



# Overview (II)

- 1 Concepts of FEAST
- 2 Treating Elasticity Problems with FEAST
- 3 Some Results and Outlook

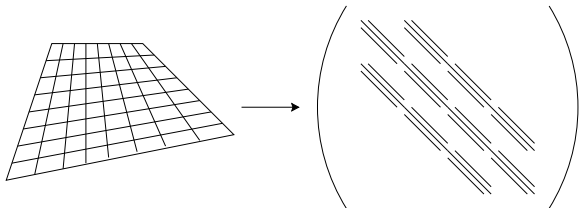




# FEAST's Mesh & Matrix Concept

'data moving  $\gg$  data processing'

- unstructured meshes  $\Rightarrow$  indirect addressing  
 $\Rightarrow$  expensive memory access  $\Rightarrow$  poor MFLOP/s rates
- FEAST uses **generalised tensor product meshes**

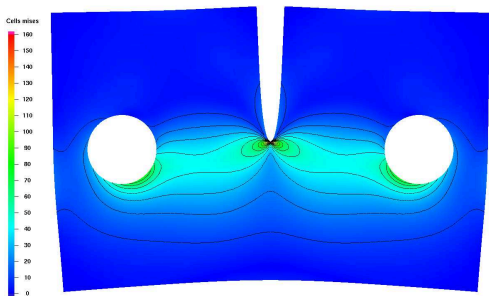
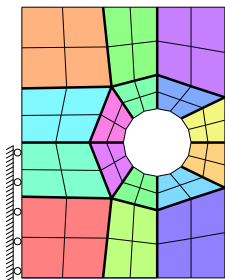


- rowwise numbering  
 $\Rightarrow$  exactly **9 matrix bands** for bilinear elements
- direct addressing, caching
- optimised Linear Algebra routines (SPARSE BANDED BLAS)



# FEAST's Mesh & Matrix Concept

More complex domains by joining several TP meshes ('macros')



Here:

- 64 macros (=64 local matrices), each macro refined 10x
- distributed over 16 processors
- $\Rightarrow 1.34 \cdot 10^8$  DOFs in total





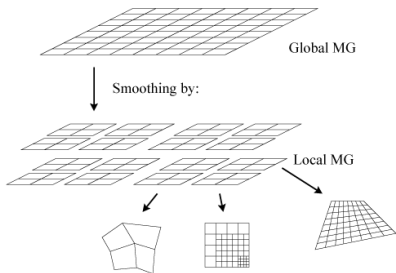
# FEAST's Solver Concept

FEAST uses **generalised Multigrid/Domain Decomposition** methods

**ScaRC**  
**Scalable Recursive Clustering**

- global MG smoothed by local MG
- locally adapted solution methods
- recursively hide local mesh irregularities

⇒ **high numerical and parallel efficiency**





# Elasticity with FEAST

- Basic idea: Reduction to solution of scalar problems
- Example: Linear Elasticity for compressible material
- Separate displacement ordering  $\Rightarrow$  **block-structured** linear system:

$$\begin{pmatrix} \mathbf{K}_{11} & \mathbf{K}_{12} \\ \mathbf{K}_{12}^T & \mathbf{K}_{22} \end{pmatrix} \begin{pmatrix} \mathbf{u}_1 \\ \mathbf{u}_2 \end{pmatrix} = \begin{pmatrix} \mathbf{f}_1 \\ \mathbf{f}_2 \end{pmatrix}$$

- $\mathbf{K}_{11}$  and  $\mathbf{K}_{22}$  correspond to scalar elliptical operators
- Basic iteration: block-preconditioned Richardson method

$$\mathbf{u}^{k+1} = \mathbf{u}^k + \tilde{\mathbf{K}}^{-1}(\mathbf{f} - \mathbf{K}\mathbf{u}^k),$$

e. g. Block-Jacobi  $\tilde{\mathbf{K}}^{-1} = \begin{pmatrix} \mathbf{K}_{11}^{-1} & \mathbf{0} \\ \mathbf{0} & \mathbf{K}_{22}^{-1} \end{pmatrix}$

- Acceleration: Krylov-space methods, multigrid





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Exploit  
FEAST  
concepts!

- Acceleration: Krylov-space methods, multigrid





# Saddle Point Solvers

- Mixed  $u/p$  formulation for (nearly) incompressible material

$$\begin{pmatrix} \mathbf{K} & \mathbf{B} \\ \mathbf{B}^T & \mathbf{C} \end{pmatrix} \begin{pmatrix} \mathbf{u} \\ \mathbf{p} \end{pmatrix} = \begin{pmatrix} \mathbf{f} \\ \mathbf{g} \end{pmatrix}$$

- Compressibility and LBB-stabilisation terms  $\rightarrow \mathbf{C}$
- Solving strategy: **Pressure Schur Complement approach**

$$\mathbf{S}\mathbf{p} = \mathbf{B}^T \mathbf{K}^{-1} \mathbf{f} - \mathbf{g}$$

with  $\mathbf{S} := \mathbf{B}^T \mathbf{K}^{-1} \mathbf{B} - \mathbf{C}$

- Basic iteration:

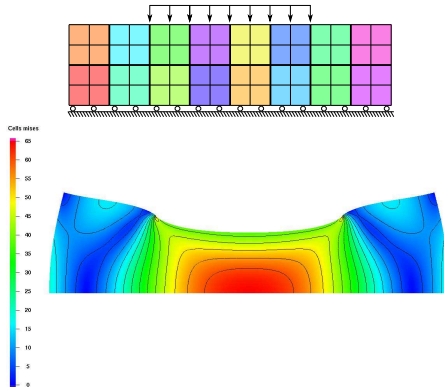
$$\mathbf{p}^{k+1} = \mathbf{p}^k + \tilde{\mathbf{S}}^{-1} (\mathbf{B}^T \mathbf{K}^{-1} \mathbf{f} - \mathbf{g} - \mathbf{S}\mathbf{p}^k)$$

- Applying SC preconditioner  $\tilde{\mathbf{S}} \Rightarrow$  **scalar equation!**
- Acceleration: Krylov-space method



# Results

- Compute cluster: 128 nodes, each one equipped with 2 Intel XEON CPUs (3.4 GHz) and 1 NVIDIA Quadro FX1400 GPU (350 MHz)
- Linear Elasticity, compressible material, outer BiCGstab solver,  $\varepsilon_{\text{rel}} = 10^{-6}$

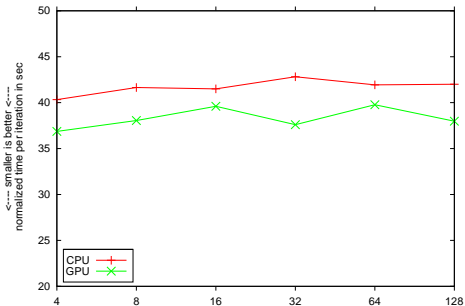






# Results

#DOFs	CPU			GPU		
	#CPUs	#iters	time	#GPUs	#iters	time
3.36e+7	8	5.5	221.8	4	5.5	202.8
6.71e+7	16	6.5	270.7	8	6.5	247.3
1.34e+8	32	6	249.0	16	6	237.6
2.68e+8	64	6	250.9	32	6	225.6
5.37e+8	128	7	293.6	64	7	278.4
1.07e+9	256	6.5	273.0	128	6.5	246.9





# Outlook (II)

## Already possible (CSM):

- Finite Deformation (St. VK, Neo-Hooke)
- Compressible + incompressible
- Damped Newton solver, Jacobian via Finite Differences
- Transient computations

## Outlook (FSI):

$$\frac{\partial \mathbf{F}(\mathbf{u}, \mathbf{v}, p)}{\partial (\mathbf{u}, \mathbf{v}, p)} = \begin{pmatrix} \mathbf{K}_{uu} & \mathbf{K}_{uv} & 0 \\ \mathbf{K}_{vu} & \mathbf{K}_{vv} & \mathbf{B}_u + \mathbf{B}_v \\ \mathbf{B}_u^T & \mathbf{B}_v^T & \mathbf{C} \end{pmatrix}$$

- Step 1: Applying fully-coupled Vanka-schemes (modified for Q1/Q1)
- Step 2: SC approach + reduction to scalar ScaRC solvers
- Step 3: Efficient Schur complement preconditioner !?!