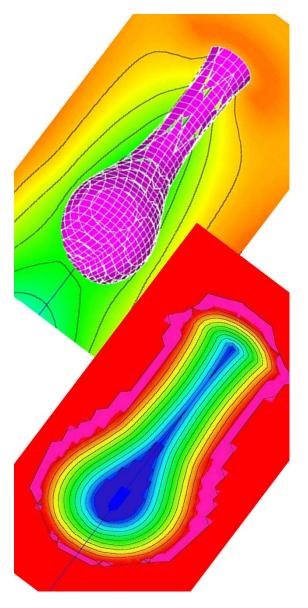
$$\frac{\partial \phi}{\partial t} + \mathbf{v} \cdot \nabla \phi = 0 \quad + \quad \frac{\partial \phi}{\partial \tau} + \mathbf{n} \cdot \nabla \phi = S(\phi) \quad \mathbf{n} = S(\phi) \frac{\nabla \phi}{|\nabla \phi|}$$

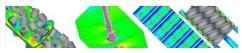
- Exact representation of the interphase
- Natural treatment of topological changes
- Provides derived geometrical quantities ( $\mathbf{n}, \kappa$ )
- Requires reinitializion w.r.t. distance field

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• Can lead to mass loss  $\rightarrow$  dG(1) discretization!

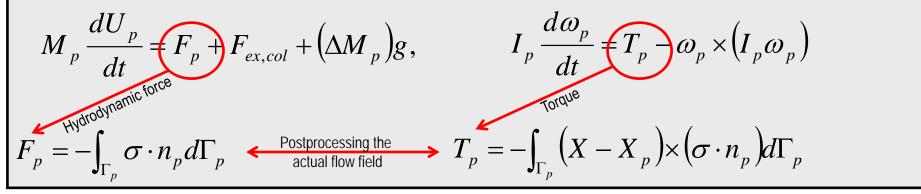
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# Two phase flow (s-l) with resolved interphases

- Fluid motion is governed by the Navier-Stokes equations
- Particle motion is described by Newton-Euler equations

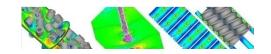


#### Fictitious Boundary Method

- Surface integral is replaced by volume integral
  Use of monitor function (liquid/solid)
- Normal to particle surface vector is non-zero only at the surface of particles  $n_p = \nabla \alpha_p$

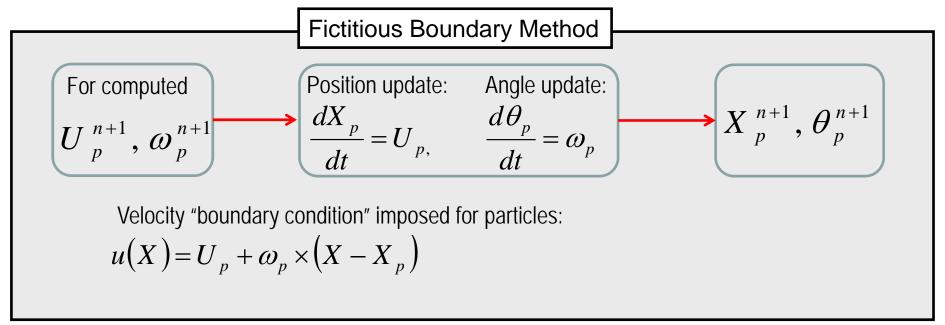
$$F_{p} = -\int_{\Gamma_{p}} \sigma \cdot n_{p} d\Gamma_{p} = -\int_{\Omega_{T}} \sigma \cdot \nabla \alpha_{p} d\Omega_{T}$$
$$T_{p} = -\int_{\Gamma_{p}} (X - X_{p}) \times (\sigma \cdot n_{p}) d\Gamma_{p} = -\int_{\Omega_{T}} (X - X_{p}) \times (\sigma \cdot \nabla \alpha_{p}) d\Omega_{T}$$





 $\alpha_p(X) = \begin{cases} 1 & \text{for} & X \in \Omega_p \\ 0 & \text{for} & X \in \Omega_f \end{cases}$ 

## Two phase flow (s-l) with resolved interphases

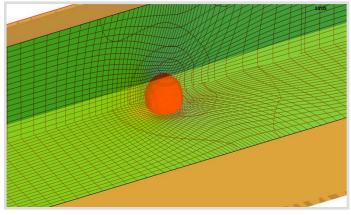


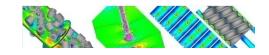
- supports HPC concepts (no computational overhead, constant data structures, optimal load balancing)
- reduces dramatically requirements put on the computational mesh
  relatively low resolution
  - Brute force  $\rightarrow$  Finer mesh resolution
  - High resolution interpolation functions
    - Grid deformation (via Level-Set function)

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#### **Grid Deformation Method**

idea : construct transformation  $\phi$ ,  $x = \phi(\xi, t)$  with det  $\nabla \phi = f$  $\implies$  local mesh area  $\approx f$ 

1. Compute monitor function  $f(x,t) > 0, f \in C^1$ and  $\int f^{-1}(x,t) dx = |O| = V(t - [0,1])$ 

$$\int_{\Omega} f^{-1}(x,t) dx = |\Omega|, \quad \forall t \in [0,1]$$

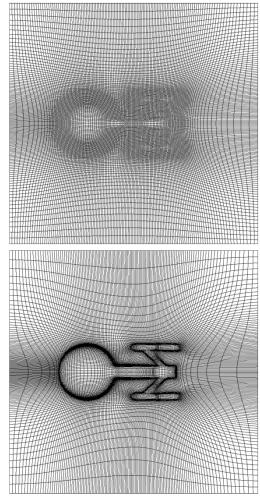
2. Solve  $(t \in [0,1])$ 

$$\Delta v(\xi,t) = -\frac{\partial}{\partial t} \left( \frac{1}{f(\xi,t)} \right), \quad \frac{\partial v}{\partial n} \Big|_{\partial \Omega} = 0$$

3. Solve the ODE system

$$\frac{\partial}{\partial t}\phi\left(\xi,t\right) = f\left(\phi\left(\xi,t\right),t\right)\nabla v\left(\phi\left(\xi,t\right),t\right)$$

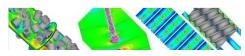
new grid points:  $x_i = \phi(\xi_i, 1)$ 



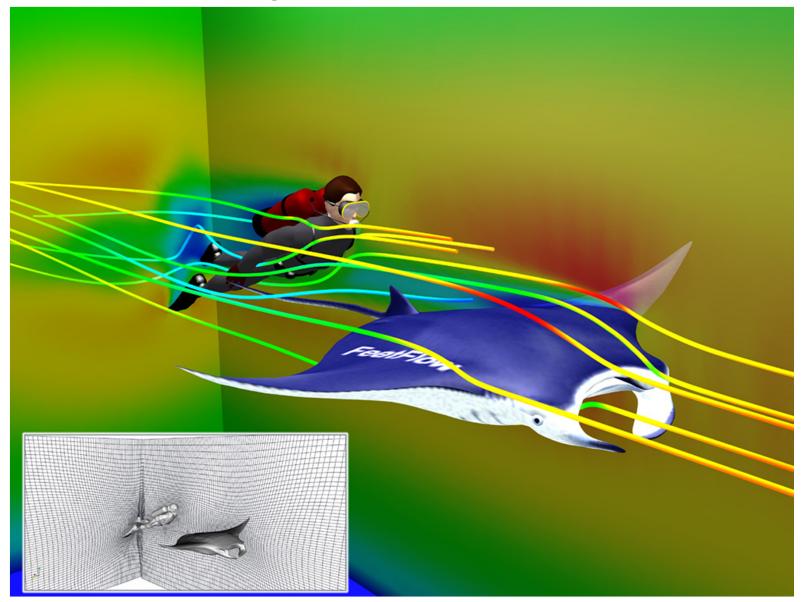
Grid deformation preserves the (local) logical structure of the grid

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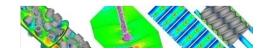
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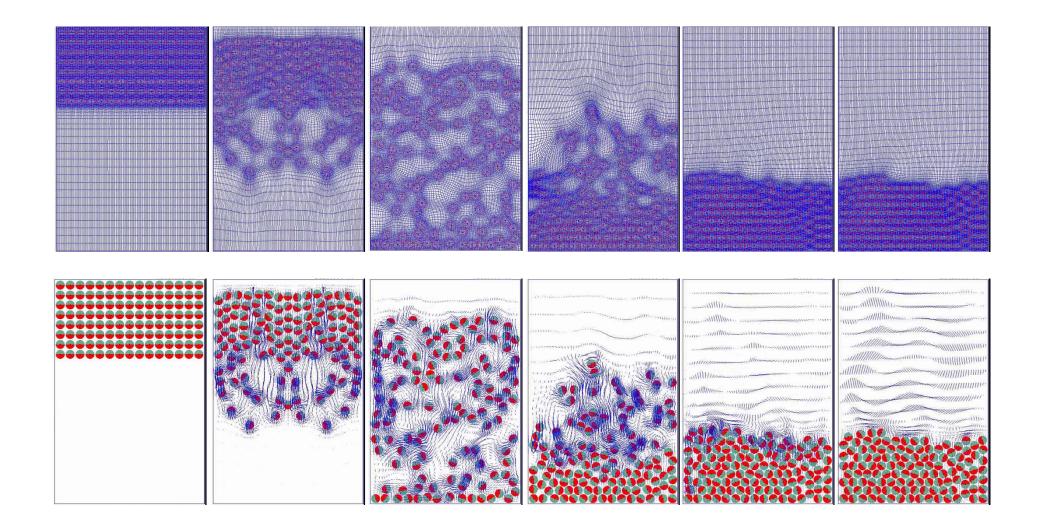
## **Generalized Tensorproduct Meshes**



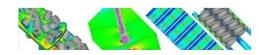




#### **Sedimentation of many Particles**



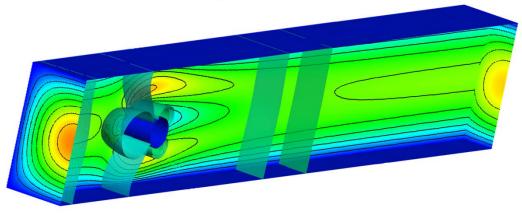




Flow Simulation for the Flow Around Cylinder problem

Known benchmark problem (DFG) in the CFD community

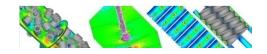
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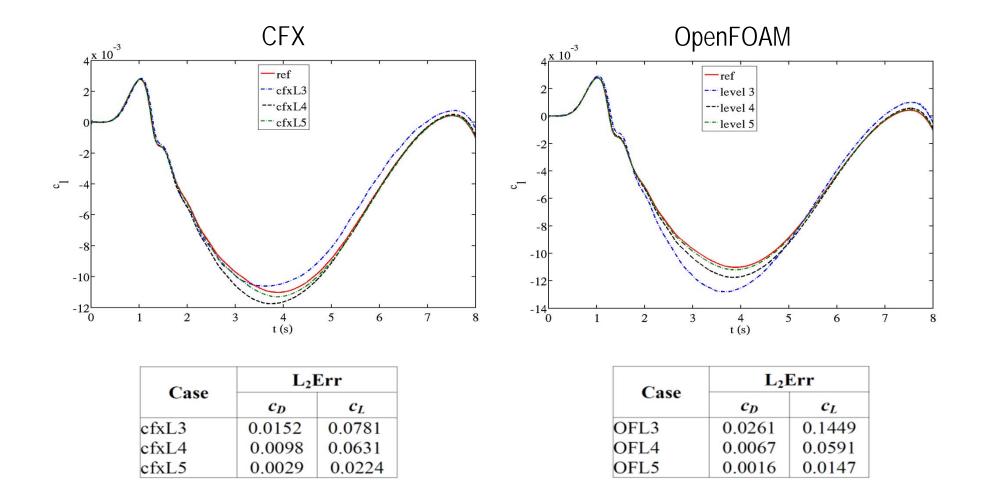


- Comparison of CFX 12.0, OpenFoam 1.6 and FeatFlow
- Drag and lift coefficients behave very sensitive to mesh resolution
- $\rightarrow$  Ideal indicator for computational accuracy
- Five consequently refined meshes L1 (coarse), ..., L5 (fine)
- Same meshes and physical models used in all three codes

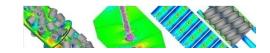
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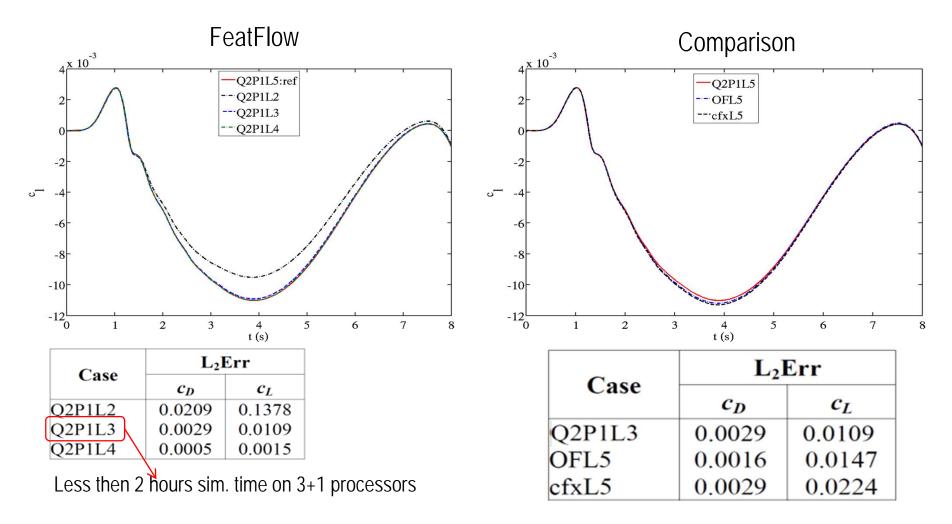
Mesh Level	# Elements	
L2	6,144	
L3	49,152	
L4	393,216	
L5	3,145,728	





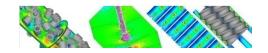






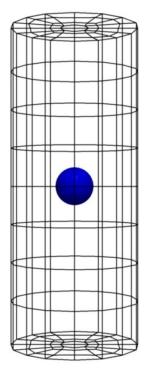
- $\rightarrow$  Same order of accuracy with FeatFlow on L3 as L5 with CFX and OpenFOAM on L5!
- → High order Q2/P1 FEM + (parallel) Multigrid Solver

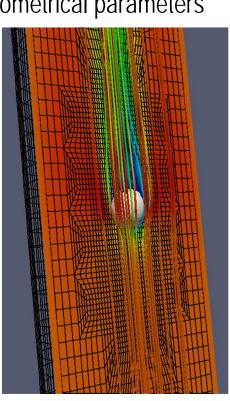
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#### Free fall of particles:

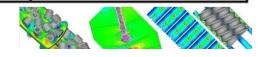
- Terminal velocity
- Different physical parameters
- Different geometrical parameters





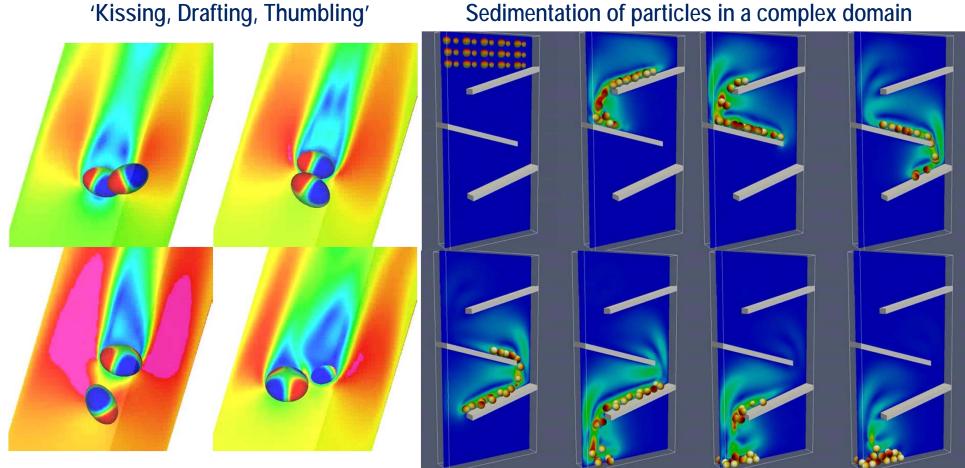
*Münster, R.; Mierka, O.; Turek, S.:* Finite Element Fictitious Boundary Methods (FEM-FBM) for 3D particulate flow, IJNMF, 2010, accepted

IMULT				
$d_s = 0.3,  \rho_s = 1.14$				
ν	$U_{featflow}$	$U_{exp}$	Relative error (%)	
0.02	5.885	6.283	6.33	
0.05	4.133	3.972	4.05	
0.1	2.588	2.426	6.66	
0.2	1.492	1.401	6.50	
$d_s = 0.2,  \rho_s = 1.14$				
ν	$U_{featflow}$	$U_{exp}$	Relative error (%)	
0.02	4.370	4.334	0.83	
0.05	2.699	2.489	8.44	
0.1	1.649	1.552	6.25	
0.2	0.946	0.870	8.74	
$d_s = 0.2,  \rho_s = 1.02$				
ν	$U_{featflow}$	$U_{exp}$	Relative error (%)	
0.01	1.4660	1.4110	3.90	
0.02	0.9998	0.9129	9.52	
0.05	0.4917	0.4603	6.82	
0.1	0.2637	0.2571	2.57	
0.2	0.1335	0.1317	1.37	

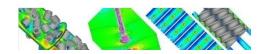




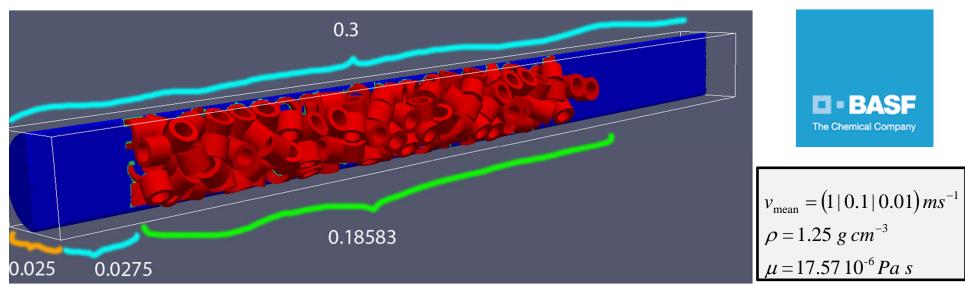
### 3D simulations with complex shapes



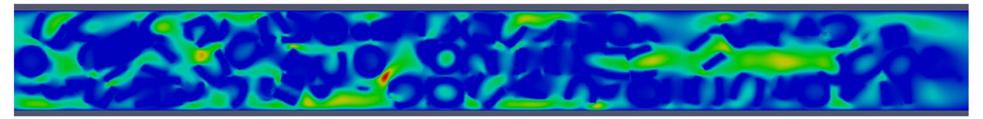




#### Absorber packing simulations



#### Velocity distribution

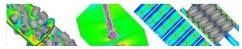


#### Pressure distribution

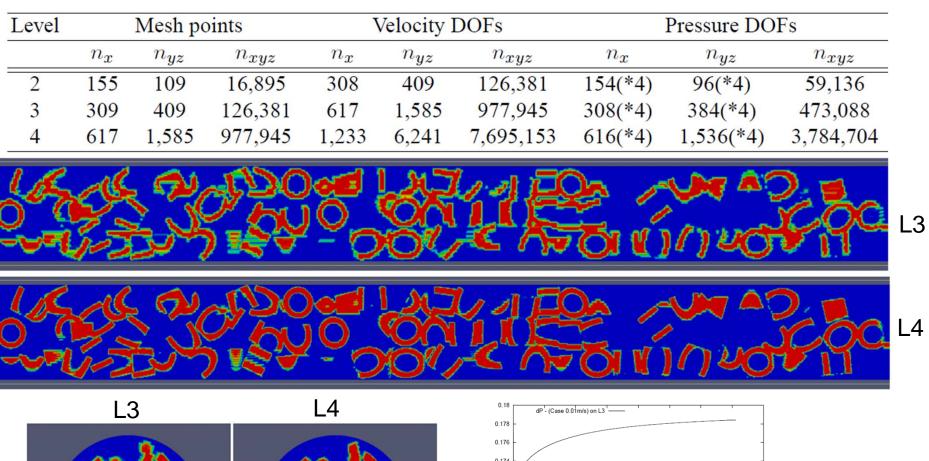


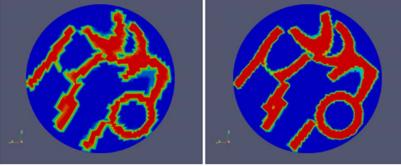
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#### Absorber packing simulations

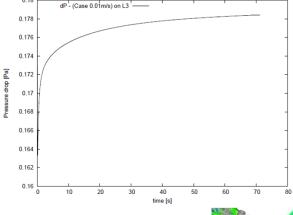


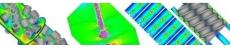


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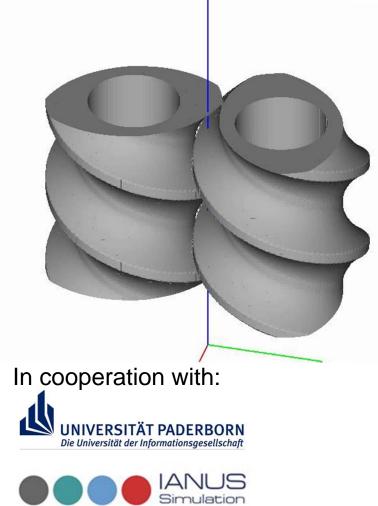


# **Twinscrew Flow Simulations**

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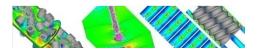
#### Geometrical representation of the twinscrews $\rightarrow$ Fictitious Boundary Method



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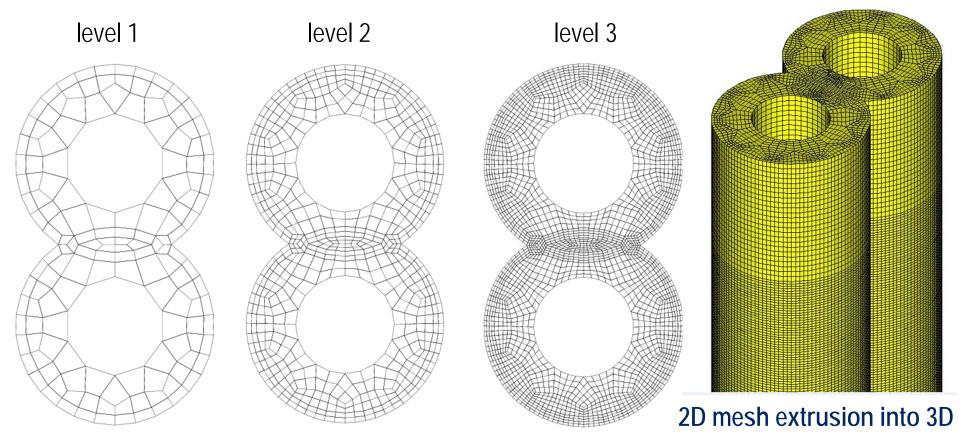


- Applicable for conveying and kneading elements
- Mathematical description available for single, double- or triplet-flighted screws
- Surface and body of the screws are known at any time
- Mathematical formulation replaces external CADdescription



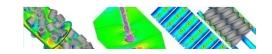
### **Twinscrew Flow Simulations**

#### Meshing strategy – Hierarchical mesh refinement

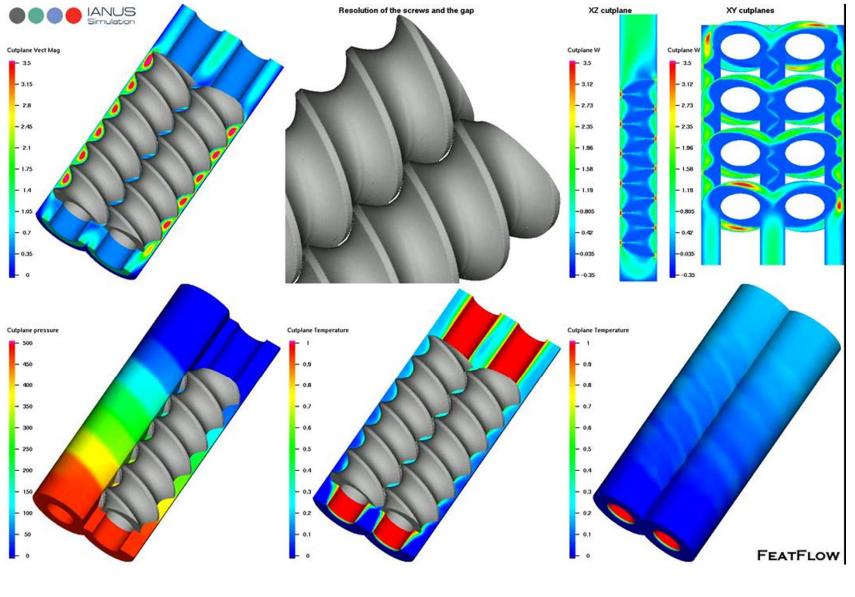


Pre-refined regions in the vicinity of gaps

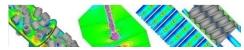




#### **Twinscrew Flow Simulations**

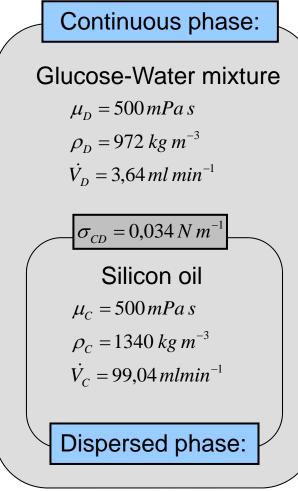






# Vielen Dank!

## Benchmarking with experimental results



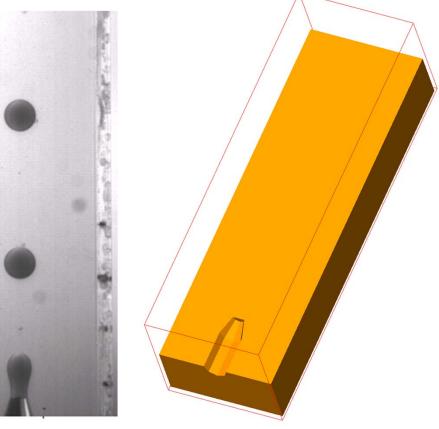
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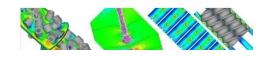
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#### Experimental Set-up with AG Walzel (BCI/Dortmund)

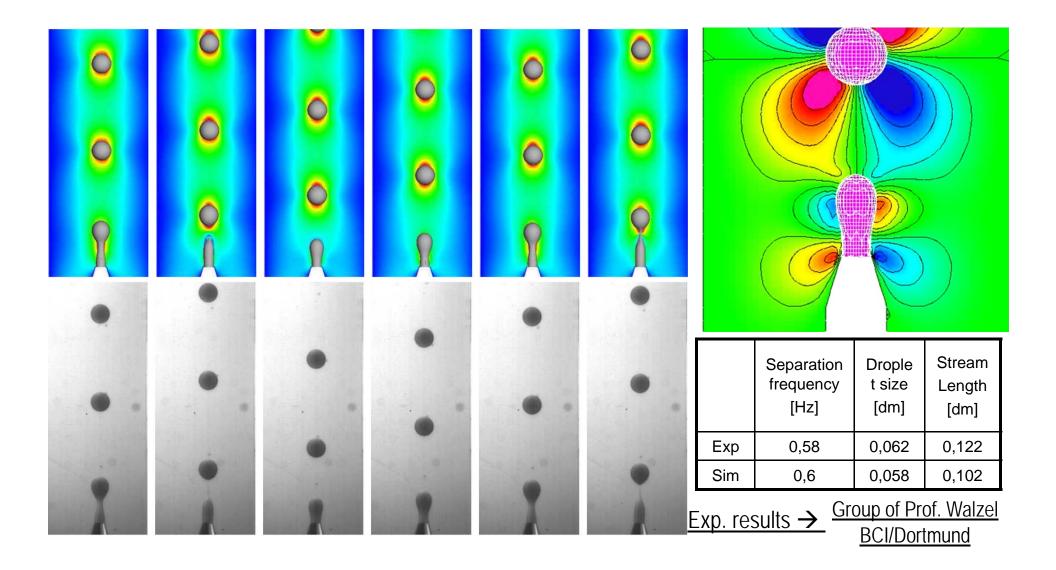


#### Validation parameters:

- frequency of droplet generation
- droplet size
- stream length



#### Benchmarking with experimental results





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