

# Numerical Time Integration in Hybrid Monte Carlo Schemes for Lattice Quantum Chromo Dynamics

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# Contents

- ▶ Lattice QCD
- ▶ Hybrid Monte Carlo
- ▶ Molecular Dynamics Step
- ▶ Geometric Integration
- ▶ Fermionic fields



# Physical background

## Quantum Chromo Dynamics (QCD)

- ▶ QCD is the theory of the strong interaction (=color force) between quarks and gluons inside subatomic particles.
- ▶ Quark = elementary particle, fundamental constituent of matter, e.g., protons and neutrons.
- ▶ Gluons = exchange particles for the strong force between quarks.

## Lattice QCD

- ▶ approach to solve the theory of QCD
- ▶ investigation of elementary particles using computer simulations
- ▶ formulated on a lattice of points in space and time
- ▶ links  $U_\mu(x) \in SU(3)$  between points  $x$  and  $x + a\hat{\mu}$



# Task of Lattice QCD

Computation of observables (particle mass, e.g.)

observables given as expectation of certain operators  $O$ :

$$\langle O \rangle = \int_{\Omega} O(U) \Pi(U) dU \quad \text{with}$$

- ▶ probability space  $(\Omega, \sigma(\Omega), F_{\Pi})$
- ▶  $\Omega = (SU(3))^N$ ,  $N =$  lattice size
- ▶ probability density  $\Pi(U) = \exp(-S(U))/Z$  with  $Z = \int_{\Omega} \exp(-S(U)) dU$ ,
- ▶ action  $S$  acting on  $U \in \Omega$ .

Problem: integral has very high dimension

$N = 64 \cdot 32^3$ , for example



# Importance sampling

Approximate integral by

$$\langle O \rangle \approx \frac{1}{n} \sum_{i=1}^n O(U_i)$$

- ▶ choose configurations  $U_i$  according to the probability density  $\exp(-S(U))/Z$
  - ▶ prefer configurations that occur with a higher probability
  - ▶ sequence
    - ▶ is generated by a Markov chain
    - ▶ is ergodic
    - ▶ satisfies the detailed balance condition
- ⇒ convergence to the unique fixed point distribution given by the density  $\Pi(U)$



# Hybrid Monte Carlo

## Method of choice in Lattice QCD

- ▶ uses augmented Markov chain
- ▶ constructs samples of pairs of links  $U \in \Omega$  and momenta  $P \in \hat{\Omega} = (\mathfrak{su}(3))^N$
- ▶ samples generated according to the probability density  $\nu(U, P)$  given by

$$\nu(U, P) = \underbrace{\frac{(2\pi)^{N/2}}{Z_H} \exp(-S(U))}_{:=\Pi(U)} \cdot \underbrace{\frac{1}{(2\pi)^{N/2}} \exp(-\langle P, P \rangle/2)}_{:=\varphi(P)}$$

$$= \frac{1}{Z_H} \exp(-H(U, P)) \quad \text{with}$$

$$Z_H = \int_{\Omega \times \hat{\Omega}} \nu(U, P) d(U, P), \quad H(U, P) = \langle P, P \rangle/2 + S(U)$$



# Transition $(U_0, P_0) \rightarrow (U^*, P^*)$

## Proposal step

$$(U_0, P_0) \rightarrow g(U_0, P_0)$$

for the moment: arbitrary mapping  $g : \Omega \times \hat{\Omega} \rightarrow \Omega \times \hat{\Omega}$

## Acceptance step

- ▶  $(U^*, P^*) := g(U_0, P_0)$   
 $g(U_0, P_0)$  is accepted with probability

$$\begin{aligned} \alpha((U_0, P_0)g(U_0, P_0)) &= \min \left( 1, \frac{\nu(g(U_0, P_0))}{\nu(U_0, P_0)} \right) \\ &= \min \left( 1, e^{-(H(g(U_0, P_0)) - H(U_0, P_0))} \right) \end{aligned}$$

- ▶ otherwise the old configuration is kept:  
 $(U^*, P^*) := (U_0, P_0)$



# Demand on $g$

Detailed balance condition holds if

- ▶  $g$  is time-reversible:

$$S \cdot g(S \cdot g(U_0, P_0)^\top) = (U_0, P_0)^\top$$

with  $S = \begin{pmatrix} I & 0 \\ 0 & -I \end{pmatrix}$  flipping the momenta

- ▶  $g$  is volume-preserving:

$$\left| \det \left( \frac{\partial g(U_0, P_0)}{\partial (U_0, P_0)} \right) \right| = 1.$$

Choice of  $g$ ?



# Detailed Balance condition I

## Transition kernel in HMC

$$\begin{aligned}
 K((U_0, P_0), (\Omega' \times \hat{\Omega}')) &= P((U^*, P^*) \in (\Omega' \times \hat{\Omega}')) | (U_0, P_0) \\
 &= \alpha((U_0, P_0), g(U_0, P_0)) \delta_{g(U_0, P_0)}(\Omega' \times \hat{\Omega}') + \\
 &\quad (1 - \alpha((U_0, P_0), g(U_0, P_0))) \delta_{(U_0, P_0)}(\Omega' \times \hat{\Omega}').
 \end{aligned}$$

## Restricted Transition kernel

$$K_L(U_0, \Omega') = P(U_0 \in \Omega' | U_0) = \int_{\hat{\Omega}} K((U_0, P), (\Omega' \times \hat{\Omega})) \varphi(P) dP$$

## Detailed Balance condition for all $A, B \in \sigma(\Omega)$

$$\int_A K_L(U, B) \Pi(U) dU = \int_B K_L(U, A) \Pi(U) dU$$



# Detailed Balance condition II

Detailed Balance condition for all  $A, B \in \sigma(\Omega)$

$$\int_A K_L(U, B) \Pi(U) dU = \int_B K_L(U, A) \Pi(U) dU$$

Left-hand side

$$\int_A \int_{\hat{\Omega}} \min \left( 1, \frac{\nu(g(U, P))}{\nu(U, P)} \right) \delta_{g(U, P)}(B \times \hat{\Omega}) \varphi(P) \Pi(U) dP dU +$$

$$\int_{A \cap B} \int_{\hat{\Omega}} \left( 1 - \min \left( 1, \frac{\nu(g(U, P))}{\nu(U, P)} \right) \right) \varphi(P) \Pi(U) dP dU.$$

Right-hand side

$$\int_B \int_{\hat{\Omega}} \min \left( 1, \frac{\nu(g(U, P))}{\nu(U, P)} \right) \delta_{g(U, P)}(A \times \hat{\Omega}) \varphi(P) \Pi(U) dP dU +$$

$$\int_{B \cap A} \int_{\hat{\Omega}} \left( 1 - \min \left( 1, \frac{\nu(g(U, P))}{\nu(U, P)} \right) \right) \varphi(P) \Pi(U) dP dU.$$



# Detailed Balance condition III

To be shown

$$\int_A \int_{\hat{\Omega}} \min(\nu(U, P), \nu(g(U, P))) \delta_{g(U, P)}(B \times \hat{\Omega}) d(P, U) =$$

$$\int_B \int_{\hat{\Omega}} \min(\nu(U, P), \nu(g(U, P))) \delta_{g(U, P)}(A \times \hat{\Omega}) d(P, U).$$

With  $\delta_{g(U, P)}(B \times \hat{\Omega}) = \delta_{(U, P)}(g^{-1})(B \times \hat{\Omega})$

$$\underbrace{\int_{(A \times \hat{\Omega}) \cap g^{-1}(B \times \hat{\Omega})} \min(\nu(U, P), \nu(g(U, P))) d(P, U)}_{F_1 =}$$

$$\underbrace{\int_{(B \times \hat{\Omega}) \cap g^{-1}(A \times \hat{\Omega})} \min(\nu(U, P), \nu(g(U, P))) d(P, U)}_{F_2 =}$$



# Detailed Balance condition IV

$\varphi(P) = \varphi(-P)$ ,  $\nu(U, P) = \nu(U, -P)$  &  $g$  time reversible

$$\nu(g(U, P)) = \nu(g^{-1}(U, -P)) \quad \& \quad g(U, -P) = g^{-1}(U, P)$$

Rewrite  $F_1$  as

$$\begin{aligned} F_1 &= \int_{g^{-1}(B \times \hat{\Omega})} \min(\nu(U, P), \nu(g(U, P))) \delta_{(U, P)}(A \times \hat{\Omega}) d(P, U) = \\ & \int_{B \times \hat{\Omega}} \min(\nu(g^{-1}(U, P)), \nu(U, P)) \delta_{g^{-1}(U, P)}(A \times \hat{\Omega}) \cdot \left| \det \frac{dg^{-1}(U, P)}{d(U, P)} \right| d(P, U) = \\ & \int_{B \times \hat{\Omega}} \min(\nu(g(U, -P)), \nu(U, -P)) \delta_{g^{-1}(U, P)}(A \times \hat{\Omega}) \cdot \left| \det \frac{dg^{-1}(U, P)}{d(U, P)} \right| d(P, U) = \\ & \int_{B \times \hat{\Omega}} \min(\nu(g(U, -P)), \nu(U, -P)) \delta_{g(U, -P)}(A \times \hat{\Omega}) \cdot \left| \det \frac{dg^{-1}(U, P)}{d(U, P)} \right| d(P, U) = \\ & \int_{(B \times \hat{\Omega}) \cap g^{-1}(A \times \hat{\Omega})} \min(\nu(g(U, P)), \nu(U, P)) \underbrace{\left| \det \frac{dg^{-1}(U, P)}{d(U, P)} \right|}_{= 1} d(P, U) = F_2 \end{aligned}$$



# Choice of $g$

Demand on  $g$ :

time-reversible and volume-preserving mapping

- ▶ Natural choice: use Hamiltonian flow  
 $H(U, P) = \langle P, P \rangle / 2 + S(U)$
- ▶ Problem: analytical flow not available
- ▶ Way-out: use numerical approximation using geometric integration
- ▶ accuracy of less importance (only to get high acceptance rate)

Demand on numerical approximation of  $g$

- ▶ time-reversible & volume preserving numerical flow
- ▶ compatible with non-Abelian structure of  
 $U \in (SU(3))^N$  and  $P \in (\mathfrak{su}(3))^N$



# Derivation of Equation of Motion

## Time Derivative of Links $U_\mu(x) \in SU(3)$

derived via an infinitesimal rotation on the group manifold

$$\dot{U}_\mu(x) = P_\mu(x)U_\mu(x)$$

## Time Derivative of Momenta $P_\mu(x) \in \mathfrak{su}(3)$

- ▶ usually: solve  $\dot{H}(U, P) = 0$  for  $\dot{P}_\mu(x)$
- ▶ via the link differential operator

$$\dot{P}_\mu(x) = -\partial_{x,\mu} H(U, P) = -\partial_{x,\mu} S(U)$$

$$\partial_{x,\mu} f(U) = T^i \partial_{x,\mu}^i f(U) \quad \text{with} \quad \partial_{x,\mu}^i f(U) = \left. \frac{df(U_s)}{ds} \right|_{s=0}$$

$$(U_s)_\nu(y) = \begin{cases} e^{sT^i} U_\mu(x) & \text{if } (y, \nu) = (x, \mu) \\ U_\nu(y) & \text{otherwise} \end{cases} .$$



# Example: Wilson action

$$S_g(U) = -\frac{\beta}{N} \text{Re tr}(U_\mu(x) \Sigma_\mu^\dagger(x)) + \text{terms indep. of } U_\mu(x)$$

Staples  $\Sigma_\mu(x)$  defined by

$$\sum_{\nu \neq \mu} [U_\nu(x) U_\mu(x + a\hat{\nu}) U_\nu(x + a\hat{\mu})^{-1} + U_\nu(x - a\hat{\nu})^{-1} U_\mu(x - a\hat{\nu}) U_\nu(x - a\hat{\nu} + a\hat{\mu})]$$

$$\Rightarrow \partial_{x,\mu}^i S_g(U) = -\frac{\beta}{N} \text{Re tr} \{ T^i U_\mu(x) \Sigma_\mu^\dagger(x) \}$$

$$\Rightarrow \partial_{x,\mu} S_g(U) = -\frac{\beta}{N} T^i \text{Re tr} \{ T^i U_\mu(x) \Sigma_\mu^\dagger(x) \}$$

$$= \frac{\beta}{2N} \{ U_\mu(x) \Sigma_\mu^\dagger(x) \}_{TA}$$

Time Derivative of Momenta  $P_\mu(x) \in \mathfrak{su}(3)$

$$\dot{P}_\mu(x) = -\partial_{x,\mu} S_g(U) = -\frac{\beta}{2N} \{ U_\mu(x) \Sigma_\mu^\dagger(x) \}_{TA}$$



# Numerical integration on Lie groups

## Structure of ODE-IVP

$$\begin{aligned}\dot{U} &= \text{diag}(P_\mu(x)U_\mu(x)), & U(t_0) &= U_0 \\ \dot{P} &= -\partial_{x,\mu}S(U), & P(t_0) &= P_0\end{aligned}$$

with  $U \in (SU(3))^N$ ,  $P \in (\mathfrak{su}(3))^N$ .

## Problem for Numerical integration schemes

- ▶ multiplicative structure of Lie group does not fit the additive structure of integrations schemes (RK and others)
- ▶ way-out: bypass via the Lie algebra with its additive structure (Magnus, 1954)





# Bypass via Lie algebra

## Lie algebra parameterization of $U$

$$U(t) = \Psi(\Omega(t))U_0 \quad \text{with } \Psi(t_0) = 0$$

## Transformation of ODE

$$\begin{aligned} \dot{U} &= \left( \frac{d}{d\Omega} \Psi(\Omega(t)) \right) \dot{\Omega}(t) U_0 \\ &= \left( d\Psi_{\Omega(t)} \left( \dot{\Omega}(t) \right) \right) \Psi(\Omega(t)) U_0 \\ &= \underbrace{\left( d\Psi_{\Omega(t)} \left( \dot{\Omega}(t) \right) \right)}_{=P(t)!} U(t) \\ \Rightarrow P(t) &= d\Psi_{\Omega(t)} \left( \dot{\Omega}(t) \right) \\ \Rightarrow \dot{\Omega}(t) &= d\Psi_{\Omega(t)}^{-1} (P(t)). \end{aligned}$$



# Transformed ODE system

## Solve ODE-IVP on Lie-algebra

$$\begin{aligned}\dot{\Omega}_\mu(x) &= d\Psi_{\Omega_\mu(x)}^{-1}(P_\mu(x)), & \Omega_\mu(x)(t_0) &= 0, \\ \dot{P} &= -\partial_{x,\mu} S(\Psi(\Omega)U_0), & P(t_0) &= P_0\end{aligned}$$

⇒ links can be obtained via the transformation

$$U_\mu(x)(t) = \Psi(\Omega_\mu(x)(t))U_0$$

## Possible choice of parameterization

- ▶ Exponential map:  $\Psi(\Omega) = \exp(\Omega) = \sum_{k=0}^{\infty} \frac{1}{k!} \Omega^k$
- ▶ Cayley map:  $\Psi(\Omega) = \text{cay}(\Omega) = (I - \Omega)^{-1}(I + \Omega)$



# Exponential map

$$\psi(\Omega) = \exp(\Omega) = \sum_{k=0}^{\infty} \frac{1}{k!} \Omega^k$$

$$\dot{\Omega}(t) = d \exp_{\Omega}^{-1}(P(t))$$

$$= \sum_{k \geq 0} \frac{B_k}{k!} \text{ad}_{\Omega}^k(P(t))$$

$$= P(t) - \frac{1}{2} [\Omega(t), P(t)] + \frac{1}{12} [\Omega(t), [\Omega(t), P(t)]] + \dots$$

- ▶ Problem: for numerical integration schemes, infinite sum has to be truncated:  $\sum_{k \geq 0} \rightsquigarrow \sum_{k=0}^q$
- ▶ Compatibility with numerical integration schemes: Order  $p$  if a) RK scheme has order  $p$  and b)  $q + 2 \geq p$  holds (Munthe-Kaas).



# Cayley map

$$\psi(\Omega) = \text{cay}(\Omega) = (I - \Omega)^{-1}(I + \Omega)$$

$$\begin{aligned}\dot{\Omega}(t) &= d\text{cay}_{\Omega}^{-1}(P(t)) \\ &= \frac{1}{2}(I - \Omega(t))P(t)(I + \Omega(t))\end{aligned}$$

- ▶ No infinite series, no truncation needed
- ▶ No compatibility condition
- ▶ cheap evaluations!



# The basis scheme: leap frog

Exponential map: Update  $(U_n, P_n) \rightsquigarrow (U_{n+1}, P_{n+1})$

$$P_{n+\frac{1}{2}} = P_n - \frac{h}{2} \partial_{x,\mu} S(U_n),$$

$$\Omega_{n+1} = \Omega_n + h \cdot d \exp_{\Omega}^{-1}(P_{n+\frac{1}{2}}) \approx \Omega_n + h \cdot P_{n+\frac{1}{2}},$$

$$U_{n+1} = \exp(\Omega_{n+1}) U_n,$$

$$P_{n+1} = P_{n+\frac{1}{2}} - \frac{h}{2} \partial_{x,\mu} S(U_{n+1}).$$

Elimination of the auxiliary  $\Omega$  variable

$$U_{n+1} = \exp\left(h \cdot \left(P_n - \frac{h}{2} \partial_{x,\mu} S(U_n)\right)\right) U_n,$$

$$P_{n+1} = P_n - \frac{h}{2} \partial_{x,\mu} S(U_n) - \frac{h}{2} \partial_{x,\mu} S\left(\exp\left(h \cdot \left(P_n - \frac{h}{2} \partial_{x,\mu} S(U_n)\right)\right)\right)$$



# The basis scheme: leap frog

Cayley map: Update  $(U_n, P_n) \rightsquigarrow (U_{n+1}, P_{n+1})$

$$P_{n+\frac{1}{2}} = P_n - \frac{h}{2} \partial_{x,\mu} S(U_n),$$

$$\Omega_{n+1} = \Omega_n + h \cdot \text{dcay}_{\Omega}^{-1}(P_{n+\frac{1}{2}})$$

$$= \Omega_n + \frac{h}{2} (I - \Omega_n) P_{n+\frac{1}{2}} (I + \Omega_n),$$

$$U_{n+1} = \text{cay}(\Omega_{n+1}) U_n = (I - \Omega_{n+1})^{-1} (I + \Omega_{n+1}) U_n,$$

$$P_{n+1} = P_{n+\frac{1}{2}} - \frac{h}{2} \partial_{x,\mu} S(U_{n+1}).$$

Elimination of the auxiliary  $\Omega$  variable

$$U_{n+1} = \text{cay}\left(h \cdot \text{dcay}_{\Omega}^{-1}\left(P_n - \frac{h}{2} \partial_{x,\mu} S(U_n)\right)\right) U_n,$$

$$P_{n+1} = P_n - \frac{h}{2} \partial_{x,\mu} S(U_n) - \frac{h}{2} \partial_{x,\mu} S\left(\text{cay}\left(h \cdot \text{dcay}_{\Omega}^{-1}\left(P_n - \frac{h}{2} \partial_{x,\mu} S(U_n)\right)\right)\right)$$



# Higher-order schemes — Composition

Starting point: basis scheme  $\varphi_t^h$   
 order  $p$ , time-reversible & volume-preserving

$$\begin{pmatrix} U_{n+1} \\ P_{n+1} \end{pmatrix} = \varphi_{t_n}^h \begin{pmatrix} U_n \\ P_n \end{pmatrix}$$

## Composition of $m$ basic schemes

$$\tilde{\varphi}_{t_n}^h = \varphi_{t_n}^{\gamma_1 h} \circ \varphi_{t_n}^{\gamma_2 h} \circ \dots \circ \varphi_{t_n}^{\gamma_m h}$$

- ▶ Volume-preservation ✓
- ▶ Condition for time-reversibility:

$$\gamma_{m+1-k} = \gamma_k, \quad k = 1, \dots, m-1$$

- ▶ Order  $p+1$ , if the underlying scheme has order  $p$ :

$$\sum_{j=1}^m \gamma_j = 1, \quad \sum_{j=1}^m \gamma_j^p = 0$$

- ▶ For leap-frog to get  $p=4$ :  $m=3$ ,  $\gamma_1 = \gamma_3 = (2 - \sqrt[3]{2})^{-1/3}$ ,  $\gamma_2 = 1 - 2\gamma_1$ .



# Higher-order schemes — Splitting

Starting point: sequence of link and momenta updates

Momenta Update

$$\dot{U}_\mu(x) = 0$$

$$\dot{P}_\mu(x) = -\partial_{x,\mu} S(U)$$

Link Update

$$\dot{U}_\mu(x) = P_{\mu,x} \cdot U_{\mu,x}$$

$$\dot{P}_\mu(x) = 0$$

- ▶ in general: order 1
- ▶ at least order 2, if splitting symmetric
- ▶ important classes: Omelyan and force-gradient schemes





# Higher-order schemes — Examples

## Symmetric five-stage Omelyan scheme

$$P_{\lambda h} \circ U_{h/2} \circ P_{(1-2\lambda)h} \circ U_{h/2} \circ P_{\lambda h} \quad \text{with}$$

$$\lambda = \frac{1}{2} - \frac{(2\sqrt{326} + 36)^{1/3}}{12} + \frac{1}{6(2\sqrt{326} - 36)^{1/3}}$$

Still order 2, but minimal leading error coefficient

## Five stage force-gradient scheme of order 4

$$\tilde{P}_{\lambda h, \xi h^3} \circ U_{h/2} \circ \tilde{P}_{(1-2\lambda)h, \chi h^3} \circ U_{h/2} \circ \tilde{P}_{\lambda h, \xi h^3} \quad \text{with}$$

$$\lambda = \frac{1}{6}, \quad \xi = 0, \quad \chi = \frac{1}{72}$$



# Higher-order schemes — Discussion

## Exponential mapping

- ▶ leap-frog scheme used as basic scheme
- ▶ time-reversibility & volume preservation ✓
- ▶ but: truncation order  $q = 0$
- ▶ Problem:  $-(H(g(U_0, P_0)) - H(U_0, P_0)) = \mathcal{O}((\Delta t)^2)$  only
- ▶ high order only with respect to modified equation of motion

$$\begin{aligned}\dot{\Omega}_\mu(x) &= P_\mu(x), \\ U_{\mu,x}(t) &= \exp(\Omega_\mu(x)(t))U_\mu(x)(0) \\ \dot{P}_\mu(x) &= -\partial_{x,\mu}S(U)\end{aligned}$$

- ▶ possible way out: if modified equation of motion based on modified Hamiltonian  $\tilde{H}(U, P)$ , use  $g(U, P) := \tilde{H}(U, P)$  instead of  $H(U, P)$



# Fermionic fields

Additional action: pseudofermionic field

Partition function now given by

$$Z = \int \exp(-S_g(U)) \det(DD^\dagger) dU \quad \text{with}$$

$$\det(DD^\dagger) = \int \exp(-S_{pf}(U, \phi)) d\phi,$$

$$S_{pf}(U, \phi) = \langle \phi, (DD^\dagger)^{-1} \phi \rangle$$

$$\Rightarrow H(U, P) = \frac{1}{2} \langle P, P \rangle + S_g(U) + S_{pf}(U, \phi)$$



# Computation of pseudofermionic force

## Additional action: pseudofermionic field

$$\begin{aligned} \partial_{x,\mu} S_{pf}(U,\phi) &= -2\text{Re} T^i \langle (DD^\dagger)^{-1} \phi, \delta_{x,\mu}^i \phi \rangle \\ (\delta_{x,\mu}^i \phi)(y) &= -\delta_{y,x} \frac{1}{2} (1 - \gamma_\mu) T^i U_\mu(x) D^{-1} \phi(x + \hat{\mu}) \\ &\quad + \delta_{y,x+\hat{\mu}} \frac{1}{2} (1 + \gamma_\mu) U_\mu^{-1}(x) T^i D^{-1} \phi(x) \end{aligned}$$

Note: Computation requires two expensive inversions of the Wilson-Dirac operator



# Nested integration - multirate schemes

## Idea: use different activity levels

- ▶ gauge field  $S_g$ : fast dynamics, cheap evaluations
- ▶ pseudofermionic field  $S_{pf}$ : slow dynamics, expensive evaluations
- ▶ exploit different dynamics by multirate schemes: higher/lower sample rate for fast/slow part
- ▶ introduce additional activity splitting of pseudofermionic field: even-odd preconditioning, domain decomposition and determinant splitting

$$S_{pf}(U, \phi) = \sum_{m=1}^M S_k[U, \phi],$$

$$\Rightarrow H(U, P) = \langle P, P \rangle / 2 + S_g(U) + \sum_{m=1}^M S_k[U, \phi].$$

# Sexton and Weingarten

## First step

- ▶ macro step size  $h_0$
- ▶ micro step size  $h_1 = h_0/m_1$

Leap-frog step

$$V_H(h_0) = V_{H_2}(h_0/2) \left( V_{H_1}(h_1) \right)^{m_1} V_{H_2}(h_0/2) \quad \text{with}$$

$$H_1(U, P) = \langle P, P \rangle / 2 + S_g[U] + \sum_{m=1}^{M-1} S_k[U, \phi], \quad H_2(U, P) = S_M[U, \phi]$$

## Nesting

- ▶ next finer step size  $h_2 = h_1/m_2$
- ▶ further splitting  $H_1$  into

$$H_1(U, P) = H_{11}(U, P) + H_{12}(U, P) \quad \text{with}$$

$$H_{11}(U, P) = \langle P, P \rangle / 2 + S_g[U] + \sum_{m=1}^{M-2} S_k[U, \phi], \quad H_{12}(U, P) = S_{M-1}[U, \phi]$$

- ▶ replace  $V_{H_1}(h_1)$  above by

$$V_{H_1}(h_1) = V_{H_{12}}(h_1/2) \left( V_{H_{11}}(h_2) \right)^{m_2} V_{H_{12}}(h_1/2).$$



# More to read ...

