On higher order FEM techniques for multiphase flow

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Overview & Motivation:

Accurate, robust, flexible and efficient simulation of *multiphase problems* with *dynamic interfaces* and *complex geometries*, particularly in 3D, is still a challenge!

Vision: Highly efficient, flexible and accurate "real Mathematical Modelling life" simulation tools based on modern Numerics Numerics / CFD Techniques and algorithms while exploiting modern hardware! Validation / Benchmarking HPC Techniques / Software **Realization:** FEATFLOW technische universität Stefan Turek dortmund

Typical applications require efficient basic flow solvers and techniques for liquid-liquid & liquid-solid interfaces in complex (time-dependent) domains



Basic Flow Solver: FeatFlow

Numerical features:

- High order FEM (Q2/P1) discretization schemes
- FCT & EO stabilization techniques
- Use of unstructured meshes
- Fictitious Boundary (FBM) methods
- Adaptive grid deformation
- Newton-Multigrid solvers

HPC features:

- Massive parallel
- GPUs/ARMs
- Open source







Hardware-oriented Numerics



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Interface capturing realized by Level Set method

$$\frac{\partial \phi}{\partial t} + \mathbf{v} \cdot \nabla \phi = 0$$

- Exact representation of the interface
- Natural treatment of topological changes
- Provides derived geometrical quantities (\mathbf{n}, κ)



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Problems and Challenges

- **Steep gradients** of the velocity field and of other physical quantities near the interface (oscillations!)
- **Reinitialization** w.r.t. distance field (artificial movement of the interface → mass loss, how often to perform?)
- Mass conservation (during advection and reinitialization of the Level Set function)
- Representation of **surface tension**: CSF, Line Integral, Laplace-Beltrami, Phasefield, etc.
- Explicit or implicit treatment (→ Capillary Time Step restriction?)
- Fast multigrid solvers for Q2/P1 via Discrete Projection Method





Steep changes of physical quantities:

1) Elementwise averaging of the physical properties (prevents oscillations):

 $\rho_e = x\rho_1 + (1-x)\rho_2$, $\mu_e = x\mu_1 + (1-x)\mu_2$ x is the volume fraction

- Flow part: Extension of nonlinear stabilization schemes (FCT, TVD, EO-FEM) for the momentum equation for LBB stable element pairs with discontinuous pressure (Q2/P1)
- Interface tracking part with DG(1)-FEM: Flux limiters satisfying LED requirements

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Reinitialization

- Mainly required in the vicinity of the interface
- How often to perform?
- Which realization to implement?
- Efficient parallelization (3D!)

Alternatives

- Brute force (introducing new points at the zero level set)
- Fast sweeping ("advancing front" upwind type formulas)
- Fast marching
- Algebraic Newton method
- Hyperbolic PDE approach
- many more.....

Maintaining the signed distance function by PDE reinitialization

$$\frac{\partial \phi}{\partial \tau} + \mathbf{u} \cdot \nabla \phi = S(\phi) \qquad \mathbf{u} = S(\phi) \frac{\nabla \phi}{|\nabla \phi|} \quad \Leftrightarrow \quad |\nabla \phi| = 1$$

Problems:

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- What to do with the sign function at the interface? (smoothing?)
- How to handle the underlying non-linearity?
- How often to perform? (expensive \rightarrow steady state)



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Fine-tuned reinitialization

Our reinitialization is performed in combination of 2 ingredients:

1) Elements intersected by the interface are modified w.r.t. the slope of the distance distribution ("Parolini trick" for DG-P1) such that $|\nabla \phi| = 1$

2) Far field reinitialization: realization is based on the PDE approach ("FBM"), but it does not require smoothening of the distance function!

In addition: continuous projection of the interface (smoothening of the discontinuous P₁ based distance function)

$$\phi_{\scriptscriptstyle P_1} \xrightarrow{L_2 \text{ projection}} \rightarrow \phi_{\scriptscriptstyle Q_1} \xrightarrow{L_2 \text{ projection}} \rightarrow \phi_{\scriptscriptstyle P_1}$$



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Surface Tension: Semi-implicit CSF formulation based on Laplace-Beltrami

$$\mathbf{f}_{\mathrm{ST}} = \int_{\Omega} \sigma \mathbf{k} \hat{\mathbf{n}} \cdot \mathbf{v} \,\delta(\Gamma, \mathbf{x}) \,d\mathbf{x} = \int_{\Omega} \sigma \left(\underline{\Delta} \mathbf{x} \big|_{\Gamma} \right) \cdot \left(\mathbf{v} \,\delta(\Gamma, \mathbf{x}) \right) d\mathbf{x}$$
$$= -\int_{\Omega} \sigma \underline{\nabla} \mathbf{x} \big|_{\Gamma} \cdot \underline{\nabla} \left(\mathbf{v} \,\delta(\Gamma, \mathbf{x}) \right) d\mathbf{x} = -\int_{\Omega} \sigma \underline{\nabla} \mathbf{x} \big|_{\Gamma} \cdot \underline{\nabla} \mathbf{v} \,\delta(\Gamma, \mathbf{x}) \,d\mathbf{x}$$

Application of the semi-implicit time integration yields $\mathbf{x}|_{\Gamma^{n+1}} = \mathbf{x}|_{\Gamma^n} + \Delta t \mathbf{u}^{n+1}$



$$\mathbf{f}_{\mathrm{ST}} = -\int_{\Omega} \boldsymbol{\sigma} \, \delta_{\varepsilon} \Big(dist(\Gamma^{n}, \mathbf{x}) \Big) \underline{\nabla} \, \widetilde{\mathbf{x}} \Big|_{\Gamma}^{n} \cdot \underline{\nabla} \mathbf{v} \, d\mathbf{x} \\ - \Delta t^{n+1} \int_{\Omega} \boldsymbol{\sigma} \, \delta_{\varepsilon} \Big(dist(\Gamma^{n}, \mathbf{x}) \Big) \underline{\nabla} \mathbf{u}^{n+1} \cdot \underline{\nabla} \mathbf{v} \, d\mathbf{x}$$

Advantages

- Relaxes Capillary Time Step restriction
- "Optimal" for FEM-Level Set approach due to global information



Data Layout for Q2/P1 FEM





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Numerical Analysis of the Multigrid Solvers

dt = 0.001 | nOfSmstepP(SOR) = 8,F,rlx = 1.0 | nOfSmstepV(SOR+JAC) = 4,V,rlx = 0.5

Level	# MG steps P	MG rates P	# NonLin/MG steps V	MG rates V
2	2.4	0.0425	2/1	3.6e-4
3	3.7	0.1324	2/1	1.3e-3
4	3.0	0.0947	2/1	2.2e-3

dt = 0.010 | nOfSmstepP(SOR) = 8,F, rlx = 1.0 | nOfSmstepV(SOR+JAC) = 4,V,rlx = 0.5

Level	# MG steps P	MG rates P	# NonLin/MG steps V	MG rates V
2	2.2	0.0330	2/1	1.3e-3
3	3.9	0.1439	2/1	6.4e-3
4	3.2	0.1064	2/1	8.5e-3

Convergence criterions

LinearDefectReductionP=1e-3

NonLinearDefectReductionV=1e-4 LinearDefectReductionV=1e-1

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Benchmarking

Known benchmark problem (DFG) in the CFD community





- Comparison of CFX 12.0, OpenFoam 1.6 and FeatFlow
- Drag and lift coefficients behave very sensitive to mesh resolution
- \rightarrow Ideal indicator for computational accuracy
- Five consequently refined meshes L1 (coarse), ..., L5 (fine)
- Same meshes and physical models used in all three codes

Mesh Level	# Elements		
L2	6,144		
L3	49,152		
L4	393,216		
L5	3,145,728		

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Benchmarking

Flow Simulation with CFD software available on the market



Case	L2 error		timing Ca		Case	L2 e	error	Timing
	c _D	CL				C _D	CL	
CFX L3	0.0152	0.0781	13420		OF L3	0.0261	0.1449	5180
CFX L4	0.0098	0.0631	4 x 58680		OF L4	0.0067	0.0591	4 x 19500
CFX L5	0.0029	0.0224	8 x 205600		OF L5	0.0016	0.0147	8 x 595200

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Benchmarking Flow Simulation with **FEATFLOW** FeatFlow Comparison $4 \frac{x \cdot 10^{-3}}{x \cdot 10^{-3}}$ 4×10^{-3} Q2P1L5:ref Q2P1L5 Q2P1L2 - OFL5 -- Q2P1L3 Q2P1L4



Less than 2 hours sim. time with adaptive time stepping on 3+1 processors

Same order of accuracy with **FEATFLOW** on L3 as L5 with **CFX** and **OpenFOAM** on L5! \rightarrow

High order Q2/P1 FEM + (parallel) Multigrid Solver \rightarrow

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Benchmarking

2D Bubble Benchmarks

http://www.featflow.de/beta/en/benchmarks/





3D convergence analysis for large density jumps



Benchmarking with experimental results





- frequency of droplet generation
- droplet size
- stream length

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Benchmarking with experimental results



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Tailored monodisperse droplets via modulation



Preliminary Studies: Coupling FBM-LSFEM



Next Steps for Multiphase Flow

- Adaptive time stepping + adaptive grid alignment/ALE.
- Coupling with turbulence models.
- Coupling with rigid particles.
- Analysis of viscoelastic effects.
- Benchmarking and experimental validation for many particles/bubbles.





